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# MAREK LASSAK

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#### A GENERAL NOTION OF EXTREME SUBSET

#### Marek Lassak

The purpose of this paper is a general view on various definitions of extreme subsets and extreme elements as used in several branches of mathematics. Using terms of set operations, we present a universal scheme common for many such definitions and we discuss it under some weak assumptions.

Let X be an arbitrary set and let  $\mathscr{P}(X)$  denote the family of all subsets of X. Any function  $\Phi$  mapping a subfamily  $\mathscr{D}_{\Phi}$  of  $\mathscr{P}(X)$  into  $\mathscr{P}(X)$  is called a *set operation* in X or simply an *operation*.  $\mathscr{D}_{\Phi}$  is the domain of  $\Phi$ .

In [16] the following definition has been proposed

DEFINITION: If  $A \subset B \subset X$  and if for any  $K \in \mathcal{D}_{\Phi} \cap \mathcal{P}(B)$  and any  $x \in A \cap \Phi(K)$  there exists  $M \in \mathcal{D}_{\Phi} \cap \mathcal{P}(A \cap K)$  such that  $x \in \Phi(M)$ , then A is said to be a  $\Phi$ -extreme subset of B.

In the case  $A = \{a\}$  of the above definition, a will be called a  $\Phi$ -extreme element of B.

Examples of  $\Phi$ -extreme elements are extreme points of a set of a real linear space ( $\Phi$  maps any set  $\{x, y\}$  onto the segment joining x and y), isolated points of a set of any topological space ( $\Phi$  is the closure operation), terminal points of a set of a metric space ( $\Phi$  maps any set  $\{x, y\}$  onto the set of all points lying metrically between x and y). For examples of  $\Phi$ -extreme subsets and other examples of  $\Phi$ -extreme elements see the last paragraph of this paper.

## 1. Set operations

This paragraph is of preparatory nature.

An operation  $\Phi$  in X is called:

- full, if  $\mathcal{D}_{\Phi} = \mathcal{P}(X)$ ,
- *isotonic*, if for any G,  $H \in \mathcal{D}_{\Phi}$  from  $G \subseteq H$  it follows  $\Phi(G) \subseteq \Phi(H)$ ,
- enlarging, if  $G \subset \Phi(G)$  for any  $G \in \mathcal{D}_{\Phi}$ ,
- idempotent, if  $\Phi(\Phi(A)) = \Phi(A)$  for any  $A \in \mathcal{D}_{\Phi}$  such that  $\Phi(A) \in \mathcal{D}_{\Phi}$ ,
- a *closure* operation, if it is full, isotonic, enlarging, and idempotent,

- additive, if it is full and  $\Phi(G \cup H) = \Phi(G) \cup \Phi(H)$  for any  $G, H \in \mathcal{P}(X)$ ,
- cover finite, if  $\Phi(G) \subset \cup \{\Phi(F); F \in \mathcal{D}_{\Phi} \cap \mathcal{P}(G), |F| < \infty\}$  for any  $G \in \mathcal{D}_{\Phi}$ ,
- domain finite, if  $\Phi(G) = \bigcup \{\Phi(F); F \in D_{\Phi} \cap \mathcal{P}(G), |F| < \infty\}$  for any  $G \in \mathcal{D}_{\Phi}$ .

Full isotonic, full enlarging, full idempotent, full domain finite, and closure operations are considered by many authors (see [1],[6],[10],[11], [20],[21] for instance).

The smallest number  $k \ge 0$  such that

$$\Phi(G) \subset \bigcup \{\Phi(F); F \in \mathcal{D}_{\Phi} \cap \mathcal{P}(G), |F| \leqslant k \} \quad \text{for any } G \in \mathcal{D}_{\Phi}$$

is called Caratheodory's number of  $\Phi$  and it is denoted by  $c(\Phi)$ . If such k does not exist, then we put  $c(\Phi) = \infty$ .

Obviously, if  $\Phi$  is isotonic, then the inclusion in the above definition can be replaced by the equality. Note that any operation with finite Caratheodory's number is cover finite.

If  $\Phi(G) = \Phi(H)$ , then G and H are called  $\Phi$ -equivalent. If additionally  $G \subset H$ , then we call G a  $\Phi$ -equivalent subset of H.

We call  $K \in \mathcal{D}_{\Phi}$  a  $\Phi$ -stable set if  $\Phi(K) = K$ .

Remeber that a closed under arbitrary intersections family  $\mathscr{C} \subset \mathscr{P}(X)$  is called a *closure system* over X. If moreover  $\phi \in \mathscr{C}$ , then  $(X, \mathscr{C})$  is usually called a *convexity structure*. Let the symbol  $h_{\mathscr{C}}(A)$  denote the intersection of all sets of  $\mathscr{C}$  which contain a given set  $A \in \mathscr{P}(X)$ .

It is well known (see e.g. [6], p. 43) that there exists one-to-one correspondence between closure systems over X and closure operations in X: ( $\rightarrow$ ) if  $\mathscr C$  is a closure system over X, then  $h_{\mathscr C}$  is a closure operation, then the family  $\mathscr C_{\Phi}$  of  $\Phi$ -stable sets is a closure system over X and  $h_{\mathscr C_{\Phi}} = \Phi$ .

If  $\Phi$  is a closure operation, then  $\Phi(K)$  is called the *closure* of K. For a given operation  $\Phi$  in X we define an auxiliary operation

$$\Phi^{\,\cup}(G) = \,\cup\,\big\{\,\Phi(\,D\,)\,;\, D \in \mathcal{D}_\Phi \cap \mathcal{P}(G)\big\}\,.$$

If  $\Phi$  is full, then let (comp. [11], p. 311)

$$\Phi^{\omega}(G) = \bigcup_{n=0}^{\infty} \Phi^{n}(G),$$

where  $\Phi^0(G) = G$ ,  $\Phi^{i+1}(G) = \Phi(\Phi^i(G))$ , i = 0, 1, ...

Obviously, both of the operations  $\Phi^{\cup}$ ,  $\Phi^{\omega}$  are full. Moreover,  $\Phi^{\cup}$  is isotonic. If  $\Phi$  is isotonic, then  $\Phi^{\cup}(G) = \Phi(G)$  for any  $G \in \mathscr{D}_{\Phi}$ . If  $\Phi$  is full and isotonic, then  $\Phi^{\cup} = \Phi$ .

## 2. General properties of $\Phi$ -extreme subsets

Observe that the definition of  $\Phi$ -extreme subset A of B can be shortly expressed by the formula

$$A \cap \Phi(K) \subset \Phi^{\cup}(A \cap K)$$
 for any  $K \in \mathcal{D}_{\Phi} \cap \mathcal{P}(B)$ . (1)

The following five statements of Theorem 1 generalize well known properties of the classic extreme subsets in real linear spaces.

## THEOREM 1: For each operation $\Phi$ in X we have:

- (a) Any finite intersection of  $\Phi$ -extreme subsets of a set B is a  $\Phi$ -extreme subset of B. This is also true for arbitrary intersections provided  $\Phi$  is cover finite.
- (b) Any union of  $\Phi$ -extreme subsets of a set B is also a  $\Phi$ -extreme subset of B.
- (c) If B is a  $\Phi$ -extreme subset of C and A is a  $\Phi$ -extreme subset of B, then A is a  $\Phi$ -extreme subset of C.
- (d) If  $A \subseteq B \subseteq C$  and if A is a  $\Phi$ -extreme subset of C, then A is a  $\Phi$ -extreme subset of B.
- (e) Sets B,  $\phi$  and (if  $\phi \in D_{\Phi}$ ) all subsets of  $B \cap \Phi(\phi)$  are  $\Phi$ -extreme subsets of B.

PROOF: We prove only the first part. The other ones are left to the reader. Let  $A_1$ ,  $A_2$  be  $\Phi$ -extreme subsets of B. Suppose,  $x \in (A_1 \cap A_2) \cap \Phi(K)$ , where  $K \in \mathcal{D}_{\Phi} \cap \mathcal{P}(B)$ . Since  $A_1$  is a  $\Phi$ -extreme subset of B and  $x \in A_1 \cap \Phi(K)$ , there exists  $M_1 \in \mathcal{D}_{\Phi} \cap \mathcal{P}(A_1 \cap K)$  such that  $x \in \Phi(M_1)$ . Similarly, from  $x \in A_2 \cap \Phi(M_1)$  and  $M_1 \in \mathcal{D}_{\Phi} \cap \mathcal{P}(B)$  we get that  $x \in \Phi(M)$  for some  $M \in \mathcal{D}_{\Phi} \cap \mathcal{P}(A_2 \cap M_1)$ . Obviously,  $M \in \mathcal{D}_{\Phi} \cap \mathcal{P}(A_1 \cap A_2 \cap K)$ . Thus  $A_1 \cap A_2$  is a  $\Phi$ -extreme subset of B. Consequently, any finite intersection of  $\Phi$ -extreme subsets of B is also  $\Phi$ -extreme.

Now, let  $\Phi$  be cover finite and  $A_{\lambda}$ ,  $\lambda \in \Lambda$ , be  $\Phi$ -extreme subsets of B. Put  $A = \cap \{A_{\lambda}, \lambda \in \Lambda\}$ . Suppose,  $K \in \mathcal{D}_{\Phi} \cap \mathcal{P}(B)$  and  $x \in A \cap \Phi(K)$ . Since  $\Phi$  is cover finite,  $x \in \Phi(M)$  for a finite  $M \in \mathcal{D}_{\Phi} \cap \mathcal{P}(K)$ . Without loss of generality, we can assume that M is minimum (in respect to inclusion) set of  $\mathcal{D}_{\Phi} \cap \mathcal{P}(K)$  for which  $x \in \Phi(M)$ . Moreover,  $x \in A_{\lambda}$  and  $A_{\lambda}$  is a  $\Phi$ -extreme subset of B for any  $\lambda \in \Lambda$ . Thus for any  $\lambda \in \Lambda$  there exists  $M_{\lambda} \in \mathcal{D}_{\Phi} \cap \mathcal{P}(A_{\lambda} \cap M) \subset \mathcal{D}_{\Phi} \cap \mathcal{P}(K)$  such that  $x \in \Phi(M_{\lambda})$ . Since M is minimal and  $M_{\lambda} \subset M$ , we have  $M_{\lambda} = M$  for all  $\lambda \in \Lambda$ . From  $M_{\lambda} \subset A_{\lambda}$ ,  $\lambda \in \Lambda$ , we get  $M \subset A$ . Hence  $M \in \mathcal{D}_{\Phi} \cap \mathcal{P}(A \cap K)$ . Thus A is a  $\Phi$ -extreme subset of B.

Note that in general case the intersection of infinitely many  $\Phi$ -extreme subsets may fail to be  $\Phi$ -extreme (comp. e.g. Example 4).

**PROPOSITION 1:** Let  $\Phi$  be a full isotonic operation [respectively: a cover

finite operation, an operation with finite Caratheodory's number, an additive operation]. A subset A of B is  $\Phi$ -extreme if and only if the below condition (2) [respectively: (3), (4), (5)] holds:

$$A \cap \Phi(K) \subset \Phi(A \cap K)$$
 for any  $K \in \mathcal{P}(B)$ , (2)

$$A \cap \Phi(K) \subset \Phi^{\cup}(A \cap K)$$
 for any finite  $K \in \mathcal{D}_{\Phi} \cap \mathcal{P}(B)$ , (3)

$$A \cap \Phi(K) \subset \Phi^{\cup}(A \cap K)$$
 for any  $K \in \mathcal{D}_{\Phi} \cap \mathcal{P}(B)$ 

with 
$$|K| \le c(\Phi)$$
, (4)

$$A \cap \Phi(B \setminus A) \subset \Phi(\phi). \tag{5}$$

PROOF: The first three statements result easily from (1), because  $\Phi^{\cup} = \Phi$  for any full isotonic operation, and from the definitions of cover finite operation and Caratheodory's number.

We prove the last part. As additive, the operation  $\Phi$  is isotonic and full. So it is sufficient to show that (2) and (5) are equivalent.

Immediately, (5) results from (2) putting  $K = B \setminus A$ .

Assume, (5) holds. Therefore  $A \cap \Phi(B \setminus A) \subset A \cap \Phi(\phi)$ . Let K be a subset of B. Since  $\Phi$  is isotonic,  $\Phi(K \setminus A) \subset \Phi(B \setminus A)$  and  $\Phi(\phi) \subset \Phi(K \cap A)$ . Moreover,  $\Phi$  is additive. Thus we get that

$$A \cap \Phi(K) = A \cap \Phi[(K \cap A) \cup (K \setminus A)]$$

$$= A \cap [\Phi(K \cap A) \cup \Phi(K \setminus A)]$$

$$= [A \cap \Phi(K \cap A)] \cup [A \cap \Phi(K \setminus A)]$$

$$\subset [A \cap \Phi(K \cap A)] \cup [A \cap \Phi(B \setminus A)]$$

$$\subset [A \cap \Phi(K \cap A)] \cup [A \cap \Phi(\phi)]$$

$$= A \cap \Phi(K \cap A) \subset \Phi(K \cap A),$$

which ends the proof.

Condition (2) is very useful and it can be applied to full isotonic operations, particularly to the operation  $\Phi^{\cup}$  for any  $\Phi$ . This is why we formulate the following proposition whose proof is left to the reader.

PROPOSITION 2: A is a  $\Phi$ -extreme subset of B if and only if A is a  $\Phi$ -extreme subset of B.

## 3. $\Phi$ -extreme and $\Phi^{\omega}$ -extreme subsets

Theorem 2: Any  $\Phi$ -extreme subset of B is also  $\Phi^{\omega}$ -extreme provided  $\Phi$  is full domain finite and B is  $\Phi^{\omega}$ -stable (particularly:  $\Phi$ -stable).

PROOF: Let A be a  $\Phi$ -extreme subset of B. Since  $\Phi$  is full and (as domain finite) isotonic,  $\Phi^{\omega}$  is also full and isotonic. By the first part of Proposition 1, to verify that A is a  $\Phi^{\omega}$ -extreme subset of B it is sufficient to show the inclusion  $A \cap \Phi^{\omega}(H) \subset \Phi^{\omega}(A \cap H)$  for any  $H \in \mathcal{P}(B)$ .

Let  $x \in A \cap \Phi^{\omega}(H)$ . Let m be the smallest number such that  $x \in \Phi^m(H)$ . Recurrently, define finite sets  $H_m, \ldots, H_0$  as follows. Put  $H_m = \{x\}$ . Obviously,  $H_m \subset \Phi^m(H)$ . Suppose, a finite subset  $H_n$  of  $\Phi^n(H)$  is defined, where  $m \ge n > 0$ . Since  $\Phi$  is full domain finite, there exists a finite set  $G_{n-1} \subset \Phi^{n-1}(H)$  such that  $H_n \subset \Phi(G_{n-1})$ . Consequently, there exists a finite minimal (in respect to inclusion) subset  $H_{n-1}$  of  $\Phi^{n-1}(H)$  such that  $H_n \subset \Phi(H_{n-1})$ . So  $H_m, \ldots, H_0$  are defined. Of course,  $H_k \subset \Phi(H_{k-1})$  for  $k = 1, \ldots, n$  and  $H_k \subset \Phi^k(H)$  for  $k = 0, \ldots, m$ .

Since  $\Phi$  is isotonic, any  $\Phi^k$  is also isotonic. Therefore

$$H_k \subset \Phi^k(H) \subset \Phi^k(B) \subset \Phi^\omega(B) = B$$
 for  $k = 0, ..., m$ .

Obviously,  $H_m \subset A$ . Assume  $H_n \subset A$ , where  $m \ge n > 0$ . Putting  $K = H_{n-1}$  in (2) we obtain  $A \cap \Phi(H_{n-1}) \subset \Phi(A \cap H_{n-1})$ . Since  $H_n \subset A$  and  $H_n \subset \Phi(H_{n-1})$ , we have  $H_n \subset \Phi(A \cap H_{n-1})$ . Moreover,  $H_{n-1}$  is a minimal subset of  $\Phi^{n-1}(H)$  such that  $H_n \subset \Phi(H_{n-1})$ . Therefore  $H_{n-1} \subset A \cap H_{n-1}$  and consequently,  $H_{n-1} \subset A$ . Thus  $H_m, \ldots, H_0$  are subsets of A. Particularly,  $H_0 \subset A$ .

From  $H_k \subset \Phi(H_{k-1})$ , k = 1, ..., m, from  $H_0 \subset A$  and  $H_0 \subset \Phi^0(H) = H$ , thanks the isotonicity of  $\Phi'$ , we get

$$\{x\} = H_m \subset \Phi(H_{m-1}) \subset \Phi^2(H_{m-2}) \subset \dots \subset \Phi^m(H_0)$$
$$= \Phi^m(H_0 \cap A) \subset \Phi^m(H \cap A) \subset \Phi^\omega(H \cap A).$$

PROPOSITION 3: Any  $\Phi^{\omega}$ -extreme subset of B is also  $\Phi$ -extreme provided:  $\Phi$  is full,  $c(\Phi) < \infty$ , and  $\Phi(F)$  is  $\Phi$ -stable for  $|F| \le c(\Phi)$ .

PROOF: Let A be a  $\Phi^{\omega}$ -extreme subset of B. By (1) we obtain that

$$A \cap \Phi^{\omega}(K) \subset (\Phi^{\omega})^{\cup} (A \cap K)$$
 for any  $K \in \mathcal{P}(B)$ .

If  $|K| \leq c(\Phi)$ , then  $\Phi^{\omega}(K) = \Phi(K)$ . Moreover,  $\Phi^{\omega}(M) = \Phi(M)$  for  $M \in \mathcal{P}(A \cap K)$ . Consequently,  $(\Phi^{\omega})^{\cup}(A \cap K) = \Phi^{\cup}(A \cap K)$ . Hence (4) is satisfied which, in virtue of Proposition 1, ends the proof.

#### 4. Φ-extreme elements

If  $\phi \in \mathscr{D}_{\Phi}$ , then any element of  $\Phi(\phi)$  is a  $\Phi$ -extreme element of each set to which it belongs (comp. (e) in Theorem 1). Such elements are called *trivially*  $\Phi$ -extreme. For an arbitrary operation  $\Phi$  in X, we denote by  $E_{\Phi}(B)$  the set of all *non-trivially*  $\Phi$ -extreme elements, i.e. of all  $\Phi$ -extreme elements of B which do not belong to  $\Phi(\phi)$ .

PROPOSITION 4: If  $a \in E_{\Phi}(B)$ , then

$$a \in \Phi(K) \Rightarrow a \in K \text{ for any } K \in \mathcal{D}_{\Phi} \cap P(B).$$
 (6)

For a full enlarging operation  $\Phi$ , the conditions  $a \in E_{\Phi}(B)$  and (6) are equivalent.

Let us observe (for use in Example 2) that if  $\Phi$  is cover finite, than (6) is equivalent to the condition

$$a \in \Phi(K) \Rightarrow a \in K \text{ for any finite } K \in \mathcal{D}_{\Phi} \cap \mathcal{P}(B).$$
 (7)

**PROPOSITION** 5: If  $\Phi$  is a full operation and  $a \in E_{\Phi}(B)$ , then

$$a \in B \setminus \Phi(B \setminus \{a\}). \tag{8}$$

For full enlarging isotonic operations, the conditions  $a \in E_{\Phi}(B)$  and (8) are equivalent.

**PROPOSITION** 6: If  $\Phi$  is full and enlarging, then  $a \in E_{\Phi}(B)$  implies

$$\Phi(B \setminus \{a\}) \neq \Phi(B). \tag{9}$$

If  $\Phi$  is a closure operation,  $a \in E_{\Phi}(B)$  is equivalent to (9).

PROPOSITION 7: Let  $\Phi$  be a full, enlarging, isotonic operation and let a belong to a  $\Phi$ -stable set B. Then  $a \in E_{\Phi}(B)$  if and only if

$$B\setminus\{a\}$$
 is  $\Phi$ -stable. (10)

We omit the proofs of Propositions 4–7 as rather tedious. Simply examples show that all assumptions about  $\Phi$  are necessary there. In the case of closure operations, an additional characterization of non-trivially  $\Phi$ -extreme elements is given in the first part of Proposition 9.

With the help of Proposition 4 one can easily obtain the following

PROPOSITION 8: Let  $\Phi$  be an enlarging operation and  $B \in \mathcal{D}_{\Phi}$ . Then  $E_{\Phi}(B)$  is contained in each  $\Phi$ -equivalent subset of B. Moreover, if  $E_{\Phi}(B)$ 

is a  $\Phi$ -equivalent subset of B, then it is the smallest  $\Phi$ -equivalent subset of B.

**PROPOSITION 9:** For any closure operation  $\Phi$  and any  $B \in \mathcal{P}(X)$  we have:

- (a)  $E_{\Phi}(B)$  coincides with the intersection of all  $\Phi$ -equivalent subsets of B.
- (b) If there exists the smallest  $\Phi$ -equivalent subset of B, then it is equal to  $E_{\Phi}(B)$ .
- (c)  $\Phi(E_{\Phi}(B)) = \Phi(B)$  if and only if the family of all  $\Phi$ -equivalent subsets of B is a closure system over B.
- (d)  $E_{\Phi}(\Phi(B)) \subset E_{\Phi}(B)$ .

PROOF: (a) Let  $a \notin E_{\Phi}(B)$ . In virtue of Proposition 8 it is sufficient to show that a does not belong to some  $\Phi$ -equivalent subset of B. The searched subset is  $B \setminus \{a\}$  because (9) does not hold.

- (b) If there exists the smallest  $\Phi$ -equivalent subset of B, then it coincides with the intersection of all  $\Phi$ -equivalent subsets of B. Consequently, it is equal to  $E_{\Phi}(B)$  as we have shown in (a).
  - (c) This statement easy results from (b) and from Proposition 8.
- (d) Let  $a \in E_{\Phi}(\Phi(B))$ . By (a) we obtain that a belongs to any  $\Phi$ -equivalent subset  $\Phi(B)$ . Particularly,  $a \in B$ . Since a is a  $\Phi$ -extreme element of  $\Phi(B)$  and  $B \subset \Phi(B)$ , we infer from part (d) of Theorem 1 that a is also a  $\Phi$ -extreme element of B. From  $a \in E_{\Phi}(\Phi(B))$  it follows  $a \notin \Phi(\Phi)$ . Consequently,  $a \in E_{\Phi}(B)$ .

For B being  $\Phi$ -stable, the reader can observe a connection of statement (a) of Proposition 9 with the operation  $j_h$  considered in [24] and consequently, a connection of Examples 1 and 4 presented at the end of this paper with Corollaries 2.3 and 2.4 of [24].

PROPOSITION 10: For any closure operation  $\Phi$  and any set  $B \in \mathcal{P}(X)$  the following conditions are equivalent:

$$E(\Phi(B)) = E_{\Phi}(B), \tag{11}$$

for any 
$$a \in B \setminus \Phi(B \setminus \{a\})$$
 the set  $\Phi(B) \setminus \{a\}$  is  $\Phi$ -stable, (12)

for any  $a \in B \setminus \Phi(B \setminus \{a\})$  there exists a  $\Phi$ -stable set S

such that 
$$S \cup \{a\}$$
 is  $\Phi$ -stable,  $a \notin S$  and  $\Phi(B \setminus \{a\}) \subset S$ . (13)

PROOF: (11)  $\Rightarrow$  (12). Let  $a \in B \setminus \Phi(B \setminus \{a\})$  in (12). From Proposition 5 we obtain that  $a \in E_{\Phi}(B) = E_{\Phi}(\Phi(B))$ . Since  $\Phi(B)$  is  $\Phi$ -stable, by Proposition 7 we get that the set  $\Phi(B) \setminus \{a\}$  is  $\Phi$ -stable.

 $(12) \Rightarrow (11)$ . Let  $a \in E_{\Phi}(B)$ . By Proposition 5 and by our assumption (12), the set  $\Phi(B) \setminus \{a\}$  is  $\Phi$ -stable. From Proposition 7 we infer that  $a \in E_{\Phi}(\Phi(B))$ . Thus  $E_{\Phi}(B) \subset E_{\Phi}(\Phi(B))$ . The inverse inclusion has been shown in Proposition 9.

- $(12) \Rightarrow (13)$ . Put  $S = \Phi(B) \setminus \{a\}$  in (12). Since  $\Phi$  is enlarging,  $a \in \Phi(B)$ . Consequently,  $S \cup \{a\} = \Phi(B)$ . By the idempotence of  $\Phi$ , the set  $S \cup \{a\}$  is  $\Phi$ -stable. From  $a \notin \Phi(B \setminus \{a\})$  and from the isotonicity of  $\Phi$  we get that  $\Phi(B \setminus \{a\}) \subset \Phi(B) \setminus \{a\} = S$ .
- $(13) \Rightarrow (12)$ . Thanks to the correspondence between closure operations and closure systems, it is sufficient to show that  $\Phi(B) \setminus \{a\}$  is an intersection of  $\Phi$ -stable sets, i.e. that for any  $c \notin \Phi(B) \setminus \{a\}$  there exists a  $\Phi$ -stable set  $K_c$  such that  $c \notin K_c$  and  $\Phi(B) \setminus \{a\} \subset K_c$ . Obviously, if our c is different from a, then one can put  $K_c = \Phi(B)$ . In the case c = a put  $K_a = S$ . Since  $S \cup \{a\}$  is  $\Phi$ -stable and since  $\Phi$  is enlarging and isotonic, from  $\Phi(B \setminus \{a\}) \subset S$  we infer that

$$\Phi(B) \subset \Phi[\Phi(B \setminus \{a\}) \cup \{a\}] \subset S \cup \{a\}.$$

Consequently,  $\Phi(B) \setminus \{a\} \subset S = K_a$ . Of course,  $a \notin K_a$ . The proof is complete.

Note that any  $\Phi$ -stable set C such that  $a \notin C$  can be presented in the form  $\Phi(B \setminus \{a\})$ , where  $B = C \cup \{a\}$ . Consequently, using standard techniques, from Proposition 10 we obtain

Theorem 3: If  $\Phi$  is a closure operation, then the following conditions are equivalent:

any set and its closure have identical non-trivially 
$$\Phi$$
-extreme elements, (14)

for any 
$$\Phi$$
-stable set  $C$  and  $a \notin C$  the set  $\Phi(C \cup \{a\}) \setminus \{a\}$  is  $\Phi$ -stable, (15)

for any 
$$\Phi$$
-stable set  $C$  and  $a \notin C$  there exists a  $\Phi$ -stable set  $S$  such that  $S \cup \{a\}$  is  $\Phi$ -stable,  $a \notin S$  and  $C \subseteq S$ , (16)

 $\Phi$ -equivalent sets have identical non-trivially  $\Phi$ -extreme elements.(17)

From Theorem 1.4 of [6], p. 46, and from the correspondence between closure operations and closure systems it results that if  $\Phi$  is a domain finite closure operation, then any  $\Phi$ -stable set not containing an element  $x \in X$  can be enlarged to a maximal  $\Phi$ -stable set not containing x. Consequently, the equivalence of (14) and (16) implies

THEOREM 4: Let  $\Phi$  be a domain finite closure operation. Any set and its closure have identical non-trivially  $\Phi$ -extreme elements if and only if for any

 $x \in X$  and any maximal  $\Phi$ -stable set C not containing x, the set  $C \cup \{x\}$  is  $\Phi$ -stable.

## 5. Some examples

Usually,  $\Phi$ -extreme subsets and elements are considered for  $\Phi$  defined on pairs of elements of X. This way one defines the notions of extreme subset and extreme point of a set of a real linear space, extreme support hyperplanes (comp. [3], p. 15), terminal points ([2], p. 53) and subsets [16] of a set of a metric space, extreme points of a subset of a partially ordered set ([7], comp. also Example 3 below), extreme points and subsets in various axiomatic convexity spaces (see e.g. [5]). Also extreme rays of a cone can be defined on this way. The equivalence of some formulas used in such definitions is presented in Proposition 11, where instead  $\Phi(\{x, y\})$  we simply write  $\Phi\{x, y\}$ .

PROPOSITION 11: Let  $\Phi$  and  $\overline{\Phi}$  be two operations defined on all pairs of (not necessarily different) elements of X such that  $x, y \notin \Phi\{x, y\}$ ,  $\Phi\{x, x\} = \phi$  and  $\overline{\Phi}\{x, y\} = \{x, y\} \cup \Phi\{x, y\}$  for any  $x, y \in X$ . For any subset A of B the following conditions are equivalent:

- (a) A is a  $\Phi$ -extreme subset of B,
- (b) A is a  $\overline{\Phi}$ -extreme subset of B,
- (c) for every  $x, y \in B$  from  $A \cap \Phi\{x, y\} \neq \phi$  it results  $x, y \in A$ ,
- (d) for every  $x, y \in B$  and  $a \in A \cap \overline{\Phi}\{x, y\}$  it is x = a, or y = a, or  $x, y \in A$ ,
- (e)  $A \cap \Phi\{x, y\} = \phi$  for each  $x \in B \setminus A$  and each  $y \in B$ ,
- (f)  $A \cap \overline{\Phi}\{x, y\} \subset \{y\}$  for each  $x \in B \setminus A$  and each  $y \in B$ .

EXAMPLE 1: Let L be a real liner space and let segm $\{x, y\} = \{(1 - \alpha)x\}$  $+\alpha y$ ;  $0 < \alpha < 1$ . Obviously, the classical notion of extreme subset of a set is just the notion of segm-extreme subset. Consider other kinds of extremeness in L. Let conv denote the operation of convex hull. From the equality  $(\overline{\text{segm}}^{\cup})^{\omega} = \text{conv}$  (comp. [4]) and by Propositions 2, 3, 5 and Theorems 2, 4 (as it results from Theorem 3.1 of [11], for any maximal convex set C not containing a gien point a, the set  $C \cup \{a\}$  is also convex) we conclude that conv-extreme subsets of any convex set coincide with extreme subsets and that conv-extreme points of any set B are identical with extreme points of conv B. A generalization of conv-extremeness is presented in Example 2. A subset A of a convex set B is called a *semi-extreme subset* of B if  $B \setminus A$  is convex (comp. [12], p. 32). As in [22], pp. 186–187, this notion can be extended to arbitrary (i.e. not necessary convex) set B: if  $A \subset B$  and  $A \cap \text{conv}(B \setminus A) = \phi$ , then we call A a semi-extreme subset of B. Simply examples show that the intersection of two semi-extreme subsets may not be a semi-extreme subset. From (a) in Theorem 1 we infer that the notion of semi-extreme subset is not a case of our scheme of  $\Phi$ -extremeness. One can extend the definition of semi-extreme subsets for operations as follows. If  $A \subset B \subset X$  and if for any  $K \in \mathcal{D}_{\Phi} \cap \mathcal{P}(B \setminus A)$  and any  $x \in A \cap \Phi(K)$  there exists  $M \in \mathcal{D}_{\Phi} \cap \mathcal{P}(A \cap K)$  such that  $x \in \Phi(M)$ , then A is called a  $\Phi$ -semi-extreme subset of B. The reader can easily check up that for  $\Phi$ -semi-extreme subsets there hold analogical properties as (b), (d) and (e) of Theorem 1 and that conv-semi-extreme subsets are just semi-extreme ones. Also relative extreme points [15] and relative extreme subsets [17] are studied. Remember that a subset A of B is said to be an extreme subset of B relative to C if for any  $x \in B$ ,  $y \in C$ , from  $A \cap \text{segm}\{x, y\} \neq \phi$  it follows  $x \in A$ . This is a special case of our notion of  $\Phi$ -extreme subset, where  $\mathcal{D}_{\Phi}$  consists of all one-point sets and  $\Phi(\{x\}) = \bigcup_{y \in C} \text{segm}\{x, y\}$ .

Example 2: Consider two kinds of extremeness in a convexity structure  $(X, \mathcal{C})$ . As in many papers concerning convexity structures, the hull operation (i.e. the closure operation)  $h_{\mathcal{C}}$  generated by  $\mathcal{C}$  will be simply denoted by the same symbol  $\mathcal{C}$ . In [22], pp. 186–187, there was introduced a notion of extreme subset for convexity structures for which, as for a special case of the definition of  $\Phi$ -semi-extreme subset presented in Example 1, we use the term  $\mathcal{C}$ -semi-extreme subset or semi-extreme subset for short. Let  $A \subset B \subset X$ . We call A a  $\mathcal{C}$ -semi-extreme subset of B if

$$A\cap\mathscr{C}(B\backslash A)=\phi.$$

Simultaneously, it is natural to consider also  $\mathscr{C}$ -extreme (shortly: extreme) subsets. By Proposition 1 it is clear that (2) may be used as a definition: if

$$A \cap \mathscr{C}(K) \subset \mathscr{C}(A \cap K)$$
 for any  $K \subset B$ ,

then A is called a *Gextreme subset* of B. In the case  $A = \{a\}$ , a is called a *Gextreme point* of B. In two special cases, the notion of *Gextreme point*  $a \in B$  has been introduced earlier: using (7) for *Gextreme being domain finite* ([8], p. 151) and with the help of (10) when  $B \in G$  (see [13], p. 127 and [14], p. 119). From Proposition 5 we obtain a simply characterization of *Gextremeness* of a point a of a, namely

$$a \notin \mathcal{C}(B \setminus \{a\}).$$

It enables us to observe a surprising connection of the notions of  $\mathscr{C}$ -extreme point and  $\mathscr{C}$ -independent set ([21], p. 38, [18], p. 174, [9], p. 27, [13], p. 120) which can be simply expressed by defining a  $\mathscr{C}$ -independent set as one with all points  $\mathscr{C}$ -extreme. Other properties of  $\mathscr{C}$ -extreme subsets and points are given in Theorems 1, 3, 4 and Propositions 4, 6, 8, 9, 10. Moreover, from (3), (4) and from the equality  $\mathscr{C} \cup \mathscr{C}$  they result

characterizations of  $\mathscr{C}$ -extreme subsets for  $\mathscr{C}$  being domain finite and for  $\mathscr{C}$  with finite Caratheodory's number. Obviously, any  $\mathscr{C}$ -extreme subset of B is a  $\mathscr{C}$ -semi-extreme one of B. Moreover,  $\mathscr{C}$ -semi-extreme and  $\mathscr{C}$ -extreme points of arbitrary set coincide.

EXAMPLE 3: Let P be a set partially ordered by a relation  $\leq$ . For any x,  $z \in P$  put  $\overline{\Sigma}\{x, z\} = \{y; x \leqslant y \leqslant z \text{ or } z \leqslant y \leqslant x\}$  and  $\Sigma\{x, z\} =$  $\overline{\Sigma}\{x,z\}\setminus\{x,z\}$ . A set  $C\subset P$  is called order convex [7] if  $\overline{\Sigma}\{x,z\}\subset C$ for any  $x, z \in C$ . Since the family of order convex subsets is a closure system over P, there is defined the corresponding closure (hull) operation  $\Omega$ . By order extreme subsets we understand  $\overline{\Sigma}$ -extreme subsets, i.e.,  $\Sigma$ -extreme subsets (see Proposition 11). Order extreme elements have been introduced and discussed in [7]. From the equality  $\overline{\Sigma}^{\cup} = \Omega$  (see [7]) and from Proposition 2 and Theorem 4 we obtain that order extreme and  $\Omega$ -extreme subsets of arbitrary set coincide and that any set and its order convex hull have identical order extreme elements. As an example of order extreme elements, one can take  $\leq a$ -maximal elements (see [23], pp. 18 and 30) in a semi-regular topological convexity structure and, more general, in any convexity structure such that for any a, b, c from  $c \in \mathcal{C}\{a, b\}$  and  $b \in \mathcal{C}\{a, c\}$  it results b = c. Similarly as in Examples 1 and 2 we can consider relative order extreme subsets (i.e. relative  $\Sigma$ -extreme subsets) and  $\Omega$ -semi-extreme subsets. It is easy to test that order extreme subsets relative a set and relative its order convex hull are identical and that A is an  $\Omega$ -semi-extreme subset of B if and only if A is an order extreme subset of B relative to  $B \setminus A$ .

EXAMPLE 4: Denote by cl the closure operation in a topological space T. From the last part of Proposition 1 we obtain that a subset A of B is cl-extreme if and only if  $A \cap cl(B \setminus A) = \phi$ . Particularly, cl-extreme points of B coincide with isolated points of B. Note that cl-extreme subsets of T are just open sets.

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Instytut Matematyki i Fizyki ATR ul. Kaliskiego 7 85-790 Bydgoszcz Poland