### HIROSHI KUNITA

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## On the representation of solutions of stochastic differential equations

#### Hiroshi Kunita

#### 0. Introduction.

Let us consider the stochastic differential equation

(0.1) 
$$d\xi_t = X_0(\xi_t)dt + \sum_{j=1}^{t} X_j(\xi_t) \circ dB_t^{j}$$

defined on a connected  $C^{\infty}$ -manifold M of dimension d. Here  $X_0$ ,  $X_1, \ldots, X_r$  are  $C^{\infty}$ -vector fields on M and  $B_t = (B_t^{\ 1}, \ldots, B_t^{\ r})$  is a standard Brownian motion. The symbol  $\circ$  denotes the Stratonovich-Fisk integral. Recently a number of authors has expressed the solution directly as a functional of  $B_t$ , under some conditions on vector fields  $X_0 \ldots, X_r$ . In Doss [1] Sussman [7], the solution is expressed in such a way that it is a continuous functional of  $B_t$ , if r=1 or  $X_1, \ldots, X_r$  are commutative. However this is not the case in general if  $r \ge 2$  and  $X_1, \ldots, X_r$  are not commutative. In fact, Yamato [8] has proved that the solution is a functional of multiple Wiener integrals of  $B_t$ , provided that the Lie algebra generated by  $X_1, \ldots, X_r$  is nilpotent.

In this paper, we shall consider the similar problem in case that the Lie algebra mentioned above is nilpotent or solvable. In section 2, we will discuss Yamato's result from a different point of view: Applealing Campbell-Hausdorff formula in Lie algebra, we will obtain an explicit expression as a functional of multiple Wiener integrals. Section 1 is devoted to Campbell-Hausdorff formula. In Section 3, we will discuss the case that the Lie algebra is solvable. We will decompose the equation (0.1) into a chain of equations such that the corresponding Lie algebra of each equation is nilpotent, and then show that the solution of (0.1) is expressed as a composition of solutions of these nilpoitent equations.

1. Campbell-Hausdorff formula.

Given a complete  $\tilde{C}$ -vector field X on the manifold M represented as  $\frac{d}{d} X_1(x) \frac{\partial}{\partial x_1}$  with a local coordinate  $(x_1, \ldots, x_d)$ , we denote by  $e^{tX}$  the one parameter group of transformations on M generated by X: This means that  $\phi_t(x) \equiv e^{tX}(x)$  satisfies, (i) for each  $t \in (-\infty, \infty)$ ,  $\phi_t$  is a diffeomorphism of M, (ii)  $\phi_t \circ \phi_s = \phi_{t+s}$  for any t. s  $\in (-\infty, \infty)$ ,  $\lim_{t \to 0} \phi_t(x) = x$  and (iii) it is the solution of the ordinary differential  $\frac{d\phi_t(x)}{dt} = X(\phi_t(x))$  starting at x, where  $X(x) = (X_1(x), \ldots, X_d(x))$ . When t = 1, we write it as  $e^X$ ,

Let X and Y be complete  $C^{\infty}$ -vector fields. We define the Lie bracket [X, Y] by XY - YX. It is often written as X(adY) Campbell-Hausdorff formula is a formula like

$$e^{X}e^{Y} = e^{X+Y-\frac{1}{2}[X, Y]+ \dots}$$

We shall extend the formula to that of n vector fields.

Suppose we are given n  $C^{\infty}$ -vector fields  $Y_1, \ldots, Y_n$  such that  $[\ldots[Y_{i_1}, Y_{i_2}] \ldots, ]Y_{i_m}], m = 1, 2, \ldots$  and their linear sums are all complete vector fields. Consider a formal power series

(1.1) 
$$Z = \Sigma_{m>0} (-1)^{m-1} m^{-1} \Sigma_{p>0} \frac{1}{p_1^{(1)} \cdots p_n^{(1)} p_1^{(2)} \cdots p_n^{(m)} p_1} \frac{1}{|p|}$$

$$\times Y_{1}(adY_{1})^{p_{1}^{(1)}-1}_{(adY_{2})^{p_{2}^{(1)}}...(adY_{n})^{p_{n}^{(1)}}_{n}(adY_{1})^{p_{1}^{(2)}}...(adY_{n})^{p_{n}^{(m)}}_{n}$$

where  $p_1^{(1)}$ , ...,  $p_n^{(m)}$  are nonnegative integers,  $|p| = \sum_{1 \le i \le n, 1 \le j \le m} p_i^{(j)}$ and  $\sum_{p>0}$  means the sum of terms such that  $\frac{n}{i=1}p_i^{(j)} > 0$  for all  $p_2^{(1)}-1$  $1 \le j \le m$ . If  $p_1^{(1)} = 0$ , we understand the first member as  $Y_2(adY_2)^{p_2^{(1)}-1}$ instead of  $Y_1(adY_1)^{p_1^{(1)}-1}$ . Now the term corresponding  $[\dots[Y_{i_1}, Y_{i_2}]\dots, Y_{i_m}]$  appears several times in the power series. Summing up all the corresponding term, we denote the coefficient of the above vector field as  $c_{i_1\cdots i_m}$ . Then the power series is written as

(1.2) 
$$Z = \sum_{m=1}^{\infty} \sum_{(i_1,\ldots,i_m)} c_{i_1\cdots i_m} Y^{i_1\cdots i_m},$$

where

(1.3) 
$$Y^{i_1 \cdots i_m} = [\dots [Y_{i_1}, Y_{i_2}] \dots ]Y_{i_m}$$

Theorem 1.1. (Campbell-Hausdorff formula) Suppose that (1.2) is absolutely convergent and define a complete vector field. Then it holds

(1.4) 
$$e^{Y_n} \dots e^{Y_1} = e^Z$$
.

The proof may be found in Jacobson [5] in case n = 2. It can be applied to the present case with a simple modification.

We shall compute coefficients  $c_{i_1...i_m}$ . Let us divide the multiindex I =  $(i_1, ..., i_m)$  to a sequence of shorter ones  $I_j$ , j = 1, ...,  $\ell$ and write it as  $\hat{I}$ ;

(1.5) 
$$\hat{\mathbf{I}} = (\mathbf{I}_1, \dots, \mathbf{I}_{k_1})(\mathbf{I}_{k_1+1}, \dots, \mathbf{I}_{k_2}) \dots (\mathbf{I}_{k_{\ell-1}+1}, \dots, \mathbf{I}_{k_{\ell}})$$

where each index  $I_k$  consists of same number  $\hat{i}_k$  and these numbers  $\hat{i}_k$ , k = 1, ...,  $k_{\ell}$  satisfies

(1.6) 
$$\hat{i}_1 > \hat{i}_2 > \dots > \hat{i}_{k_1} < \hat{i}_{k_1+1} > \dots > \hat{i}_{k_2} \dots < \hat{i}_{k_{\ell-1}+1} > \dots > \hat{i}_{k_{\ell}}$$

The division  $\hat{I}$  is defined uniquely from I. We call this a natural division. We denote the length of  $I_k$  (the number of elements in  $I_k$ ) as  $n_k$ . Then  $\sum_{k=1}^{k_k} n_k = m$ . Divide again each index  $I_k$  into  $j_k$  indices, each of which consists of  $n_k^{(1)}$  elements (i = 1, ...,  $j_k$ ). Hence it holds  $n_k^{(1)} + \dots + n_k^{(j_k)} = n_k$ . Then we have

(1.7) 
$$c_{i_1\cdots i_m} = \frac{1}{m} \sum_{s=0}^{\ell-1} \sum_{s=0}^{j_1+\cdots+j_k} (j_1 + \cdots + j_k - s)^{-1}$$

$$\times \frac{1}{n_{1}^{(1)}! \dots n_{1}^{(j_{1})} \dots n_{k_{\ell}}^{(1)}! \dots n_{k_{\ell}}^{(j_{\ell})}}$$

Here, the sum  $\Sigma_{\star}$  is taken for all subdivisions of  $I_k$ ,  $k = 1, ..., k_{\ell}$ , i.e., for all positive integers  $n_k^{(i)}$ ,  $i = 1, ..., j_k$ ,  $k = 1, ..., k_{\ell}$ such that  $\sum_{i} n_k^{(i)} = n_k$ .

Let I' be another multi-index of length m and let

$$\hat{\mathbf{I}}' = (\mathbf{I}'_1, \dots, \mathbf{I}'_{k_1}) \dots (\mathbf{I}'_{k_{l-1}+1}, \dots, \mathbf{I}'_{k_{l}})$$

be its natural division. We say that I and I' are equivalent if for each k  $I_k$  and  $I'_k$  contain the same number of elements and  $k'_1 = k_1, \ldots, k'_{\ell} = k_{\ell}$  hold. Note that  $c_I = c_I$ , holds if I and I' are equivalent. If each  $I_k$  in (1.5) contains a single element, I is divided as

$$\hat{\mathbf{I}} = (\mathbf{i}_1, \dots, \mathbf{i}_{k_1})(\mathbf{i}_{k_1+1}, \dots, \mathbf{i}_{k_2}) \dots (\mathbf{i}_{k_{\ell-1}+1}, \dots, \mathbf{i}_{k_{\ell}})$$

where  $k_{l} = m$ . We will call such I as single. In this case, (1.7) becomes

(1.8) 
$$c_{i_1\cdots i_m} = \frac{1}{m} \sum_{s=0}^{\ell-1} {\binom{\ell-1}{s}} (-1)^{m-s-1} (m-s)^{-1}$$

We shall calculate a few of coefficients

(a) 
$$c_{i} = 1$$
  
(b)  $c_{ij} = -\frac{1}{4}$  if  $i > j$ ,  $c_{ij} = \frac{1}{4}$  if  $i < j$   
(c)  $c_{ijk} = \begin{cases} \frac{1}{9} & \text{if } i < j < k \text{ or } k < j < i \\ -\frac{1}{18} & \text{if } j < i \& j < k \text{ or } j > i \& j > k \\ \frac{1}{36} & \text{if } i \neq j = k \end{cases}$ 

2. Representation of solutions (I). Nilpotent case.

Consider the stochastic differential equation on M.

(2.1) 
$$d\xi_t = X_0(\xi_t)dt + \sum_{j=1}^r X_j(\xi_t) \circ dB_t^j$$
,

where  $X_0, X_1, \ldots X_r$  are complete  $C^{\infty}$ -vector fields. If  $X_0, X_1, \ldots X_r$ are commuting, i.e.,  $[X_i, X_j] = 0$  for each i and j, then the solution of the above equation starting at x is represented as

(2.2) 
$$\xi_t(x) = \exp(tX_0 + B_t^1X_1 + \dots + B_t^rX_r)(x)$$

Here we understand that  $tX_0(\omega) + B_t^1(\omega)X_1 + \ldots + B_t^r(\omega)X_r$  is a vector field for each t and a.s.  $\omega$ . This means that  $\xi_t(x, \omega)$  equals  $\phi_1(x, \omega)$  a.s., where  $\phi_s(x, \omega)$  is the solution of the ordinary differential equation

$$\frac{\mathrm{d}\phi_{\mathrm{s}}}{\mathrm{d}t} = (tX_{0}(\omega) + \ldots + B_{\mathrm{t}}^{\mathrm{r}}(\omega)X_{\mathrm{r}})(\phi_{\mathrm{s}}),$$

regarding t and  $\omega$  as parameters. The fact can be proved directly, applying Ito's formula [4] to (2.2). However, if  $X_0$ , ...,  $X_r$  are not commuting, the formula (2.2) is not valid. We have to add several terms to the right hand of (2.2). This will be done in Theorem 2.3.

Our basic assumption in this section is that the Lie algebra  $L = L(X_0, X_1, ..., X_r)$  generated by  $X_0, X_1, ..., X_r$  is nilpotent of step p, i.e.,

$$[\dots [X_{i_1}, X_{i_2}] \dots ]X_{i_m}] = 0$$

holds whenever  $i_1, \ldots, i_m \in \{0, 1, \ldots, r\}$  and m > p. The algebra L is then a finite dimensional vector space, obviously. Then any element of L is a complete (or proper) vector field (See Palais [6], p.95). Under the same condition, Yamato [8] showed that the solution  $\xi_t$  of equation (2.1) is a functional of multiple Wiener integrals of  $B_t$  of degrees less than or equal to p. We will obtain the functional in a more explicit manner, making use of Campbell-Hausdorff formula. We begin with notations on multi-index. We shall divide a multiindex I =  $(i_1, \ldots, i_m)$  to shorter ones; I =  $I_1 \ldots, I_q \quad (q \le m)$ , where each  $I_k$  consists of the same element  $\hat{i_j}$ . Given positive integers  $k_1 < k_2 < \ldots < k_g = q$ , we define a divided index of I as

(2.3) 
$$\Delta I = (I_1, \ldots, I_{k_1})(I_{k_1+1}, \ldots, I_{k_2}) \ldots (I_{k_{\ell-1}+1}, \ldots, I_{k_{\ell}})$$

(This time we do not assume relation (1.6)). If each  $I_k$  contains a single element (or at most two), we say that  $\Delta I$  is single (or double). The equivalence of two indices  $\Delta I$  and  $\Delta I'$  is defined similarly as in Section 1. Suppose now we are given an index I and a divided one  $\Delta I$ .  $\Delta I$  is not equal to the natural division of I. But if there is an index I' such that its natural division  $\hat{I}'$  is equivalent to  $\Delta I$ , then we set  $c_{\Delta I} = c_I$ , for convention.

Let  $B_t = (B_t^1, \ldots, B_t^r)$  be a standard r-dimensional Brownian motion. We set  $B_t^0 = t$  for convention. Given a single divided index  $\Delta I$ , we define the multiple Wiener integral  $B_t^{\Delta I}$  as

(2.4) 
$$B_t^{\Delta I} = \int \dots \int_A dB_{t_1}^{i_1} \dots dB_{t_m}^{i_m}$$

where

(2.5) 
$$A = \{t_{k_1} < \dots < t_1 < t, \dots, t_{k_{\ell}} < \dots < t_{k_{\ell-1}} + 1 < t, t_{k_1} < t_{k_1} + 1, \dots < t_{k_{\ell-1}} + 1 < t, t_{k_1} < t_{k_{\ell}} + 1, \dots < t_{k_{\ell}} < t$$

i = 1, ..., l}

If  $\Delta I$  is a double index, we define

(2.6) 
$$B_{t}^{\Delta I} = \int \dots \int_{A} dB_{t_{1}}^{I_{1}} \dots dB_{t_{k}}^{I_{k_{\ell}}},$$

where

(2.7) 
$$B_{t}^{I_{k}} = \begin{cases} a_{t}^{i_{k}} & \text{if } I_{k} = \{i_{k}\} \text{ (single)} \\ t & \text{if } I_{k} = \{i_{k}, i_{k}\} \text{ (double)} \end{cases}$$

Lemma 2.1. Let  $\xi_t(x)$  be the solution of (2.1) with  $\xi_0 = x$ . Then it is represented as

(2.8) 
$$\xi_t(x) = (\exp W_t)(x),$$

where

(2.9) 
$$W_{t} = tX_{0} + \dots + B_{t}^{r}X_{r} + \sum_{J:1 < |J| \le p} \{\Sigma^{*} c_{\Delta J}B_{t}^{\Delta J}\}X^{J}$$
$$X^{J} = [\dots [X_{j_{1}}, X_{j_{2}}] \dots ]X_{j_{m}}] \quad (J = (j_{1}, \dots, j_{m}))$$

Here  $\sum_{\substack{\Delta J \\ \Delta J}}^{\chi}$  is the sum for all single and double divided indices of J.  $\Delta J$ Proof. For a fixed positive integer n and positive time t, set  $\delta B_k^j = B_{k-1}^j - B_{k-1}^j$  and define  $Y_1 = \frac{t}{n} X_0 + \delta B_1^1 X_1 + \ldots + \delta B_1^r X_r$ .  $Y_n = \frac{t}{n} X_0 + \delta B_n^1 X_1 + \ldots + \delta B_n^r X_r$ 

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Set

(2.10) 
$$\xi_t^{(n)}(x) = (\exp Y_n \dots \exp Y_1)(x)$$

Then, clearly it is the value at 1 of the solution of equation

$$\frac{d\xi'_s}{ds} = (X_0 + \frac{n}{t} \sum_{j=1}^{t} \delta B_k^j X^j) (\xi'_s) \text{ if } (\frac{k-1}{n}) t \le s \le \frac{k}{n} t$$

There is a subsequence of  $\xi_t^{(n)}(x)$  converging to  $\xi_t(x)$  a.s.

We shall next apply Campbell-Hausdorff formula to the right hand side of (2.10). It holds

(2.11) 
$$\sum_{\substack{i_1,\dots,i_m \\ (i_1,\dots,i_m)}} \sum_{\substack{i_1\dots i_m \\ (i_1,\dots,i_m)}} \sum_{\substack{j_1,\dots,j_m \\ (i_1,\dots,i_m \\ (i_1,\dots,i_m)}} \sum_{\substack{j_1,\dots$$

Here  $\Sigma_{I:\hat{I}} \sim \Delta_J \delta_{I_1}^{j_1} \dots \delta_{I_m}^{j_m}$  means the sum for all indices I such that  $\hat{I}$  is equivalent to  $\Delta_J$ . The sum converges to  $B_t^{\Delta J}$  if  $\Delta_J$  is a single or double index. If  $\Delta_J$  is more than double (i.e.,  $\Delta_J$  contains a subindex I<sub>k</sub> with more than two elements), then the sum converges to 0. Therefore, (2.11) converges a.s. to

$$\sum_{\mathbf{J}} \{ \sum_{\Delta \mathbf{J}} \mathbf{E}_{\Delta \mathbf{J}} \mathbf{B}_{\mathbf{t}}^{\Delta \mathbf{J}} \} \mathbf{X}^{\mathbf{J}}.$$

This proves that the sum of (2.11) for m = 1, 2, ... converges to  $W_t$  a.s.

Then the exponential map converges a.s. to e<sup>W</sup>t. The proof is complete. We shall next calculate multiple Wiener integrals in (2.9) in cases

that |J| are 2 and 3. We introduce notations.

$$[B^{i}, B^{j}]_{t} = \int_{0}^{t} B_{s}^{i} dB_{s}^{j} - \int_{0}^{t} B_{s}^{j} dB_{s}^{i}$$

This indicates the stochastic area enclosed by the Brownian curve  $(B_s^i, B_s^j)$ ,  $0 \le s \le t$  and its chord. Similarly, we set

$$[[B^{i}, B^{j}], B^{k}]_{t} = \int_{0}^{t} [B^{i}, B^{j}]_{s} dB^{k}_{s} - \int_{0}^{t} B^{k}_{s} d[B^{i}, B^{j}]_{s}$$

Lemma 2.2 (i) Coefficient of  $X^{ij}$  in (2.9) equals  $\frac{1}{2}[B^i, B^j]_t$ if  $i \neq j$ . (ii) Coefficient of  $X^{ijk}$  equals  $\frac{1}{18}[[B^i, B^j], B^k]_t$  if i, j, k are different or  $0 = j = k \neq i$ . If  $0 < j = k \neq i$ , it equals  $\frac{1}{36} tB_t^i$  plus the above quantity.

Proof. The coefficient of  $X^{ij}$  equals

$$c_{(i)(j)}B_{t}^{(i)(j)} + c_{(ij)}B_{t}^{(ij)}$$
  
=  $\frac{1}{4} \iint_{0 \le s \le u \le t} dB_{s}^{i}dB_{u}^{j} - \frac{1}{4} \iint_{0 \le u \le s \le t} dB_{s}^{i}dB_{u}^{j} = \frac{1}{4}[B^{i}, B^{j}]_{t}$ 

The coefficient of  $X^{ji}$  is then equal to  $\frac{1}{4}[B^{j}, B^{i}]_{t}$ . Since  $X^{ij} = -X^{ji}$ , joining these two terms, we see that coefficient of  $X^{ij}$  is  $\frac{1}{2}[B^{i}, B^{j}]_{t}$ .

We shall next consider coefficient of  $X^{ijk}$ . If i, j, k are different or if  $0 = j = k \neq i$ , terms corresponding to double indices are 0 and what we have is

$$c_{(i)(j)(k)}B_{t}^{(i)(j)(k)} + c_{(i)(jk)}B_{t}^{(i)(jk)} + c_{(ij)(k)}B_{t}^{(ij)(k)} + c_{(ijk)}B_{t}^{(ijk)}$$

$$= \frac{1}{9} \iiint_{\substack{0 < t_{i} < t_{j} < t_{k} < t}} dB_{t_{i}}^{i} dB_{t_{j}}^{j} dB_{t_{k}}^{k} - \frac{1}{18} \iiint_{\substack{0 < t_{i} < t_{j} < t \\ 0 < t_{k} < t_{j} < t \\ 0 < t_{k} < t_{j} < t \\ 1 & 0 & 0 & 0 \\ 0 < t_{k} < t_{j} < t \\ 0 < t_{k} < t_{j} < t \\ 1 & 0 & 0 & 0 \\ 0 < t_{k} < t_{j} < t \\ 1 & 0 & 0 & 0 \\ 0 < t_{k} < t_{j} < t \\ 1 & 0 & 0 & 0 \\ 0 < t_{k} < t_{j} < t \\ 1 & 0 & 0 & 0 \\ 0 < t_{k} < t_{j} < t \\ 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 < t_{k} < t_{j} < t_{i} < t \\ 1 & 0 & 0 & 0 \\ 0 < t_{k} < t_{j} < t_{i} < t \\ 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 < t_{k} < t_{j} < t_{i} < t \\ 1 & 0 & 0 & 0 \\ 1 & 0 &$$

Similarly, the coefficient of X<sup>jik</sup> is

$$\frac{1}{18} \{ [[B^{j}, B^{i}], B^{k}]_{t} + [[B^{i}, B^{k}], B^{j}]_{t} \}$$

Since  $x^{jik} = -x^{ijk}$ , we join these two and see that the coefficient of  $x^{ijk}$  is

(2.12) 
$$\frac{1}{18} \{ 2[[B^{i}, B^{j}], B^{k}]_{t} + [[B^{j}, B^{k}], B^{i}]_{t} - [[B^{i}, B^{k}], B^{j}]_{t} \}$$

We have on the other hand Jacobi identity

$$[[B^{i}, B^{j}], B^{k}]_{t} + [[B^{k}, B^{i}], B^{j}]_{t} + [[B^{j}, B^{k}], B^{i}]_{t} = 0.$$

Substitute the above to (2.12), then we see that the coefficient of  $X^{ijk}$  is  $\frac{1}{18} [[B^i, B^j], B^k]_t$ .

If  $i \neq j = k \neq 0$  the coefficient of  $X^{ijk}$  contains terms with double indices. These are

$$c_{(ijj)} \int_{0}^{t} sdB_{s}^{i} + c_{(i)(jj)} \int_{0}^{t} B_{s}^{i} ds = \frac{1}{36} tB_{t}^{i}$$

which should be added to the quantity obtained above.

Summarizing these two lemmas, we establish the following theorem.

Theorem 2.3. Suppose that the Lie algebra generated by  $X_0$ , ...,  $X_r$  is nilpotent of step p. Then the solution of equation (2.1) with  $\xi_0 = x$  is represented as  $\xi_t(x) = (\exp W_t)(x)$ , where

$$(2.13) \qquad W_{t} = \sum_{i=1}^{r} B_{t}^{i} x^{i} + \frac{1}{2} \sum_{i < j} [B^{i}, B^{j}]_{t} [X_{i}, X_{j}] \\ + \frac{1}{18} \sum_{i < j, k} [[B^{i}, B^{j}], B^{k}]_{t} [[X^{i}, X^{j}], X^{k}] + \frac{1}{36} \sum_{i=0}^{r} \sum_{j=1}^{r} t B_{t}^{i} [[X_{i}, X_{j}], X_{j}] \\ + \sum_{j;3 < |J| < p} \left\{ \sum_{\Delta J} c_{\Delta J} B_{t}^{\Delta J} \right\} x^{J}$$

Example (Yamato [8]) Consider the equation in  $\mathbb{R}^3$  where  $X_0 = 0$ ,  $X_1 = \frac{\partial}{\partial x_1} + 2x_2 \frac{\partial}{\partial x_3}$  and  $X_2 = \frac{\partial}{\partial x_2} - 2x_1 \frac{\partial}{\partial x_3}$ . Then  $[X_1, X_2] = -4 \frac{\partial}{\partial x_3}$ and  $[[X_1, X_2], X_1] = [[X_1, X_2], X_2] = 0$ . Hence the corresponding Lie algebra is nilpotent of step 2. The solution is then written as  $\xi_t(x) = \exp W_t(x)$ , where

$$W_{t} = B_{t}^{1}X_{1} + B_{t}^{2}X_{2} + \frac{1}{2}[B^{1}, B^{2}]_{t}[X_{1}, X_{2}]$$
$$= B_{t}^{1}\frac{\partial}{\partial x_{1}} + B_{t}^{2}\frac{\partial}{\partial x_{2}} + 2\{B_{t}^{1}x_{2} - B_{t}^{2}x_{1} - [B^{1}, B^{2}]_{t}]\frac{\partial}{\partial x_{3}}$$

Therefore

$$\exp W_{t}(x) = \begin{cases} x_{1} + B_{t}^{1} \\ x_{2} + B_{t}^{2} \\ x_{3} + 2\{B_{t}^{1}x_{2} - B_{t}^{2}x_{1} - [B^{1}, B^{2}]_{t}\} \end{cases}$$

where  $x = (x_1, x_2, x_3)$ .

We shall mention that similar representation is valid for a more general class of stochastic differential equation. Let us consider a vector field valued stochastic process. Let  $X(t, x, \omega) = X(t, \omega)$ be a stochastic process such that for each t > 0, it is a  $C^{\infty}$ -vector field for almost all  $\omega$ . We assume that it is continuous in t for almost all  $\omega$  and  $F_t$ -adapted, where  $F_t$ ,  $t \ge 0$  is a given family of increasing  $\sigma$ -fields. Suppose we are given r + 1 vector field valued stochastic processes  $X_0, X_1, \ldots, X_r$ . We will call that  $\{X_0, X_1, \ldots, X_r\}$ is nilpotent of step p, if

 $[\dots [X_{i_1}, X_{i_2}] \dots, ]X_{i_m}](t_1, \dots, t_m \omega) = 0$  a.s. p

holds for any  $i_1, \ldots, i_m \in \{0, 1, \ldots, r\}$  and  $t_1, \ldots, t_m \ge 0$  if m > p.

Let  $B_t = (B_t^1, \ldots, B_t^r)$  be a  $F_t$ -Brownian motion. Consider the stochastic differential equation

(2.14) 
$$\xi_{t} = x + \int_{0}^{t} X_{0}(s, \xi_{s}, \omega) ds + \sum_{j=1}^{r} \int_{0}^{t} X_{j}(s, \xi_{s}, \omega) dB_{s}^{j}$$

Theorem 2.2. Suppose that for each i,  $X_i(t, \omega)$  is a complete vector field for any t and a.s.  $\omega$ . Suppose further that the Lie algebra generated by  $\{X_0, X_1, \ldots, X_r\}$  is finite dimensional and nilpotent. Then the solution of (2.14) is represented as exp W(t), where

$$W(t, x) = \int_{0}^{t} X_{0}(s, x) ds + \frac{r}{\sum_{j=1}^{t}} \int_{0}^{t} X_{j}(s, x) \circ dB_{s}^{j}$$

+ 
$$\sum_{J:1 < |J| \le p} \sum_{\Delta J} c_{\Delta J} \int_{A} x^{J}(\hat{s}_{1}, \ldots, \hat{s}_{\ell}) \circ dB_{s_{1}}^{J} \ldots \circ dB_{s}^{\ell},$$

where A is the set of (2.5),  $B_s^{J_k}$  is defined by (2.7) and  $\hat{s}_k = s_k^{J_k}$ if  $|J_k| = 1$  and  $\hat{s}_k = (s_k, s_k)$  if  $|J_k| = 2$ . The sum  $\Sigma^*$  is taken for all single or double divided indices  $\Delta J$  of J.

The proof is similar to that of Lemma 2.1.

#### 3. Representation of solutions (II). Solvable case

Let  $L = L(X_0, X_1, ..., X_r)$  be the Lie algebra of vector fields generated by  $X_0, X_1, ..., X_r$ . Define a chain of Lie algebras as  $L_1 = [L, L], L_2 = [L_1, L_1], ..., L_n = [L_{n-1}, L_{n-1}]$ . Then  $L \supset L_1 \supset L_2 \supset ...$ and  $L_i$  is an ideal in  $L_{i-1}$ . The Lie algebra L is called solvable if there exists p such that  $L_p = \{0\}$ . By the definition, nilpotent Lie algebra is solvable.

Consider the stochastic differential equation

(3.1) 
$$d\xi_{t} = X_{0}(\xi_{t})dt + \sum_{j=1}^{r} X_{j}(\xi_{t}) \circ dB_{t}^{j}.$$

The purpose of this section is to show that the above equation is decomposed to a chain of equations whose coefficients are nilpotent vector fields if L is a finite dimensional solvable algebra. We will then prove that the solution of (3.1) is expressed as a composition of solutions of these equations.

The differential of smooth map is needed for our discussion. Let  $\Phi$  be a diffeomorphism of the manifold M. The differential  $\Phi_{\star}$  is an automorphism of the space of vector fields defined by

(3.2) 
$$\Phi_{\star} X(f)(x) = X(f \circ \Phi)(\Phi^{-1}(x)), \qquad \forall f \in C^{\infty}(M),$$

where  $C^{\infty}(M)$  is the space of all real  $C^{\infty}$ -functions on M.

Let  $\{Y_0, \ldots, Y_r\}$  be a nilpotent subset of L. Consider the stochastic differential equation

(3.3) 
$$d\zeta_t = Y_0(\zeta_t)dt + \sum_{j=1}^r Y_j(\zeta_t) \cdot dB_t^j.$$

The solution  $\zeta_t(\mathbf{x})$  starting at  $\mathbf{x}$  is represented as (2.6), so that  $\zeta_t$  may be regarded as a diffeomorphism for each t > 0 and almost all  $\omega$ . Set

(3.4) 
$$Z_j = (\zeta_t^{-1})_* (X_j - Y_j), \quad j = 0, ..., r.$$

These are vector field valued stochastic processes. Consider

(3.5) 
$$d\eta_t = Z_0(\eta_t)dt + \sum_{j=1}^{t} Z_j(\eta_t) \circ dB_t^{j}$$

Proposition 3.1. Solutions of equations (3.1), (3.3) and (3.5) are linked by the relation  $\xi_t = \zeta_t \circ \eta_t$ .

Proof. Using a local coordinate, we shall write  $\eta_t = (\eta_t^1, ..., \eta_t^d)$  etc. We put t as  $B_t^0$  for convention. Let f be a C<sup>°</sup>-function. By Ito's formula we have

(3.6) 
$$f(\zeta_{t} \circ \eta_{t}) - f(x) = \sum_{k} \int_{0}^{k} \frac{\partial f}{\partial x_{k}} (\zeta_{t}(x)) \circ d\zeta_{t}^{k}(x) \Big|_{x=\eta_{t}}$$
$$+ \sum_{\ell} \int_{0}^{t} \frac{\partial}{\partial x_{\ell}} (f \circ \zeta_{t}) (\eta_{t}) \circ d\eta_{t}^{\ell}$$

Since  $d\zeta_t^k = \Sigma Y_j^k(\zeta_t) \circ dB_t^j$ , the first term of the right hand side equals

$$\sum_{k} \int_{0}^{t} \sum_{j} Y_{j}^{k}(\zeta_{t}(\mathbf{x})) \frac{\partial f}{\partial \mathbf{x}_{k}}(\zeta_{t}(\mathbf{x})) \cdot dB_{t}^{j}\Big|_{\mathbf{x}=\eta_{t}}$$
$$= \sum_{j} \int_{0}^{t} Y_{j}f(\zeta_{t} \cdot \eta_{t}) \cdot dB_{t}^{j}.$$

The second term is

$$\sum_{\ell} \int_{0}^{t} \sum_{j} z_{j}^{\ell} (n_{t}) \frac{\partial}{\partial x_{\ell}} (f \circ \zeta_{t}) (n_{t}) \circ dB_{t}^{j}$$

$$= \sum_{j} \int_{0}^{t} z_{j} (f \circ \zeta_{t}) (n_{t}) \circ dB_{t}^{j}$$

$$= \sum_{j} \int_{0}^{t} (X_{j} - Y_{j}) (f \circ \zeta_{t} \circ \zeta_{t}^{-1}) (\zeta_{t} \circ n_{t}) \circ dB_{t}^{j}$$

$$= \sum_{j} \int_{0}^{t} (X_{j} - Y_{j}) f (\zeta_{t} \circ n_{t}) \circ dB_{t}^{j}$$

Therefore we have

$$f(\zeta_t \circ \eta_t) - f(x) = \sum_{j = 0}^{L} \int_{0}^{t} X_j f(\zeta_t \circ \eta_t) \circ dB_t^j$$

Since this holds for any  $C^{\infty}$ -function, we see that  $\zeta_{t} \circ \eta_{t}(x)$  is the solution of (3.1) starting at x. The proof is complete.

Now we shall decompose vector fields  ${\rm X}_{0}^{},\,\ldots,\,{\rm X}_{r}^{}$  into sums of vector fields

$$X_0 = X_0^{(1)} + \ldots + X_0^{(n)}, \ldots, \quad X_r = X_r^{(1)} + \ldots + X_r^{(n)}$$

such that

$$L^{(1)} = L(X_0^{(1)}, \ldots, X_r^{(1)}), \ldots, L^{(n)} = L(X_0^{(n)}, \ldots, X_r^{(n)})$$

are all nilpotent Lie algebra. Such a decomposition exists always, although it is not unique. For example, let us choose a basis of  $L = L(X_0, ..., X_r)$  and denote it as  $Y_1, ..., Y_n$ . Then each  $X_i$  is written as  $X_i = \frac{n}{j=1} a_{ij} Y_j$ . Setting  $X_i^{(j)} = a_{ij} Y_j$ , for example, we have a decomposition mentioned above.

Let us now consider a chain of stochastic differential equations.

(3.7) 
$$d\zeta_{t}^{\ell} = \sum_{j=0}^{r} x_{j}^{\ell} \circ dB_{t}^{j}, \qquad \ell = 1, ..., n$$

(3.8) 
$$d\xi_t^{\ell} = \sum_{j=0}^r (\xi_t^{\ell-1})_*^{-1} \dots (\xi_t^{1})_*^{-1} X_j^{\ell} \circ dB_t^{j}, \quad \ell = 2, 3, \dots n$$

where  $\xi_t^1 = \zeta_t^1$  and

(3.9) 
$$d\eta_{t}^{\ell} = \sum_{j=0}^{t} (\zeta_{t}^{\ell})_{\star}^{-1} \{ (\xi_{t}^{\ell-1})_{\star}^{-1} \dots (\xi_{t}^{1})_{\star}^{-1} x_{j}^{\ell} - x_{j}^{\ell} \} \circ_{dB_{t}^{j}}^{dB_{t}^{j}},$$
$$\ell = 2, 3, \dots, n$$

Since  $L^{(\ell)}$  is nilpotent, the solution  $\zeta_t^{\ell}(x)$  is a diffeomorphism of M for each t and a.s.  $\omega$ . Hence the differential  $(\zeta_t^{\ell})_{\star}^{-1}$  is well defined. In order to show the analogous fact for  $\xi_t^{\ell}(x)$  and  $\eta_t^{\ell}(x)$ , we require

Lemma 3.2. Coefficients of equations on  $\eta_t^{\ell}$  are nilpotent. Proof. We will prove that coefficients of the equation are in L<sub>1</sub>, since L<sub>1</sub> is nilpotent ([5], p. 51). We first consider the case  $\ell = 2$ . Since  $\xi_t^1(x) = \zeta_t^1(x) = \exp W_t$  where  $W_t$  is the vector field valued stochastic process of (2.9), it is a diffeomorphism of M for each t and a.s.  $\omega$ . Hence the differential  $(\xi_t^1)_{\star}^{-1}$  is well defined. We shall show that  $(\xi_t^1)_{\star}^{-1} x_j^{\ell} - x_j^{\ell}$  belongs to  $L_1$  a.s. P for each j and  $\ell$ , following the argument of Ichihara-Kunita [3]. Let us choose  $Y_1, \ldots, Y_n$  as a basis of L, such that  $Y_1, \ldots, Y_k$  (k < n) is a basis of  $L_1$ . Set  $Y_k(s) = (e^{t})_{\star} Y_k$ , the parameter t being fixed. Then it is known that

$$\frac{\frac{dY_k(s)}{ds}}{=} = (e^{sW_t})_*[W_t, Y_k]$$

Since  $[W_t, Y_k]$  in  $L_1$ , it is written as

$$[W_t, Y_k] = \sum_{i=1}^n a_{ki}(t)Y_i, \qquad a_{ki}(t) = 0 \quad \text{if } k < i \leq n.$$

Then the above equation derives a system of linear differential equations

$$\frac{dY(s)}{ds} = AY(s), \quad Y(s) = [Y_1(s), \dots, Y_n(s)], \quad A = (a_{ki}(s))$$

The solution is then written as

$$Y(s) = e^{As}Y(0) = \sum_{p=0}^{\infty} \frac{s^p}{p!} A^p Y(0)$$

Note that  $a_{mi}^{(p)} = 0$  if  $k \le i \le n$ , where  $(a_{mi}^{(p)}) = A^p$ . Then Y(s) - Y(0) is a linear sum of  $Y_1, \ldots, Y_k$ . Since  $X_j^{\ell}$  is written as a linear sum of  $Y_1, \ldots, Y_n$ ,  $(e^{sW_t})_* X_j^{\ell} - X_j^{\ell}$  also a linear sum of  $Y_1, \ldots, Y_k$ , so that it is in  $L_1$ . Since  $(e^{-1})_* = (e^{-1})_*^{-1}$ , we see that  $(e^{-1})_*^{-1} X_j^{\ell} - X_j^{\ell}$  is in  $L_1$  a.s. P for any  $t \ge 0, 0 \le j \le r, 1 \le \ell \le n$ .

Now noting that  $L_1$  is an ideal in L, we can show similarly as the above argument that  $(\zeta_t^2)_{\star}^{-1}$  maps  $L_1$  into itself. Therefore  $(\zeta_t^2)_{\star}^{-1}\{(\xi_t^2)_{\star}^{-1}X_j^{\ell} - X_j^{\ell}\}$  is in  $L_1$  a.s. P for any  $t \ge 0$ ,  $0 \le j \le r$ and  $1 \le \ell \le n$ . We have thus shown that coefficients of equation on  $n_{\star}^2$  are nilpotent.

The solution  $\xi_t^2$  has the decompotion  $\zeta_t^2 \circ \eta_t^2$  by Lemma 3.1. Hence  $\xi_t^2$  is a diffeomorphism of M for each t and a.s.  $\omega$ . Thus equations (3.8) and (3.9) are well defined for  $\ell = 3$ . We then see that coefficients of equation on  $\eta_t^3$  are nilpotent as before. Repeating this argument, it turns out that coefficients of equations on  $\eta_t^{\ell}$  are nilpotent for all  $\ell = 2, 3, ..., n$ . The proof is complete.

We can now show the following theorem.

Theorem 3.3. Suppose that the Lie algebra generated by  $X_0$ ,  $X_1$ , ...,  $X_r$  is finite dimensional and solvable. Then the solution of the equation (3.1) is represented as

(3.10) 
$$\xi_{t} = \zeta_{t}^{1} \circ \zeta_{t}^{2} \circ \eta_{t}^{2} \circ \cdots \circ \zeta_{t}^{n} \circ \eta_{t}^{n},$$

where  $\zeta_t^{\ell}$  and  $\eta_t^{\ell}$  are solutions of equations (3.7) and (3.9) with nilpotent coefficients.

Proof. We have  $\xi_t = \xi_t^1 \circ \dots \circ \xi_t^n$  by Lemma 3.1. Furthermore it holds  $\xi_t^{\ell} = \zeta_t^{\ell} \circ \eta_t^{\ell}$  for  $\ell = 2, \dots, n$ . Hence we get the representation (3.10).

If coefficients of equations on  $\xi_t^{\ell}$  in (3.8) are already nilpotent, it is not necessary to decompose it to  $\xi_t^{\ell}$  and  $\eta_t^{\ell}$ , and we may obtain a shorter decomposition of  $\xi_t$ . This occurs if  $X_j^{\ell}$ , j = 0, ..., r are in the derived ideal  $L_1$ , since  $(\xi_t^{\ell-1})_{\star}^{-1} \dots (\xi_t^1)_{\star}^{-1} X_j^{\ell}$  are in  $L_1$  for any j = 0, ..., r. We shall discuss two examples. Example 1. (Linear System) Consider

$$(3.11) \qquad d\xi_t = A\xi_t dt + CB_t,$$

where A is a d×d-matrix and C is a d×r-matrix. Corresponding vector fields are

$$X_{0} = \sum (\sum_{i \neq j} a_{ij} x_{j}) \frac{\partial}{\partial x_{i}}, \quad X_{j} = \sum_{i} c_{ij} \frac{\partial}{\partial x_{i}}$$

It holds

$$(adX_0)^n X_j = (-1)^n \sum_i (A^n C)_{ij} \frac{\partial}{\partial x_i}$$

The Lie algebra L generated by  $X_0$  and  $X_j$  is the linear span of  $X_0$  and  $(ad^n X_0)X_j$ , n = 0, 1, 2, ... The derived ideal  $L_1 = [L, L]$  is the linear span of  $(adX_0)^n X_j$ , n = 1, 2, ... Since latters are commuting each other, it holds  $L_2 = [L_1, L_1] = \{0\}$ . Hence L is solvable.

Consider two equations

$$d\xi_{t}^{1} = X_{0}dt$$
$$d\xi_{t}^{2} = \sum_{j=1}^{r} (\xi_{t}^{1})_{*}^{-1}X_{j} \circ dB_{t}^{j}$$

Then it holds  $\xi_t^1(x) = e^{tA}x$  and

$$(\xi_t^1)_{\star}^{-1} X_j = \sum_i (e^{-tA}C)_{ij} \frac{\partial}{\partial x_i}$$
,

so that

$$d\xi_t^2 = e^{-tA}C \circ dB_t$$

The solution is  $\xi_t^2(x) = x + \int_0^t e^{-sA} CdB_s$ . Therefore we have

$$\xi_{t} = \xi_{t}^{1} \circ \xi_{t}^{2} = e^{tA} (x + \int_{0}^{t} e^{-sA} C dB_{s}).$$

This is a well known formula for the solution of the linear system.

Example 2. (Bilinear system) Consider the equation

(3.12) 
$$d\xi_{t} = A_{0}\xi_{t}dt + \sum_{j=1}^{r} A_{j}\xi_{t} \circ dB_{t}^{j}$$

where  $A_j = (a_{k,l}^{(j)})$ , j = 0, ..., r are d×d-triangular matrices such that  $a_{k_l}^{(j)} = 0$  if k > l. Corresponding vector fields are

$$X_{j} = \sum_{k} \left( \sum_{k} a_{kk}^{(j)} \mathbf{x}_{k} \right) \frac{\partial}{\partial \mathbf{x}_{k}} , \quad j = 0, \dots, r.$$

It holds  $[X_i, X_j] = -\sum_k (\sum_k [A_i, A_j]_k \ell_k) \frac{\partial}{\partial x_k}$ , where  $[A_i, A_j] = A_i A_j - A_j A_i$ . Hence  $L(X_0, X_1, \ldots, X_r)$  is isomorphic to the matrix Lie algebra  $L(A_0, \ldots, A_r)$ . The derived ideal  $L_1$  of  $L(A_0, \ldots, A_r)$  consists of nilpotent matrices as is easily seen. Thus  $L(A_0, \ldots, A_r)$ , or equivalently,  $L(X_0, \ldots, X_r)$  is a solvable Lie algebra.

We shall decompose matrices  $A_j$  to sums of diagonal matrices  $D_j = (\delta_{k\ell} a_{k\ell}^{(j)})$  and nilpotent ones  $N_j = ((1 - \delta_{k\ell}) a_{k\ell}^{(j)})$ , where  $\delta_{k\ell}$  is Kronecker's delta. Consider

$$d\xi_{t}^{1} = \sum_{j=0}^{r} D_{j}\xi_{t}^{j} \cdot dB_{t}^{j}$$

where  $B_t^0 = t$ . The solution is then written as

(3.13) 
$$\xi_{t}^{1}(x) = e^{W_{t}}x, \quad W_{t} = \sum_{j=0}^{r} B_{t}^{j}D_{j}$$

It holds  $(\xi_t^1)_{\star}^{-1}N_j = e^{-W_t}N_j e^{W_t}$ . Consider

$$d\xi_{t}^{2} = \sum_{j=0}^{r} e^{-W_{t}} N_{j} e^{W_{t}} \xi_{t}^{2} \circ dB_{t}^{j}$$

Since  $e^{-W_t}N_je^{W_t}$ , j = 0, ..., r are nilpotent matrices, the solution is represented as  $\xi_t^2(x) = e^{V_t}x$ , where

$$(3.14) \qquad V_{t} = \sum_{j=0}^{t} \int_{0}^{t} e^{-W_{s}} N_{j} e^{W_{s}} e^{dB_{s}^{j}} \\ + \frac{1}{2} \sum_{i < j} \iint_{0 < s < u < t} [e^{-W_{s}} N_{i} e^{W_{s}}, e^{-W_{u}} N_{j} e^{W_{u}}] \circ (dB_{s}^{i} dB_{u}^{j} - dB_{s}^{j} dB_{u}^{i}) + \dots$$

The solution of (3.12) is then written as,

$$\xi_{t}(\mathbf{x}) = e^{\mathsf{W}_{t}} e^{\mathsf{V}_{t}} \mathbf{x}.$$

Department of Applied Science Faculty of Engineering Kyushu University Fukuoka, 812 Japan

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