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A proof via the Seiberg-Witten moduli space of Donaldson's theorem on smooth 4-manifolds with definite intersection forms

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Most of what follows was explained to me by D. Kotschick, with additional clarifications by T. Delzant, J.-C. Sikorav, and K. Wojciechowski. In [1], the existence of such a proof is attributed to P. Kronheimer and others. Compared to the original proof of Donaldson's theorem, the proof using the new moduli space is essentially trivial, which is what motivated a nonspecialist to present this exposition for nonspecialists in the field.

Theorem (S. Donaldson [9]). Let X be a smooth oriented 4-manifold. Suppose that the intersection form of X is negative definite. Then it is minus the identity.

We perform a surgery, without changing the intersection form in 2-dimensional homology modulo torsion, to reduce to the case of X^4 with $b_1 = 0$ (for details, see section 6).

Consider the Seiberg-Witten moduli space associated with a complex line bundle L satisfying $c_1(L) = w_2(TX) \pmod{2}$ (cf. [3], [6]). The Seiberg-Witten equations are

$$D_A \phi = 0, \ F_A^+ = i\sigma(\phi, \phi) \tag{1}$$

in unknowns (A, ϕ) . Here $\phi \in \Gamma(V_+)$ is a positive spinor, V_+ is a spin^c structure of determinant L, while D_A is the Dirac operator built from a connection A on L and the Levi-Civita connection on TX, and σ is a quadratic form. The self-dual part F_A^+ of the curvature of A is in $\Lambda^{2,+}(X)$. By Clifford multiplication, $\Lambda^{2,+}$ acts by endomorphisms of the bundle V_+ . At a point, such an endomorphism is given by a 2 by 2 matrix. To build such a matrix out of ϕ , think of ϕ as a column vector with two components. Then $\sigma(\phi,\phi)$ is like $(\phi\phi^*)_0$, the trace-free part of the 2 by 2 matrix obtained as the product of ϕ by its conjugate transpose.

The gauge group G = Map(X, U(1)) acts on solutions by $g.A = A - 2d \log g$, $g.\phi = g\phi$ (multiplication by complex scalars). The Seiberg-Witten moduli space is $M_L = \{\text{solutions}\}/G$. The action of G is free except at "reducible points" $\phi = 0$, i.e. $(A, \phi) = (A, 0)$. Choose a basepoint $x_0 \in X$. The based gauge group G_0 is the subgroup of G

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defined as the set of $g \in G$ such that $g(x_0) = 1 \in U(1)$ (gauge transformations fixing the fiber over the basepoint). We have an exact sequence $G_0 \to G \to U(1)$. The action of G_0 is free. The based moduli space M_0 is the quotient of the space of solutions of SW equations by G_0 .

To prove Donaldson's theorem, we argue by contradiction. Suppose the negative definite intersection form is not minus the identity. The argument is in 5 steps:

- 1. We specify an L defining a moduli space M_L of positive virtual dimension (using the fact that the intersection form is not standard).
- 2. The reducible point is unique (we use $b_1 = 0$ here).
- 3. We truncate around the reducible point to arrive at a contradiction with a standard result in surgery theory called Pontrjagin's theorem.
- 4. We perturb the second equation to ensure genericity, and verify the existence and uniqueness of the reducible point for the perturbed equations.
- 5. We perturb the first equation to ensure the smoothness of the based moduli space M_0 at the reducible point.

The arithmetic source of Donaldson's theorem is a remark of N. Elkies [1]:

Theorem. The identity is the only bilinear unimodular positive definite form (,) over \mathbb{Z} which does not admit a vector $w \in \mathbb{Z}^n$ satisfying the following 2 properties:

- (a) (w, w) < n;
- (b) for all $v \in \mathbb{Z}^n$ one has $(v, v + w) = 0 \pmod{2}$.

Such a w will be called a short characteristic vector. Now (w, w) is congruent to the signature modulo 8 (cf. [2]). Thus in the positive definite case, any non-standard form admits a w such that

$$(w, w) = n - 8k \text{ with } k \ge 1.$$

1. Choice of L defining a moduli space of positive dimension

The condition $c_1(L) = w_2(TX)$ of the existence of a spin^c structure means (by Wu's theorem) that $c_1(L)$ is a characteristic vector of the intersection form of X. We choose the short one, or more precisely any class whose reduction modulo torsion is the short vector. Then (2) gives

$$c_1(L)^2 = -|c_1(L)^2| = -b_2 + 8k, \ k \ge 1$$
 (3)

since the intersection form is negative definite. The virtual dimension of the SW moduli space is (cf. [6]) one quarter of

$$c_1(L)^2 - (2\chi + 3\sigma) = -b_2 + 8k - (4 - 4b_1 - b_2) = 8k - 4 + 4b_1 > 0 \text{ if } k \ge 1.$$
 (4)

2. Uniqueness of the reducible point

Reducible solutions (A,0) of equations (1) are characterized by $F_A^+ = 0$ i.e. $*F_A = -F_A$. Since the curvature form F_A is closed, applying d we see that F_A is harmonic. Existence

is immediate since every harmonic form is anti-self-dual by hypothesis (cf. section 4 below for more details). By Gauss-Bonnet the cohomology class $[F_A] = 2i\pi c_1(L)$ is prescribed by the choice of L, hence F_A is unique. Now suppose there are 2 connections A and A' with the same curvature form. Their difference is therefore a closed 1-form, hence exact $(b_1 = 0)$. Thus

$$A - A' = idf (5)$$

and the gauge transformation $g(x) = e^{if(x)/2}$ establishes the gauge equivalence of A and A'.

For example, the flat connection on a line bundle L whose $c_1(L)$ is torsion, is unique. The flat connections up to gauge equivalence correspond to representations of the fundamental group in U(1) = R/Z. If $b_1 = 0$, different representations of $\pi_1(X)$ define different line bundles, and hence the flat connection on L is unique. Thus for the Enriques surface, $\pi_1 = Z/2Z$, there are 2 representations in U(1) hence two flat connections, but the nontrivial one lives on the canonical bundle. The latter is nontrivial since the surface is not spin.

3. Truncating around the reducible point and contradiction with Pontrjagin's theorem

Consider again the moduli space M_L of dimension 2k-1 from formula (4). The compactness of M_L is established using a Weitzenbock formula and a C^0 estimate on the size of ϕ (cf. [6]). Assume that away from the reducible point, M_L is nonempty and smooth (see section 4).

Consider the based moduli space M_0 which is the quotient of the space of solutions of SW equations by G_0 , gauge transformations fixing the fiber over a basepoint. Note that dim $M_0 = 2k$. Let $p \in M_0$ be the preimage of the reducible point $(A,0) \in M$. Assume M_0 is smooth at p (see section 5). Choose a metric on M_0 invariant under the action of U(1). The induced linear action in the tangent space T_pM_0 at p is free, for otherwise some vector would have a nontrivial finite stabilizer. Via the exponential map this would produce a point in $M_0 \setminus \{p\}$ with a nontrivial stabilizer, contradicting the freeness of the action of all of G on irreducible solutions. Multiplication by $i \in U(1)$ thus defines a complex structure on T_pM_0 . The action of U(1) in the tangent space is scalar. Factoring by the U(1) action we obtain the standard quotient

$$S^{2k-1}/S^1 = CP^{k-1}. (6)$$

The exponential map at p is equivariant with respect to the U(1) action. Therefore the quotient of a small distance sphere centered at p by U(1) is still CP^{k-1} . Truncating out the neighborhood of the reducible point in M bounded by the CP^{k-1} , we obtain a smooth (2k-1)-dimensional manifold V whose boundary is CP^{k-1} . For example, if k=1 we obtain a compact 1-dimensional manifold whose boundary is a single point, which is a contradiction.

Consider the circle bundle over V defined by the projection $M_0 \to M$. Its restriction to CP^{k-1} is the Hopf fibration, of non-zero second Stiefel-Whitney class w_2 . Hence its number is nonzero: $w_2^{k-1}[CP^{k-1}] \neq 0$. But by Pontrjagin's theorem, all such numbers

have to vanish, as the fibration extends over all of V (cf. [4], p. 52; the argument given here for the tangent bundle works also for the Hopf fibration). Note that we have made no use of the orientability of V. The contradiction proves that a non-standard intersection form on a smooth 4-manifold could not have existed in the first place.

4. Existence and uniqueness of the reducible point for the perturbed equations

In [6] it is shown that the perturbed SW equations

$$D_A \phi = 0, \ F_A^+ - i\sigma(\phi, \phi) = e \tag{7}$$

for generic $e \in \Lambda^+$, have a smooth moduli space of the dimension predicted by the index theorem, using the surjectivity of the linearized operator and the existence of a suitable slice for the action of G. Here one needs the unique continuation property for spinors in the kernel of D_A (cf. [7]).

We now check that it always contains a reducible point, i.e. that the perturbed equation

$$F_A^+ = e$$
, where $e \in \Lambda^+$, (8)

has a solution. Then if M_0 is smooth at this point (see section 5), we can conclude that the (irreducible) moduli space is non-empty. Simultaneously we check that the reducible point is unique, so that step 2 above goes through when the equations are perturbed.

Consider the Hodge decomposition

$$e = df + *dg + h (9)$$

where h is a harmonic 2-form, and f and g are 1-forms unique up to adding exact 1-forms (since $b_1 = 0$). In our set-up a harmonic self-dual form is necessarily 0 hence h = 0 and the equation *e = e implies df = dg. Thus $e = (1 + *)df = d^+(f)$. Now pick any connection A_0 and find f such that

$$d^{+}(f) = e - F_{A_0}^{+} \tag{10}$$

from the Hodge decomposition of the right hand side. The connection $A_0 + f$ then solves the perturbed equation. The solution is unique up to adding an exact 1-form, i.e. up to gauge transformation.

5. Smoothness of the based moduli space at the reducible point

The linearisation of the equations at (A,0) is $D_A: \Gamma(V_+) \to \Gamma(V_-)$. This operator is not always surjective as it is possible to have 'harmonic' spinors of both chiralities. We perturb the first equation by adding a 1-form c to the operator:

$$(D_A + c)\phi = 0, \ F_A^+ - i\sigma(\phi, \phi) = e.$$
 (11)

The equations are still gauge-invariant. We need to verify that the moduli space is still compact. But the operator $D_A + c = D_{A'}$ with A' = A + 2c is still of the same type.

Applying the Weitzenbock formula to $D_{A'}$ as in [6], we obtain the necessary C^0 estimate for ϕ , containing an additional term $|2d^+c+e|$ besides the scalar curvature as follows. At a point where $|\phi|$ is a maximum, we have as in [6],

$$\begin{array}{ll} 0 & \leq & \Delta |\phi|^2 \leq -\frac{s}{2} |\phi|^2 + < F_{A'}^+ \phi, \phi > \\ & = & -\frac{s}{2} |\phi|^2 + < (F_A^+ + 2d^+c)\phi, \phi > \\ & = & -\frac{s}{2} |\phi|^2 + < i\sigma(\phi,\phi)\phi, \phi > + < (2d^+c + e)\phi, \phi > \\ & \leq & -\frac{s}{2} |\phi|^2 - \frac{1}{4} |\phi|^4 + |2d^+c + e| |\phi|^2 \end{array}.$$

To choose a suitable 1-form c, we suppose for simplicity that $\operatorname{ind}(D_A) = 0$ and the kernel is 1-dimensional. Let $\alpha \in Ker(D_A)$ and $\beta \in Im(D_A)^{\perp} \subset \Gamma(V_-)$. By the unique continuation property (cf. [7]), there exists a point x such that $\alpha(x) \neq 0$ and $\beta(x) \neq 0$. We choose c so that $c(x).\alpha(x) = \beta(x)$ for Clifford multiplication. Choose a function ψ with support near x, and let $\psi_{\epsilon} = \epsilon \psi$. Then $D_A + \psi_{\epsilon} c$ is invertible for small ϵ (cf. [8]).

6. Remarks

- 1. If one changes the orientation of X so that the intersection form is positive definite (while keeping F^+ in the SW equations), the calculation changes. There is no difficulty in producing a positive dimensional moduli space, but there is no reducible point since there are no anti-self-dual harmonic forms.
- 2. Surgery along a loop representing the free part of $H_1(X)$ does not change the intersection form in $H_2(X, Z)$ modulo torsion. Indeed, let S^1 be a loop in X representing a nonzero class in $H_1(X, R)$. Let X_- be a neighborhood of S^1 (homeomorphic to $S^1 \times B^3$) and X_+ its complement. The Mayer-Vietoris sequence gives

$$0 \to H_2(X_-) \oplus H_2(X_+) \to H_2(X) \to 0 \tag{12}$$

where the last arrow is zero by assumption on S^1 , and the first arrow replaces a homomorphism which is zero because $H_3(X) \to H_2(S^1 \times S^2)$ is surjective (it suffices to consider the "dual" surface transverse to S^1). After the surgery replacing X_- by $B^2 \times S^2$, we obtain the exact sequence

$$0 \to H_2(S^1 \times S^2) \to H_2(B^2 \times S^2) \oplus H_2(X_+) \to H_2(X') \to 0$$
 (13)

where X' is the result of applying the standard surgery on X along S^1 . Here the second arrow is injective because $H_2(S^1 \times S^2) = \mathbf{R}$ is isomorphic to $H_2(B^2 \times S^2)$.

In passing from 0 to $H_2(S^1 \times S^2)$ we have increased the rank by 1, and in passing from $H_2(X_-)$ to $H_2(B^2 \times S^2)$ we have increased the rank by 1. Since the Euler characteristic of the sequence is still 0, it follows that the rank of $H_2(X)$ is unchanged. Moreover, neither is the intersection form (in $H_2(X,Z)$ modulo torsion), since we can perform the surgery so as to avoid a family of 2-cycles representing the generators of $H_2(X,Z)$, and in particular leave their intersections unchanged.

3. Can we avoid the equations (11) and the proof of the smoothness of the based moduli space at the reducible point? At the reducible point, the linearisation of the perturbed SW equations (7) is $D_A(\phi)$. Perturbing the metric does not solve the problem

here, for it is not known whether D_A is surjective for a generic metric (cf. [5]). If D_A is not surjective, then the Kuranishi model (I am now using the notation from [6]) for the moduli space near the reducible point is $\psi^{-1}(0)/U(1)$ where

$$\psi: Ker(D_A) \to Coker(D_A) \tag{14}$$

and the U(1) action on the spinors is scalar.

Here the advantage of the Kuranishi model seems to be that we can still take a sphere of radius ϵ in $Ker(D_A)$, which will be transverse to $\psi^{-1}(0)$ for almost all ϵ . The quotient by U(1) will then give a smooth manifold (the analogue of the projective space in formula (6) of section 3). Consider the restriction of the U(1) bundle over the irreducible moduli space to this manifold. Does this bundle have nontrivial Stiefel-Whitney numbers?

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