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## Some extensions of Ito's formula

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In recent studies of stochastic differential equations on manifold, stochastic calculus to differential geometric objects are often considered. In this note we shall discuss three types of formulas for stochastic calculus which may be considered as extensions of Ito's formula. The first formulas (Theorem 1.1 and 1.2) are concerned with the composition of stochastic flows of diffeomorphisms defined by stochastic differential equation. A similar formula is obtained by Bismut [1].

The second formula (Theorem 2.4) is for the stochastic parallel displacement of tensor fields introduced by $K$. It $\hat{o}$ [3]. The third one (Theorem 3.3) is concerned with the stochastic transformation of tensor fields induced by flows of diffeomorphisms defined by stochastic differential equation. The theorem is due to $S$. Watanabe [9]. A special case of the formula is also discussed in Kunita [7].

1. Ito's formula for the composition of processes.

Let $(\Omega, F, P)$ be a complete probability space equipped with a right continuous increasing family $F_{t}, t \geq 0$ of sub $\sigma$-fields of $F$.

Theorem 1.1. Let $F_{t}(x), t \geq 0, x \in R^{d}$ be a stochastic process continuous in ( $t, x$ ) a.s., satisfying
(i) For each $t>0, F_{t}(\cdot)$ is a $C^{2}$-map from $R^{d}$ into $R^{1}$ a.s.
(ii) For each $x, F_{t}(x)$ is a continuous semimartingale represented as

$$
\begin{equation*}
F_{t}(x)=F_{0}(x)+\sum_{j=1}^{m} \int_{0}^{t} f_{s}^{j}(x) d N_{s}^{j} \tag{1.1}
\end{equation*}
$$

where $\mathbb{N}_{s}^{1}, \ldots, \mathbb{N}_{s}^{m}$ are continuous semimartingales, $f_{s}^{j}(x), s \geq 0, x \in \mathbb{R}^{d}$ are stochastic processes continuous in ( $s, x$ ) such that
(a) For each $s>0, f_{s}^{j}(x)$ are $C^{1}$-maps from $R^{d}$ into $R^{1}$.
(b) For each $x, f_{s}^{j}(x)$ are adapted processes.

Let now $M_{t}=\left(M_{t}^{1}, \ldots, M_{t}^{d}\right)$ be continuous semimartingales. Then we have

$$
\begin{align*}
F_{t}\left(M_{t}\right) & =F_{0}\left(M_{0}\right)+\sum_{j=1}^{M} \int_{0}^{t} f_{s}^{j}\left(M_{s}\right) d N_{s}^{j}+\sum_{i=1}^{d} \int_{0}^{t} \frac{\partial F_{s}}{\partial x_{i}}\left(M_{s}\right) d M_{s}^{i}  \tag{1.2}\\
& \left.+\sum_{i=1}^{d} \sum_{j=1}^{m} \int_{0}^{t} \frac{\partial f_{s}^{j}}{\partial x_{i}}\left(M_{s}\right) d<N^{j}, M_{s}^{i}\right\rangle_{s}^{1)} \\
& +\frac{1}{2} \sum_{i, j=1}^{d} \int_{0}^{t} \frac{\partial^{2} F_{s}}{\partial x_{i} \partial x_{j}}\left(M_{s}\right) d\left\langle M^{i}, M^{j}\right\rangle
\end{align*}
$$

Proof. Fix a time $t$ and let $\Delta_{n}=\left\{0=t_{0}<t_{1}<\ldots<t_{n}=t\right\}$ be
a partition of $[0, t]$. Then

$$
\begin{aligned}
F_{t}\left(M_{t}\right)-F_{0}\left(M_{0}\right) & =\sum_{k=0}^{n-1}\left(F_{t_{k+1}}\left(M_{t_{k}}\right)-F_{t_{k}}\left(M_{t_{k}}\right)\right) \\
& +\sum_{k=0}^{n-1}\left(F_{t_{k+1}}\left(M_{t_{k+1}}\right)-F_{t_{k+1}}\left(M_{t_{k}}\right)\right) \\
& =I_{1}^{(n)}+I_{2}^{(n)} .
\end{aligned}
$$

It holds

1) $\left\langle N^{j}, M^{1}\right\rangle_{t}$ is a continuous process of bounded variation such that $\tilde{N}_{t}^{j} \tilde{M}_{t}^{1}-\left\langle\mathbb{N}^{j}, M^{1}\right\rangle_{t}$ is a local martingale, where $\tilde{N}_{t}^{j} \tilde{M}_{t}^{1}$ ) is the local martingale part of $N_{t}^{j}\left(M_{t}^{1}\right)$. See Kunita-Watanabe [8],

$$
I_{1}^{(n)}=\left.\sum_{k=0}^{n-1} \sum_{j=1}^{m} \int_{t_{k}}^{t_{k+1}} f_{s}^{j}(x) d N_{s}^{j}\right|_{x=M_{t_{k}}}=\sum_{j=1}^{m} \sum_{k=0}^{n-1} \int_{t_{k}}^{t_{k+1}} f_{s}^{j}\left(M_{t_{k}}\right) d N_{s}^{j}
$$

Let $\Delta_{n}, n=1,2, \ldots$ be a sequence of partions such that $\left|\Delta_{n}\right| \rightarrow 0$. Then

$$
\lim _{n \rightarrow \infty} I_{1}^{(n)}=\sum_{j=1}^{m} \int_{0}^{t} f_{s}^{j}\left(M_{s}\right) d N_{s}^{j}
$$

The second member is computed as follow.

$$
\begin{aligned}
I_{2}^{(n)} & =\sum_{i=1}^{d} \sum_{k=0}^{n-1} \frac{\partial}{\partial x_{i}} F_{t_{k+1}}\left(M_{t_{k}}\right)\left(M_{t_{k+1}}^{i}-M_{t_{k}}^{i}\right) \\
& +\frac{1}{2} \sum_{i, j=1}^{d} \sum_{k=0}^{n-1} \frac{\partial^{2}}{\partial x_{i} \partial x_{j}} F_{t_{k+1}}\left(\xi_{k}\right)\left(M_{t_{k+1}}^{i}-M_{t_{k}}^{i}\right)\left(M_{t_{k+1}}^{j}-M_{t_{k}}^{j}\right) \\
& =J_{1}^{(n)}+J_{2}^{(n)},
\end{aligned}
$$

where $\xi_{k}$ are random variables such that $\left|\xi_{k}-M_{t_{k}}\right| \leq\left|M_{t_{k+1}}-M_{t_{k}}\right|$. We have

$$
\begin{aligned}
J_{1}^{(n)} & =\sum_{i=1}^{d} \sum_{k=0}^{n-1} \frac{\partial}{\partial x_{i}} F_{t_{k}}\left(M_{t_{k}}\right)\left(M_{t_{k+1}}^{i}-M_{t_{k}}^{i}\right) \\
& +\sum_{i=1}^{d} \sum_{k=0}^{n-1}\left(\frac{\partial}{\partial x_{i}} F_{t_{k+1}}\left(M_{t_{k}}\right)-\frac{\partial}{\partial x_{i}} F_{t_{k}}\left(M_{t_{k}}\right)\right)\left(M_{t_{k+1}}^{i}-M_{t_{k}}^{i}\right)
\end{aligned}
$$

The first member converges to

$$
\sum_{i=1}^{d} \int_{0}^{t} \frac{\partial F_{s}}{\partial x_{i}}\left(M_{s}\right) d M_{s}^{i}
$$

The second member is written as

$$
\begin{aligned}
& \left.\sum_{i=1}^{d} \sum_{j=1}^{m} \sum_{k=0}^{n-1} \int_{t_{k}}^{t_{k+1}} \frac{\partial f_{s}^{j}}{\partial x_{i}}(x) d N_{s}^{j}\right|_{x=M_{t_{k}}} \times\left(M_{t_{k+1}}^{i}-M_{t_{k}}^{i}\right) \\
= & \sum_{i=1}^{d} \sum_{j=1}^{m} \sum_{k=0}^{n-1}\left(\int_{t_{k}}^{t_{k+1}} \frac{\partial f_{s}^{j}}{\partial x_{i}}\left(M_{t_{k}}\right) d N_{s}^{j}\right)\left(M_{t_{k+1}}^{i}-M_{t_{k}}^{i}\right)
\end{aligned}
$$

This converges to

$$
\left.\sum_{i=1}^{d} \sum_{j=1}^{m} \int_{0}^{t} \frac{\partial f_{s}^{j}}{\partial x_{i}}\left(M_{s}\right) d<N^{j}, M^{i}\right\rangle_{s}
$$

It is easily seen that $J_{2}^{(n)}$ converges to

$$
\frac{1}{2} \sum_{i, j=1}^{d} \int_{0}^{t} \frac{\partial^{2} F_{s}}{\partial x_{i} \partial x_{j}}\left(M_{s}\right) d<M^{i}, M^{j}>_{s}
$$

Summing up these calculations, we arrive at the formula (1.2).
In order to establish Ito formula for Stratonovich integral, we need a stronger assumption.

Theorem 1.2. Let $F_{t}(x), t \geq 0, x \in R^{d}$ be a stochastic process continuous in ( $t, x$ ) a.s., satisfying
(i) For each $t>0, F_{t}(\cdot)$ is a $C^{3}$-map from $R^{d}$ into $R^{1}$ for a.s. $\omega$.
(ii) For each $x, F_{t}(x)$ is a continuous semimartingale represented
$a s$

$$
\begin{equation*}
F_{t}(x)=F_{0}(x)+\sum_{j=1}^{m} \int_{0}^{t} f_{s}^{j}(x) \cdot d N_{s}^{j} \tag{1.3}
\end{equation*}
$$

1) The symbol - demotes Stratonovich integral.
where $N_{s}^{1}, \ldots, N_{s}^{m}$ are continuous semimartingales, $f_{t}^{j}(x)$ are stochastic processes satisfying conditions (i) and (ii) of Theorem 1.1, that is, they are continuous in ( $t, x$ ) a.s., $C^{2}$-maps from $R^{d}$ into $R^{1}$ for each $t>0$ a.s., and are represented as

$$
\begin{equation*}
f_{t}^{j}(x)=f_{0}^{j}(x)+\sum_{k=1}^{\ell} \int_{0}^{t} g_{s}^{j k}(x) d 0_{s}^{k} \tag{1.4}
\end{equation*}
$$

where $0_{t}^{1}, \ldots, 0_{t}^{\ell}$ are continuous semimartingales and $g_{s}^{j k}(x)$ are continuous in ( $s, x$ ), satisfying conditions (a) and (b) of Theorem 1.1. Let now $M_{t}=\left(M_{t}^{1}, \ldots, M_{t}^{d}\right)$ be continuous semimartingales. Then we have

$$
\begin{equation*}
F_{t}\left(M_{t}\right)=F_{0}\left(M_{0}\right)+\sum_{j=1}^{m} \int_{0}^{t} f_{s}^{j}\left(M_{s}\right) \cdot d N_{s}^{j}+\sum_{i=1}^{d} \int_{0}^{t} \frac{\partial F_{s}}{\partial x_{i}}\left(M_{s}\right) \cdot d M_{s}^{i} \tag{1.5}
\end{equation*}
$$

Proof. Using Ito integral, $F_{t}(x)$ of (1.3) is written as

$$
F_{t}(x)=F_{0}(x)+\sum_{j=1}^{m} \int_{0}^{t} f_{s}^{j}(x) d N_{s}^{j}+\frac{1}{2} \sum_{j, k} \int_{0}^{t} g_{s}^{j k}(x) d<0^{k}, N_{s}^{j}{ }_{s}
$$

Hence by Theorem 1.1,
(1.6)

$$
\begin{aligned}
F_{t}\left(M_{t}\right) & \left.=F_{0}\left(M_{0}\right)+\sum_{j} \int_{0}^{t} f_{s}^{j}\left(M_{s}\right) d N_{s}^{j}+\frac{1}{2} \sum_{j, k} \int_{0}^{t} g_{s}^{j k}\left(M_{s}\right) d<0^{k}, N^{j}\right\rangle_{s} \\
& +\sum_{i} \int_{0}^{t} \frac{\partial F_{s}}{\partial x_{i}}\left(M_{s}\right) d M_{s}^{i}+\sum_{i, j} \int_{0}^{t} \frac{\partial f_{s}^{j}}{\partial x_{i}}\left(M_{s}\right) d\left\langle N^{j}, M^{i}\right\rangle_{s} \\
& +\frac{1}{2} \sum_{i, j} \int_{0}^{t} \frac{\partial^{2} F_{s}}{\partial x_{i} \partial x_{j}}\left(M_{s}\right) d\left\langle M^{i}, M^{j}\right\rangle_{s} .
\end{aligned}
$$

We shall apply Theorem 1.1 to $f_{t}^{j}(x)$ in the place of $F_{t}(x)$. Then we see that $f_{t}^{j}\left(M_{t}\right)$ is a continuous semimartingale whose martingale part equals

$$
\sum_{i} \int_{0}^{t} \frac{\partial f_{s}^{j}}{\partial x_{i}}\left(M_{s}\right) d \tilde{M}_{s}^{i}+\sum_{k}^{\sum} \int_{0}^{t} g_{s}^{j k}\left(M_{s}\right) d \tilde{0}_{s}^{k},
$$

where $\tilde{M}_{s}^{i}$ and $\tilde{0}_{s}^{k}$ are martingale parts of $M_{s}^{i}$ and $0_{s}^{k}$, respectively. Therefore we have

$$
\begin{aligned}
\int_{0}^{t} f_{s}^{j}\left(M_{s}\right) \cdot d N_{s}^{j} & =\int_{0}^{t} f_{s}^{j}\left(M_{s}\right) d N_{s}^{j}+\frac{1}{2}\left\langle f^{j}(M), N^{j}\right\rangle \\
& \left.=\int_{0}^{t} f_{s}^{j}\left(M_{s}\right) d N_{s}^{j}+\frac{1}{2} \sum_{i} \int_{0}^{t} \frac{\partial f_{s}^{j}}{\partial x_{i}} d<M^{i}, N^{j}\right\rangle_{s} \\
& \left.+\frac{1}{2} \sum_{k} \int_{0}^{t} g_{s}^{j k}\left(M_{s}\right) d<0^{k}, N^{j}\right\rangle_{s} .
\end{aligned}
$$

Similarly, $\frac{\partial F_{s}}{\partial x_{i}}\left(M_{s}\right)$ is a continuous semimartingale whose martingale part is

$$
\sum \int_{j}^{t} \frac{\partial f_{s}^{j}}{\partial x_{i}}\left(M_{s}\right) d \tilde{N}_{s}^{j}+\sum_{j} \int_{0}^{t} \frac{\partial^{2} F_{s}}{\partial x_{i} \partial x_{j}}\left(M_{s}\right) d \tilde{M}_{s}^{j}
$$

where $\tilde{N}_{t}^{j}$ are martingale parts of $N_{t}^{j}$. Then we have

$$
\begin{aligned}
\int_{0}^{t} \frac{\partial F_{s}}{\partial x_{i}}\left(M_{s}\right) \cdot d M_{s}^{i} & =\int_{0}^{t} \frac{\partial F_{s}}{\partial x_{i}}\left(M_{s}\right) d M_{s}^{i}+\frac{1}{2}\left\langle\frac{\partial F}{\partial x_{i}}(M), M_{t}^{i}\right\rangle_{t} \\
& \left.=\int_{0}^{t} \frac{\partial F_{s}}{\partial x_{i}}\left(M_{s}\right) d M_{s}^{i}+\frac{1}{2} \sum \int_{0}^{t} \frac{\partial f_{s}^{j}}{\partial x_{i}}\left(M_{s}\right) d<N^{j}, M_{s}^{i}\right\rangle_{s}
\end{aligned}
$$

$$
+\frac{1}{2} \sum_{j} \int_{0}^{t} \frac{\partial^{2} F_{s}}{\partial x_{i} \partial x_{j}}\left(M_{s}\right) d\left\langle M^{j}, M^{i}\right\rangle_{s}
$$

Hence the right hand side of (1.6) equals that of (1.5). The proof is complete.

In [6] and [7], the author used the above formula (1.5) without proof for the study of the composition of flows of diffeomorphisms defined by stochastic differential equations. We shall briefly discuss the problem.

Let $M$ be a connected, $\sigma$-compact $C^{\infty}$-manifold of dimension $d$. Given $C^{\infty}$-vector fields $X_{1}, \ldots, X_{r}$ on $M$ and continuous semimartingales $M_{t}^{1}, \ldots, M_{t}^{r}, t \geq 0$, consider a stochastic differential equation

$$
\begin{equation*}
d \xi_{t}=\sum_{j=1}^{r} x_{j}\left(\xi_{t}\right) \circ d M_{t}^{j} \tag{1.7}
\end{equation*}
$$

The solution starting at $x$ at time 0 is denoted by $\xi_{t}(x)$. Under some conditions on vector fields $X_{1}, \ldots, X_{r}, \xi_{t}$ defines a flow of diffeomorphisms of $M$ a.s. See [7]. We assume it throughout this note.

Now let $F_{t}(x), t \geq 0, x \in M$ be a real valued stochastic process continuous in ( $t, x$ ) a.s., satisfying conditions (i) and (ii) of Theorem 1.2, where we replace $R^{d}$ by $M$. Then we have

$$
\begin{equation*}
F_{t}\left(\xi_{t}\right)=F_{0}\left(\xi_{0}\right)+\sum_{j=1}^{m} \int_{0}^{t} f_{s}^{j}\left(\xi_{s}\right) \cdot d N_{s}^{j}+\sum_{j=1}^{r} \int_{0}^{t} X_{j} F_{s}\left(\xi_{s}\right) \circ d M_{s}^{j} \tag{1.8}
\end{equation*}
$$

Here, $X_{j} F_{s}(x)$ is the derivation of $F_{s}(x)\left(s\right.$; fixed) by $X_{j}$. In fact, let $\left(x^{1}, \ldots, x^{d}\right)$ be a local coordinate and let $X_{j}^{i}(x), i=1, \ldots, d$ be components of $x_{j}$, i.e., $x_{j}=\sum_{i} x_{j}^{i} \frac{\partial}{\partial x^{i}}$. Then $\xi_{t}=\left(\xi_{t}^{1}, \ldots, \xi_{t}^{d}\right)$ are
continuous semimartingales represented as
(1.9) $\quad d \xi_{t}^{i}=\sum_{j} X_{j}^{i}\left(\xi_{t}\right) \circ d M_{t}^{j}, \quad i=1, \ldots, d$.

Apply formula (1.5) to $F_{t}\left(\xi_{t}\right)$. Then the third term of the right hand side of (1.5) is

$$
\begin{aligned}
\sum_{i=1}^{d} \int_{0}^{t} \frac{\partial F_{s}}{\partial x_{i}}\left(\xi_{s}\right) \circ d \xi_{s}^{i} & =\sum_{j} \sum \int_{0}^{t} x_{j}^{i}\left(\xi_{s}\right) \frac{\partial F_{s}}{\partial x_{i}}\left(\xi_{s}\right) \circ d M_{s}^{j} \\
& =\sum_{j} \int_{0}^{t} X_{j} F_{s}\left(\xi_{s}\right) \circ d M_{s}^{j}
\end{aligned}
$$

This shows the formula (1.8).
Let now $Y_{1}, \ldots, Y_{m}$ be other $C^{\infty}$-vector fields on $M$ and $\eta_{t}$ be a solution of stochastic differential equation
(1.10) $\quad d \eta_{t}=\sum_{k=1}^{m} Y_{k}\left(\eta_{t}\right) \cdot d N_{t}^{k}$.

Then the solution $\eta_{t}(x)$ starting at $x$ is a $C^{\infty}$-map under some conditions on $Y_{1}, \ldots, Y_{s}$. Using a local coordinate $\left(x^{1}, \ldots, x^{d}\right), \eta_{t}=\left(n_{t}^{1}, \ldots, \eta_{t}^{d}\right)$ satisfies

$$
\eta_{t}^{i}\left(\xi_{t}\right)=x^{i}+\sum_{k=1}^{m} \int_{0}^{t} Y_{k}^{i}\left(\eta_{s} \circ \xi_{s}\right) \circ d N_{s}^{k}+\sum_{j=1}^{r} \int_{0}^{t} x_{j} \eta_{s}^{i}\left(\xi_{s}\right) \circ d M_{s}^{j}
$$

Then the composed process $\zeta_{t}=\eta_{t}{ }^{\circ} \xi_{t}$ satisfies
(1.11) $\quad d \zeta_{t}=\sum_{k=1}^{m} Y_{k}\left(\zeta_{t}\right) \circ d N_{t}^{k}+\sum_{j=1}^{r} \eta_{t *}\left(X_{j}\right)\left(\zeta_{t}\right) \circ d M_{t}^{j}$.

Here $\eta_{t *}\left(X_{j}\right)$ is a stochastic vector field defined by

$$
\eta_{t *}\left(x_{j}\right)_{x}=\left(n_{t *}\right)_{n_{t}}^{-1}(x)\left(x_{j}\right)_{n_{t}}^{-1}(x),
$$

where $\eta_{t *}$ is the differential of the map $\eta_{t}$. See [6] and [7] for other problems of decompositions.
2. Ito's formula for stochastic parralel displacement of tensor fields,

As an application of extended Ito's formula established in Section 1, we shall discuss an Ito's formula for stochastic parallel displacement of tensor fields along curves obtained by a stochastic differential equation. Stochastic parallel displacement along Brownian curves on Riemannian manifold was introduced by K , Itô [3], [4]. Our definition is close to [4]. See Ikeda-Watanabe [2] for other approaches by EellesElworthy and Malliavin, where stochastic moving frames play an important role.

We shall recall some facts on parallel displacement needed later. Let $M$ be a connected, $\sigma$-compact $C^{\infty}$-manifold of dimension $d$, where an affine connection is defined. Denote by $T_{x}(M)$ the tangent space at the point $x$ of $M$. Suppose we are given a smooth curve $\phi_{s}(x)$, $s \geq 0$ starting at $x$ at time 0 . Let $u_{t}$ be a tangent vector belonging to $T_{\phi_{t}(x)}(M)$ and let $u_{0}$ be the parallel displacement of $u_{t}$ along the curve $\phi_{s}(x), 0 \leq s \leq t$ from the point $\phi_{t}(x)$ to $x$. Then the $\operatorname{map} \pi_{t x}: u_{t} \rightarrow u_{0}$ defines an isomorphism from $T_{\phi_{t}}(x)(M)$ to $T_{x}(M)$. Given a vector field $Y$ on $M$, we denote by $Y_{x}$ the restriction of $Y$ to the point $x$, which is an element of $T_{x}(M)$. For each $t>0$,
a vector field $\pi_{t} Y$ is defined by $\left(\pi_{t} Y\right)_{x}=\pi_{t x} Y_{\phi_{t}}(x), \forall x \in M$. The one parameter family of vector fields $\pi_{t} Y, t \geq 0$ satisfies
(2.1) $\quad \frac{d}{d t}\left(\pi_{t} Y\right)_{x}=\left(\pi_{t} \nabla_{\dot{\phi}} Y_{x}, \quad \forall x \in M\right.$,
where $\nabla_{\dot{\phi}} Y$ is the covariant derivative of $Y$ along the curve $\phi_{t}$, If $\phi_{t}(x)$ is a solution of an ordinary differential equation:

$$
\dot{\phi}_{t}=\sum_{j=1}^{r} X_{j}\left(\phi_{t}\right) u_{j}(t), \quad \phi_{0}=x
$$

where $X_{1}, \ldots, X_{r}$ are vector fields on $M$ and $u_{1}(t), \ldots, u_{r}(t)$ are smooth scalar functions, then equation (2.1) becomes

$$
\begin{equation*}
\frac{d}{d t}\left(\pi_{t} Y\right)_{x}=\sum_{j=1}^{r}\left(\pi_{t} \nabla_{X_{j}} Y\right)_{x} u_{j}(t) \tag{2.2}
\end{equation*}
$$

The inverse map $\pi_{t x}^{-1}$ defines another vector field $\pi_{t}^{-1} Y$ as $\left(\pi_{t}^{-1} Y\right)_{x}={ }_{t \phi_{t}^{-1}}^{-1}(x)^{Y} \phi_{t}^{-1}(x)$, which is the parallel displacement of $Y_{\phi_{t}}^{-1}(x)$ al.ong the curve $\phi_{s}, 0 \leq s \leq t$ from $\phi_{t}^{-1}(x)$ to $x$. It holds

$$
\begin{equation*}
\frac{d}{d t}\left(\pi_{t}^{-1} Y\right)_{x}=-\sum_{j=1}^{r}\left(\nabla_{X_{j}} \pi_{t}^{-1} Y\right)_{X_{j}}(t) \tag{2.3}
\end{equation*}
$$

Let $T_{x}(M)$ * the cotangent space at $x$ (dual of $T_{x}(M)$ ). The dual $\pi_{t x}^{*}$ is an isomorphism from $T_{x}(M)^{*}$ to $T_{\phi_{t}(x)}(M){ }^{*}$ such that $\left\langle\pi{ }_{t x}^{*} \theta, Y\right\rangle=\left\langle\theta, \pi_{t x} Y\right\rangle$ holds for any $\theta \in T_{x}(M)^{*}$ and $Y \in T_{\phi_{t}(X)}{ }^{(M)}$. Given a 1 -form $\theta$ (covariant vector field), $\pi_{t}^{*} \theta$ is a l-form defined by $\left(\pi_{t}^{*} \theta\right){ }_{x}=\pi_{t \phi_{t}^{-1}(x)}^{\phi_{t}}{ }_{t}^{-1}(x) \cdot \pi_{t}^{*^{-1}} \theta$ is defined similarly.

1) It is assumed that $\phi_{t}$ is a one to one map from $M$ into itself for any $t \geq 0$.

A tensor field $K$ of type ( $p, q$ ) is, by definition, an assignment of a tensor $K_{x}$ of $T_{q}^{P}(x)$ to each point $x$ of $M$, where

$$
T_{q}^{p}(x)=T_{x}(M) \otimes \ldots \otimes T_{x}(M) \otimes T_{x}(M)^{*} \otimes \ldots \otimes T_{x}(M)^{*}
$$

( $T_{x}(M) ; p$ times and $T_{x}(M)^{*}$; $q$ times). Hence for each $x, K_{x}$ is a multilinear form on the product space

$$
T_{x}(M)^{*} \times \ldots \times T_{x}(M)^{*} \times T_{x}(M) \times \ldots \times T_{x}(M)
$$

Thus, for given 1-forms $\theta^{1}, \ldots, \theta^{p}$ and vector fields $Y_{1}, \ldots, Y_{q}$,

$$
K_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)\left(\equiv K_{x}\left(\theta_{x}^{1}, \ldots, \theta_{x}^{p}, Y_{1 x}, \ldots, Y_{q x}\right)\right)
$$

is a scalar field. In the sequel, we assume that it is a $\mathrm{C}^{\infty}$-function. ${ }^{1)}$
The parallel displacement $\pi_{t} K$ of the tensor field $K$ along the curve $\phi_{S}$ is defined by the relation

$$
\begin{equation*}
\left(\pi_{t} K\right)_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)=K_{\phi_{t}(x)}\left(\pi_{t}^{*} \theta^{1}, \ldots, \pi_{t}^{*} \theta^{p}, \pi_{t}^{-1} Y_{1}, \ldots, \pi_{t}^{-1} Y_{q}\right) \tag{2.4}
\end{equation*}
$$

If $K$ is a vector field, it coincides clearly with the usual parallel displacement mentioned above. If $K$ is a 1-form, it coincides with $\pi_{t}^{*^{-1}} \mathrm{~K}$. Hence we can write the above relation as

$$
\begin{equation*}
\left(\pi_{t} K\right)_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)=K_{\phi_{t}(x)}\left(\pi_{t}^{-1} \theta^{1}, \ldots, \pi_{t}^{-1} \theta^{p}, \pi_{t}^{-1} Y_{1}, \ldots, \pi_{t}^{-1} Y_{q}\right) \tag{2.4'}
\end{equation*}
$$

1) $K$ is a $C^{\infty}$-tensor field.

Let $X$ be a complete vector field and $\phi_{t}$, the one parameter group of transformations generated by $X$. Then the covariant derivative $\nabla_{\mathrm{X}} \mathrm{K}$ of tensor field K is defined by

$$
\begin{equation*}
\left(\nabla_{x} K\right)_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)=\left.\frac{d}{d t}\left(\pi_{t} K\right)_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)\right|_{t=0} . \tag{2.5}
\end{equation*}
$$

The following relation is easily checked.

$$
\begin{align*}
& \left(\nabla_{x} K\right)_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)  \tag{2.6}\\
& =X_{X}\left(K_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)\right) \\
& -\sum_{k=1}^{p} K_{x}\left(\theta^{1}, \ldots, \nabla_{x} \theta^{k}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right) \\
& -\sum_{\ell=1}^{q} K_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, \nabla_{X} Y_{\ell}, \ldots, Y_{q}\right),
\end{align*}
$$

Now let $\xi_{t}(x)$ be the stochastic flow of diffeomorphisms defined by the equation (1.7). The curves $\xi_{s}(x), 0 \leq s \leq t$ are not smooth a.s., so that the argument of the parallel displacement mentioned above is not applied directly. We shall define the stochastic parallel displacement following the idea of Ito [4]. We begins with defining the stochastic parallel displacement of vector fields along $\xi_{s}(x), 0 \leq s \leq t$ from $\xi_{t}(x)$ to $x$.

A stochastic analogue of equation (2.2) is as follow.

$$
\begin{equation*}
\left(\pi_{t} Y\right)_{x}=Y_{x}+\sum_{j=1}^{r} \int_{0}^{t}\left(\pi_{s} \nabla_{X_{j}} Y\right)_{x} \circ d M_{s}^{j}, \quad \forall x e M, \tag{2.7}
\end{equation*}
$$

Here, $\pi_{t}$ is a stochastic linear map acting on the space of yector fields such that $\pi_{t}(f Y)_{x}=f\left(\xi_{t}(x)\right)\left(\pi_{t} Y\right)_{x}$ for scalar function $f$, Let ( $x^{1}, \ldots, x^{d}$ ) be a local coordinate and let $\partial_{k}=\frac{\partial}{\partial x^{k}}$. Then equation (2.7) is written as

$$
\begin{array}{r}
\left(\pi_{t} \partial_{k}\right)_{x}=\left(\partial_{k}\right)_{x}+\sum_{j \alpha, \ell}^{\sum} \int_{0}^{t} x_{j}^{\alpha}\left(\xi_{s}(x)\right) \Gamma_{\alpha k}^{\ell}\left(\xi_{s}(x)\right)\left(\pi_{s} \partial_{\ell}\right)_{x}{ }^{\wedge d M_{s}^{j}},  \tag{2.8}\\
k=1, \ldots, d,
\end{array}
$$

where $X_{j}=\sum_{\alpha} x_{j}^{\alpha} \partial_{\alpha}$ and $\Gamma_{\alpha k}^{\ell}$ is the Christoffel symbol. It may be considered as an equation on the tangent space $T_{x}(M)$. The equation has a unique solution $\left(\pi_{t} \partial_{k}\right)_{x}, k=1, \ldots, d$ for any $x$, Define $\left(\pi_{t} Y\right)_{x}=\sum_{i} Y^{i}\left(\xi_{t}(x)\right)\left(\pi_{t} \partial_{i}\right)_{x}$ if $Y=\sum Y_{i} \partial_{i}$. Then it is a unique solution of (2.7). We shall call $\left(\pi_{t} Y\right)_{x}$ the parallel displacement of $Y_{\xi_{t}}(x)$ along the curve $\xi_{s}(x), 0 \leq s \leq t$ from $\xi_{t}(x)$ to $x$. Denote the linear map $Y_{\xi_{t}(x)} \rightarrow\left(\pi_{t} Y_{x}\right.$ as $\pi_{t x}$.

Lemma 2.1. $\pi_{t x}$ is an isomorphism from $T_{\xi_{t}(x)}(M)$ to $T_{x}(M)$ a.s.
Proof. Using the above local coordinate, we shall write

$$
\left(\pi_{t} \partial_{i}\right)_{x}=\sum_{j} \pi_{t}^{i j}(x)\left(\partial_{j}\right)_{x}, \quad p_{j}^{k \ell}(x)=\sum_{\alpha} x_{j}^{\alpha}(x) \Gamma_{\alpha k}^{\ell}(x)
$$

From (2.8), the matrix $\Pi_{t}(x)=\left(\pi_{t}^{i j}(x)\right)$ satisfies

$$
\begin{equation*}
\Pi_{t}(x)=I+\sum_{j=1}^{r} \int_{0}^{t} P_{j}\left(\xi_{s}(x)\right) \Pi_{s}(x) \odot d M_{s}^{j} \tag{2.9}
\end{equation*}
$$

where $P_{j}=\left(p_{j}^{k l}\right)$ and $I$ is the identity. Consider the adjoint matrix equation of (2.9) :

$$
\begin{equation*}
\Sigma_{t}(x)=I-\sum_{j=1}^{r} \int_{0}^{t} \sum_{s}(x) P_{j}\left(\xi_{s}(x)\right) \cdot d M_{s}^{j} \tag{2.10}
\end{equation*}
$$

Then Ito's formula implies $d \Sigma_{t}(x) \Pi_{t}(x)=0$. This proves $\Sigma_{t}(x) \Pi_{t}(x)=I$ so that $\Pi_{t}(x)$ has the inverse $\Sigma_{t}(x)$. The proof is complete.

Now the inverse map $\pi_{t x}^{-1}: T_{x}(M) \longrightarrow T_{\xi_{t}}(x)(M)$ defines the stochastic parallel displacement from $x$ to $\xi_{t}(x)$. Obviously we have $\pi_{t x}^{-1}\left(\partial_{k}\right) x=\sum_{\ell} \sigma_{t}^{k \ell}(x)\left(\partial_{\ell}\right)_{\xi_{t}(x)}$, where $\Sigma_{t}=\left(\sigma_{t}^{k \ell}\right)$. The components of the vector $\pi_{t x}^{-1}\left(\partial_{k}\right)_{x}$ satisfies by (2.10)

$$
\begin{equation*}
\sigma_{t}^{k \ell}(x)=\delta_{k \ell}-\sum_{j=1}^{r} \int_{0}^{t} \sum_{i, \alpha} x_{j}^{\alpha}\left(\xi_{s}(x)\right) \Gamma_{\alpha i}^{\ell}\left(\xi_{s}(x)\right) \sigma_{s}^{k i}(x) \circ d M_{s}^{j} \tag{2.11}
\end{equation*}
$$

In [2] and [4], the above equation is employed for defining the stochastic parallel displacement. Actually, if $\sigma_{t}^{k \ell}$ is a solution of (2.11), $\sum_{\ell} \sigma_{t}^{k \ell}\left(\partial_{\ell}\right)_{\xi_{t}}(x)$ is defined as the stochastic parallel displacement of $\left(\partial_{k}\right)_{x}$ along $\xi_{s}(x), 0 \leq s \leq t$ from $x$ to $\xi_{t}(x)$ : Then equation (2.8) is induced from it as the inverse. A reason that we adopt (2.7) as the definition is that all $\left(\pi_{t} Y\right)_{x}$ are elements of the fixed tangent space $T_{x}(M)$. While $\pi_{t x}^{-1} Y_{x}$ are moving in various tangent spaces $T_{\xi_{t}}(x)(M)$ as $t$ and $\omega$ vary. In fact we may consider that (2.11) is an equation for stochastic moving frames represented by local coordinate ( $\mathbf{x}^{\mathbf{1}}, \ldots, \mathrm{x}^{\mathrm{d}}$, $\sigma^{11}, \ldots, \sigma^{1 \mathrm{~d}}, \ldots, \sigma^{\mathrm{dl}}, \ldots, \sigma^{\mathrm{dd}}$ ) (c.f. [2]).

Given a vector field $Y$, we denote by $\left(\pi_{t}^{-1} Y\right)_{X}$ the stochastic parallel displacement of $Y$ along $\xi_{s}, 0 \leq s \leq t$ from $\xi_{t}^{-1}(x)$ to $x$. Then it holds $\quad\left(\pi_{t}^{-1} Y\right)_{X}=\pi_{t \xi_{t}^{-1}(x)}^{Y} \xi_{t}^{-1}(x)$.

Proposition 2.2. It holds

$$
\begin{equation*}
\left(\pi_{t}^{-1} Y\right)_{x}=Y_{x}-\sum_{j=1}^{r} \int_{0}^{t}\left(\nabla_{X_{j}} \pi_{s}^{-1} Y_{x} \circ d_{s}^{j}\right. \tag{2.12}
\end{equation*}
$$

Proof. It is known that the inverse map $\xi_{t}^{-1}$ satisfies

$$
d \xi_{t}^{-1}(x)=-\sum_{j} \xi_{t^{*}}^{-1}\left(X_{j}\right)\left(\xi_{t}^{-1}(x)\right) \cdot d M_{t}^{j}
$$

(Kunita [7], Proposition 5.1). Apply Theorem 1.2 to $\Sigma_{t}$. Then

$$
\begin{align*}
\sigma_{t}^{k \ell}\left(\xi_{t}^{-1}(x)\right)=\delta_{k \ell} & -\sum_{j=1}^{r} \int_{0}^{t} \sum_{i, \alpha} x_{j}^{\alpha}(x) \Gamma_{\alpha i}^{\ell}(x) \sigma_{s}^{k i}\left(\xi_{s}^{-1}(x)\right) \circ d M_{s}^{j}  \tag{2.13}\\
& -\sum_{j=1}^{r} \int_{0}^{t} \xi_{s *}^{-1}\left(x_{j}\right) \sigma_{s}^{k \ell}\left(\xi_{s}^{-1}(x)\right) \circ d M_{s}^{j}
\end{align*}
$$

Noting $\quad \xi_{s^{*}}^{-1}\left(X_{j}\right) f\left(\xi_{s}^{-1}(x)\right)=X_{j}\left(f^{\circ} \xi_{s}^{-1}\right)(x)$, we see that $K_{t}^{k \ell} \equiv \sigma_{t}^{k \ell} \circ \xi_{t}^{-1}$ satisfies

$$
\begin{equation*}
k_{t}^{k \ell}=\delta_{k \ell}-\sum_{j=1}^{r} \int_{0}^{t} \sum_{\alpha} x_{j}^{\alpha}\left(\sum_{i} \Gamma_{\alpha i}^{\ell} k_{s}^{k i}+\partial_{\alpha}\left(k_{s}^{k \ell}\right)\right) \circ d M_{s}^{j} \tag{2.14}
\end{equation*}
$$

Since $\pi_{t}^{-1} \partial_{k}=\sum_{\ell} \kappa_{t}^{k \ell \partial_{\ell}}$, the above equality shows

$$
\pi_{t}^{-1} \partial_{k}=\partial_{k}-\sum_{j=1}^{r} \int_{0}^{t} \nabla_{X_{j}} \pi_{s}^{-1} \partial_{k} \circ d M_{s}^{j}
$$

## This proves the proposition.

The dual $\pi_{t}^{*}$ of $\pi_{t}$ is defined as before. It is acting on the space of 1 -forms. It holds

$$
\left\langle\pi_{t}^{*} \theta, Y\right\rangle_{\xi_{t}(x)}=\left\langle\theta, \pi_{t} Y\right\rangle
$$

for any 1-form $\theta$ and vector field $Y$. We shall obtain equations for $\pi_{t}^{*} \theta$ and $\pi_{t}^{*-1} \theta$.

Proposition 2.3. It holds

$$
\begin{equation*}
\left(\pi_{t}^{*} \theta\right)_{x}=\theta_{x}-\sum_{j=1}^{r} \int_{0}^{t}\left(\nabla_{x_{j}} \pi_{s}^{*} \theta\right)_{x}{ }^{\circ} \mathrm{dM}_{s}^{j} \tag{2.15}
\end{equation*}
$$

$$
\begin{equation*}
\left(\pi_{t}^{*-1} \theta\right)_{x}=\theta_{x}+\sum_{j=1}^{r} \int_{0}^{t}\left(\pi_{s}^{*-1} \nabla_{x_{j}} \theta\right)_{x} \circ d M_{s}^{j} \tag{2.16}
\end{equation*}
$$

Proof. Set $F_{t}(x)=\left\langle\theta, \pi_{t} Y\right\rangle_{x}$. We shall calculate $F_{t}\left(\xi_{t}^{-1}(x)\right)$, using Theorem 1.2. It holds

$$
\begin{aligned}
F_{t}\left(\xi_{t}^{-1}(x)\right)-F_{0}(x) & =-\sum_{j=1}^{r} \int_{0}^{t} \xi_{s^{*}}^{-1}\left(X_{j}\right)\left(F_{s}\right)\left(\xi_{s}^{-1}(x)\right) \circ d M_{s}^{j} \\
& +\sum_{j=1}^{r} \int_{0}^{t}\left\langle\theta, \pi_{s} \nabla_{X_{j}}{ }^{Y}\right\rangle \xi_{s}^{-1}(x) \quad \circ d M_{s}^{j}
\end{aligned}
$$

Note that

$$
\xi_{s^{*}}^{-1}\left(X_{j}\right)\left(F_{s}\right)\left(\xi_{s}^{-1}(x)\right)=X_{j}\left(\left\langle\theta, \pi_{s} Y\right\rangle_{\xi_{s}}^{-1}(x)\right.
$$

Since $\left\langle\nabla_{X_{j}}{ }^{\theta}, \mathrm{Y}\right\rangle+\left\langle\theta, \nabla_{X_{j}} Y\right\rangle=X_{j}(\langle\theta, Y\rangle)$ holds by (2.6), the above formula leads to

$$
\left\langle\theta, \pi_{t} \mathrm{Y}\right\rangle_{\xi_{t}}^{-1}(\mathrm{x}) \quad-\langle\theta, \mathrm{Y}\rangle \mathrm{x}=-\sum_{\mathrm{j}} \int_{0}^{t}\left\langle\nabla_{\mathrm{X}_{\mathrm{j}}} \pi_{\mathrm{s}}^{*} \theta, \mathrm{Y}\right\rangle \mathrm{x}^{\circ \mathrm{dM}_{s}^{\mathrm{j}} .}
$$

This proves (2.15). (2.16) is proved similarly.
The stochastic parallel displacement of tensor field $K$ is defined
similarly as before: $\pi_{t} K$ is a tensor field such that

$$
\begin{equation*}
\left(\pi_{t} K\right)_{x}\left(\theta^{1}, \ldots, \theta^{P}, Y_{1}, \ldots, Y_{q}\right)=K_{\xi_{t}(x)}\left(\pi_{t}^{*} \theta^{1}, \ldots, \pi_{t}^{*} \theta^{p}, \pi_{t}^{-1} Y_{1}, \ldots, \pi_{t}^{-1} Y_{q}\right) . \tag{2.17}
\end{equation*}
$$

We shall obtain an Ito's formula for $\pi_{t} K$, which is an extension of formulas (2.7) and (2.16).

Theorem 2.4. It holds

$$
\begin{align*}
\pi_{t} K & =K+\sum_{j=1}^{r} \int_{0}^{t} \pi_{s} \nabla_{X_{j}} K \circ d M_{s}^{j}  \tag{2.18}\\
& \left.=K+\sum_{j=1}^{r} \int_{0}^{t} \pi_{s} \nabla_{X_{j}} K d M_{s}^{j}+\frac{1}{2} \sum_{j, k} \int_{0}^{t} \pi_{s} \nabla_{X_{j}} \nabla_{x_{k}} K d<M^{j}, M^{k}\right\rangle_{s} .
\end{align*}
$$

Proof. Apply Ito's formula to the multilinear form $K_{x}$.
Noting the relation (2.12) and (2.15), we have

$$
\begin{aligned}
& K_{x}\left(\pi_{t}^{*} \theta^{1}, \ldots, \pi_{t}^{*} \theta^{p}, \pi_{t}^{-1} Y_{1}, \ldots, \pi_{t}^{-1} Y_{q}\right)-K_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right) \\
&=-\sum_{j=1}^{r}\left\{\sum_{k=1}^{p} \int_{0}^{t} K_{x}\left(\pi_{s}^{*} \theta^{1}, \ldots, \nabla_{x_{j}} \pi_{s}^{*} \theta^{k}, \ldots, \pi_{s}^{-1} Y_{1}, \ldots, \pi_{s}^{-1} Y_{q}\right) \cdot d M_{s}^{j}\right. \\
&\left.+\sum_{\ell=1}^{q} \int_{0}^{t} K_{x}\left(\pi_{s}^{*} \theta^{1}, \ldots, \pi_{s}^{-1} Y_{1}, \ldots, \nabla_{X_{j}} \pi_{s}^{-1} Y_{\ell}, \ldots, \pi_{s}^{-1} Y_{q}\right) \cdot d M_{s}^{j}\right\}
\end{aligned}
$$

Set

$$
F_{t}(x)=K_{x}\left(\pi_{t}^{*} \theta^{1}, \ldots, \pi_{t}^{*} \theta^{p}, \pi_{t}^{-1} Y_{1}, \ldots, \pi_{t}^{-1} Y_{q}\right)
$$

and apply Theorem 1.2 to $F_{t}\left(\xi_{t}(x)\right)$. Then
(2.19)

$$
\begin{aligned}
F_{t}\left(\xi_{t}(x)\right) & -F_{0}(x) \\
& =\sum_{j=1}^{r}\left\{\int_{0}^{t} X_{j} F_{s}\left(\xi_{s}(x)\right) \circ d M_{s}^{j}\right. \\
& -\sum_{k}^{\sum} \int_{0}^{t} K_{\xi_{s}(x)}\left(\pi_{s}^{*} \theta^{1}, \ldots, \pi_{s}^{*} \nabla_{X_{j}} \theta^{k}, \ldots, \pi_{s}^{-1} Y_{1}, \ldots, \pi_{s}^{-1} Y_{q}\right) \circ d M_{s}^{j} \\
& \left.-\sum_{\ell} \int_{0}^{t} K_{\xi_{s}(x)}\left(\pi_{s}^{*} \theta^{1}, \ldots, \pi_{s}^{-1} Y_{1}, \ldots, \nabla_{X_{j}} \pi_{s}^{-1} Y_{\ell}, \ldots, \pi_{s}^{-1} Y_{q}\right) \circ d M_{s}^{j}\right\} .
\end{aligned}
$$

Noting the relation (2.6), we see that the right hand side of (2.19) is

$$
\sum_{j=1}^{r} \int_{0}^{t} \pi_{s} \nabla_{X_{j}} K\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right) \circ d M_{s}^{j}
$$

The proof is complete.
Remark. The inverse $\pi_{t}^{-1}$ is defined by

$$
\left(\pi_{t}^{-1} K\right)_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)=K_{\xi_{t}^{-1}(x)}\left(\pi_{t} \theta^{1}, \ldots, \pi_{t} \theta^{p}, \pi_{t} Y_{1}, \ldots, \pi_{t} Y_{q}\right) .
$$

Then similarly as Theorem 2.4, we have

$$
\begin{aligned}
\pi_{t}^{-1} K & =K-\sum_{j=1}^{r} \int_{0}^{t} \nabla_{X_{j}} \pi_{s}^{-1} \mathrm{~K} \circ d M_{s}^{j} \\
& \left.=K-\sum_{j=1}^{r} \int_{0}^{t} \nabla_{X_{j}} \pi_{s}^{-1} K d M_{s}^{j}-\frac{1}{2} \sum_{j, k} \int_{0}^{t} \nabla_{X_{j}} \nabla_{X_{k}} \pi_{s}^{-1} K d<M^{j}, M^{k}\right\rangle
\end{aligned}
$$

The Ito formula (2.18) can be applied to getting a heat equation for tensor fields. Suppose that $\xi_{t}$ is determined by
(2.20) $d \xi_{t}=\sum_{j=1}^{r} X_{j}\left(\xi_{t}\right) \cdot d B_{t}^{j}+X_{0}\left(\xi_{t}\right) d t$,
where $\left(B_{t}^{1}, \ldots, B_{t}^{r}\right)$ is a Brownian motion. Then,
(2.21) $\quad \pi_{t} K-K=\sum_{j=1}^{r} \int_{0}^{t} \pi_{s} \nabla_{X_{j}} K d B_{s}^{j}+\int_{0}^{t} \pi_{s}\left(\frac{1}{2} \sum_{j=1}^{r} \nabla_{X_{j}}^{2}+\nabla_{X_{0}}\right) K d s$

Theorem 2.5. Define for each $t$ a tensor field $K_{t}$ by

$$
\left(K_{t}\right)_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)=E\left[\left(\pi_{t}{ }^{K}\right)_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)\right] .
$$

Then it satisfies the heat equation

$$
\frac{\partial R_{t}}{\partial t}=\left(\frac{1}{2} \sum_{j=1}^{r} \nabla_{X_{j}}^{2}+\nabla_{x_{0}}\right) K_{t}, \quad K_{0}=k
$$

Proof. We shall omit $\theta^{1}, \ldots, \theta^{\mathrm{p}}, \mathrm{Y}_{1}, \ldots, \mathrm{Y}_{\mathrm{q}}$ for simplicity. Set $K_{s}=E\left[\pi_{s} K\right]$. Taking expectation to both sides of (2.21), we have

$$
K_{s}-K=\int_{0}^{s} E\left[\pi_{u}\left(\frac{1}{2} \sum_{j} \nabla_{X_{j}}^{2}+\nabla_{X_{0}}\right) K\right] d u
$$

Since $K_{x}$ is smooth relative to $x$, so is ( $\left.K_{s}\right)_{x}$.
Let us substitute $K_{t}$ to the above formula. Then

$$
E\left[\pi_{s} K_{t}\right]-K_{t}=\int_{0}^{s} E\left[\pi_{u}\left(\frac{1}{2} \sum_{j=1}^{r} \nabla_{x_{j}}^{2}+\nabla_{x_{0}}\right) K_{t}\right] d u .
$$

Now it holds $\pi_{t+s}=\pi_{t} \hat{\pi}_{s}$, where $\hat{\pi}_{s}$ is the parallel displacement along $\xi_{u}, \mathrm{t} \leq \mathrm{u} \leq \mathrm{t}+\mathrm{s}$ from $\xi_{\mathrm{t}+\mathrm{s}}(\mathrm{x})$ to $\xi_{\mathrm{t}}(\mathrm{x})$. Then by Markov property, we have

$$
E\left[\pi_{s+t} K\right]=E\left[\pi_{t} \hat{\pi}_{s} K\right]=E\left[\pi_{t} K\right.
$$

Consequently,

$$
K_{t+s}-K_{t}=\int_{0}^{s} E\left[\pi_{u}\left(\frac{1}{2} \sum_{j} \nabla_{X_{j}}^{2}+\nabla_{X_{0}}\right) K_{t}\right] d u
$$

so that we have

$$
\frac{\partial}{\partial t} K_{t}=\left(\frac{1}{2} \sum_{j=1}^{r} \nabla_{X_{j}}^{2}+\nabla_{X_{0}}\right) K_{t}
$$

The proof is complete.
3. Ito's formula for $\xi_{t}^{*}$ acting on tensor fields.

In this section, we shall obtain an Ito's formula for stochastic maps $\xi_{t}^{*}$ acting on tensor fields, which is induced by the solution $\xi_{t}(x)$ of (1.7). The formula looks similar to the one for parallel displacement. The only difference is that Lie derivative is involved in place of covariant derivative. The formula has been obtained by
S. Watanabe [9]. His approach is based on the lift of the process to
a frame bundle in a suitable way and the use of scalarization of tensor field on the bundle. On the other hand, our proof is very close to the method in previous section.

Given a diffeomorphism $\phi$ of $M$, the differential $\phi_{*_{X}}$ is a linear map of $T_{x}(M)$ onto $T_{\phi(x)}(M)$. The dual map $\phi_{x}^{*}$ of the differential $\phi_{*_{x}}$ is a linear map of $T_{\phi(x)}(M)^{*}$ onto $T_{x}(M)^{*}$. Let $Y$ be a vector field. The $\phi$-related vector field $\phi_{*}(Y)$ is defined by the
relation $\phi_{*}(\mathrm{Y})_{X}=\phi_{* \phi^{-1}(x)}{ }^{Y} \phi^{-1}(x)$. For 1-form $\theta, \phi^{*}(\theta)$ is defined by $\phi^{*}(\theta)_{\mathbf{x}}=\phi_{\mathbf{x}}^{*} \theta_{\phi(x)}$. The inverse $\phi^{*-1}(\theta)$ is defined in the same way. Let $K$ be a tensor field of type ( $p, q$ ). We define a tensor field $\phi^{*} \mathrm{~K}$ by the relation

$$
\begin{align*}
& \left(\phi^{*} K\right)_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)  \tag{3.1}\\
& =K_{\phi(x)}\left(\phi^{*-1}\left(\theta^{1}\right), \ldots, \phi^{*-1}\left(\theta^{p}\right), \phi_{*}\left(Y_{1}\right), \ldots, \phi_{*}\left(Y_{q}\right)\right) .
\end{align*}
$$

If $K$ is a vector field, it holds $\phi^{*} K=\phi_{*}^{-1}(K)$ and if $K$ is a 1-form, it holds $\phi^{*} K=\phi^{*}(K)$.

Remark. The definition of the above $\phi^{*}$ is not equal to that of $\tilde{\phi}$ in Kobayashi-Nomizu [5], p. 28. The relation of these is $\tilde{\phi}^{-1}=\phi^{*}$ or $\tilde{\phi}=\left(\phi^{-1}\right)^{*}$.

Let $X$ be a complete vector field and $\phi_{t}, t \in(-\infty, \infty)$ be the one parameter group of transformations generated by $X$. The Lie derivative of tensor field $K$ with respect to $X$ is defined by
(3.2) $L_{X} K=\lim _{t \neq 0} \frac{1}{t}\left\{\phi_{t}^{*} K-K\right\}$.

The following properties are well known. (i) If $K$ is a scalar function, then $L_{X} K=X(K)$. (ii) If $K$ is a vector field, then $L_{X} K=[X, K]$, where [, ] is the Lie bracket. (iii) If $Y$ is a vector field and $\theta$ is a 1-form, then

$$
\begin{equation*}
\left.\left\langle\mathrm{L}_{\mathrm{X}} \theta, \mathrm{Y}\right\rangle+\left\langle\theta, \mathrm{L}_{\mathrm{X}}^{\mathrm{Y}}\right\rangle=\mathrm{X}<\theta, \mathrm{Y}\right\rangle \tag{3.3}
\end{equation*}
$$

(iv) If $K$ is a tensor field of type ( $p, q$ ), then

$$
\begin{align*}
&\left(L_{x} K\right)_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)=x\left(K_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right)\right)  \tag{3.4}\\
&-\sum_{k=1}^{p} K_{x}\left(\theta^{1}, \ldots, L_{x} \theta^{k}, \ldots, \theta^{p}, Y_{1}, \ldots, Y_{q}\right) \\
&-\sum_{l=1}^{q} K_{x}\left(\theta^{1}, \ldots, \theta^{p}, Y_{1}, \ldots, L_{X} Y_{\ell}, \ldots, Y_{q}\right)
\end{align*}
$$

Now let $\xi_{t}(x)$ be a solution of stochastic differential equation (1.7). Then $\xi_{t}^{*} K$ is a stochastic tensor field. We shall obtain Ito's formula for $\xi_{t}^{*} K$ and $\left(\xi_{t}^{*}\right)^{-1} K$. We first consider the case that $K$ is a vector field and then the case that $K$ is a 1-form

Lemma 3.1. (c.f. [7], Proposition 5.2 and 5.3). Let $Y$ be a vector field. Then it holds

$$
\begin{align*}
& \xi_{t}^{*} Y=Y+\sum_{j=1}^{r} \int_{0}^{t} \xi_{s}^{*} L_{X_{j}} Y \circ d M_{s}^{j}  \tag{3.5}\\
& \xi_{t^{*}}(Y)=Y-\sum_{j=1}^{r} \int_{0}^{t} L_{X_{j}} \xi_{s *}(Y) \circ d M_{s}^{j} \tag{3.6}
\end{align*}
$$

Lemma 3.2. Let $\theta$ be a 1-form. Then it holds

$$
\begin{align*}
& \xi_{t}^{*} \theta=\theta+\sum_{j} \int_{0}^{t} \xi_{s}^{*} L_{X_{j}} \theta \circ d M_{s}^{j}  \tag{3.7}\\
& \left(\xi_{t}^{*}\right)^{-1} \theta=\theta-\sum_{j} \int_{0}^{t} L_{X_{j}}\left(\xi_{s}^{*}\right)^{-1} \theta \circ d M_{s}^{j} \tag{3.8}
\end{align*}
$$

Proof. We shall prove (3.8) only since (3.7) is a special case
of the next theorem. It holds

$$
\left\langle\left(\xi_{t}^{*}\right)^{-1} \theta, Y\right\rangle_{x}=\left\langle\xi_{t}^{*-1} \theta, Y\right\rangle_{x}=\left\langle\theta, \xi_{t}^{*}\right\rangle_{\xi_{t}^{-1}(x)}
$$

Then similarly as the proof of Proposition 2.3, we have

$$
\left\langle\theta, \xi_{t}^{*} Y_{\xi_{t}}^{-1}(x)-\langle\theta, Y\rangle_{x}=-\sum_{j} \int_{0}^{t}\left\langle L_{X_{j}}\left(\xi_{s}^{*}\right)^{-1} \theta, Y\right\rangle_{x}^{\circ d M_{s}^{j}}\right.
$$

This proves (3.8).
Formulas (3.5), (3.6), (3.7) and (3.8) correspond formulas (2.7), (2.12), (2.15) and (2.16), respectively. Then the next Ito's formula for tensor field $\xi_{t}^{*} K$ is proved in the same way as the case of parallel displacement.

Theorem 3.3. (c.f. S. Watanabe [9]). Let $K$ be a smooth tensor field of type ( $p, q$ ). Then it holds

$$
\begin{align*}
\xi_{t}^{*} K & =K+\sum_{j=1}^{r} \int_{0}^{t} \xi_{s}^{*} L_{X_{j}}{ }^{K} \cdot d M_{s}^{j}  \tag{3.9}\\
& \left.=K+\sum_{j=1}^{r} \int_{0}^{t} \xi_{s}^{*} L_{X_{j}} K d M_{s}^{j}+\frac{1}{2} \sum_{j, k} \int_{0}^{t} \xi_{s}^{*} L_{X_{j}} L_{X_{k}} K d<M^{j}, M^{k}\right\rangle_{s}
\end{align*}
$$

Similarly as Theorem 2.4, we have
Theorem 3.4. Let $\xi_{t}$ be a solution of (2.20). Set

$$
K_{t}=E\left[\xi_{t}^{*} K\right]
$$

$$
\begin{aligned}
\frac{\partial}{\partial t} K_{t} & =\frac{1}{2}\left(\sum_{j=1}^{r} L_{X_{j}}^{2}+L_{X_{0}}\right) K_{t} \\
K_{0} & =K
\end{aligned}
$$

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