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ALGEBRAIC CHARACTERIZATIONS OF THE ALGEBRA OF FUNCTIONS AND OF THE LIE ALGEBRA OF VECTOR FIELDS OF A MANIFOLD

M. De Wilde and P. Lecomte

1. Introduction

Let M be a smooth, connected, Hausdorff and second countable manifold. Denote by $\mathcal{H}(M)$ the Lie algebra of smooth vector fields of M and by $C_{\infty}(M)$ the space of smooth functions on M. Recall that the Lie derivative $\mathcal{L}_X(X \in \mathcal{H}(M))$ is defined on $\otimes^p C_{\infty}(M)$ by

$$\mathscr{L}_X(f_1 \otimes \cdots \otimes f_p) = \sum_{i=1}^p f_i \otimes \cdots \otimes (\mathscr{L}_X f_j) \otimes \cdots \otimes f_p.$$

If $L: \otimes^p C_\infty(M) \to C_\infty(M)$ is a p-linear map, the adjoint action of \mathcal{L}_X on L, $ad(\mathcal{L}_X)L$ is the commutator $\mathcal{L}_X \circ L - L \circ \mathcal{L}_X$. We intend to show that the only symmetric p-linear maps $L: \otimes^p C_\infty(M) \to C_\infty(M)$ for which $ad(\mathcal{L}_X)L = 0$ for each $X \in \mathcal{H}(M)$ are the multiples of the product of p factors: $f_1 \otimes \cdots \otimes f_p \to f_1 \cdots f_p$. It provides thus a characterization of the product by means of its derivations.

A similar question is investigated for the Lie bracket of vector fields, which is shown to be determined up to a constant by the fact that its derivations are the Lie derivatives. This question has been solved by Van Strien in [4] under stronger assumptions which will be discussed in §3.

2. Characterization of the algebraic structure of $C_{\infty}(M)$

LEMMA 2.1: There exist a finite partition of the unity $\lambda_t(t \le r)$ of M, vector fields $X_t(t \le r) \in \mathcal{H}(M)$ and functions $\mu_t(t \le r) \in C_{\infty}(M)$ such that $\lambda_t = \lambda_t X_t \cdot \mu_t$ for each $t \le r$.

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PROOF: It is well known from dimension theory [2], p. 20 that M admits an open cover $U_t(t \le r)$ such that each U_t is the disjoint union of domains of charts $U_{it}(i \in \mathbb{N})$, as well as a locally finite partition of the unity ρ_{it} $(t \le r, i \in \mathbb{N})$ such that each ρ_{it} has compact support in U_{it} . We set $V_{it} = \{x \in U_{it} : \rho_{it}(x) > 0\}$ and choose a partition of the unity $\rho'_{it}(t \le r; i \in \mathbb{N})$ such that supp ρ'_{it} is compact in V_{it} for all i, t.

For each $t \le r$ and $i \in \mathbb{N}$, we may find α_{it} , $\beta_{it} \in C_{\infty}(M)$ with compact supports in U_{it} such that $\alpha_{it} \mid V_{it} = 1$ and $\beta_{it} = 1$ in some neighborhood of supp α_{it} . If $(x_{it}^1, \ldots, x_{it}^n)$ are local coordinates in U_{it} ,

$$\lambda_t = \sum_i \rho'_{it}, X_t = \sum_i \alpha_{it} D_{x_{it}^1} \text{ and } \mu_t = \sum_i \beta_{it} x_{it}^1$$

have the required properties. Hence the lemma.

Denote by A_p the subspace of $\bigotimes^p C_{\infty}(M)$ spanned by the tensors which are antisymmetric in at least two arguments.

LEMMA 2.2: For all $f_i \in C_{\infty}(M)$ $(i \le p)$, there exist $N \in \mathbb{N}$, vector fields $X_i \in \mathcal{H}(M)$ $(i \le N)$ and $f_{ik} \in C_{\infty}(M)$ $(i \le N, k \le p)$, such that

$$f_1 \otimes \cdots \otimes f_p - \sum_{i=1}^N \mathcal{L}_{f_1 X_i} (f_{i1} \otimes \cdots \otimes f_{ip}) \in A_p.$$

Moreover the vector fields $X_i (i \le N)$ and the functions $f_{ik} (i \le N, k \le p)$ can be choosen independently of f_1 .

PROOF: We have

$$f_1 \otimes \cdots \otimes f_p = \sum_{t \leq r} \lambda_t f_1 \otimes f_2 \cdots \otimes f_p.$$
 (*)

Since $\lambda_t = \lambda_t X_t \cdot \mu_t$,

$$\lambda_{t}f_{1} \otimes f_{2} \cdots \otimes f_{p} = \mathcal{L}_{f_{1}\lambda_{t}}X_{t} (\mu_{t} \otimes f_{2} \otimes \cdots \otimes f_{p})$$

$$-\sum_{i>1} \mu_{t} \otimes f_{2} \otimes \cdots \otimes f_{1}\lambda_{t}X_{t} \cdot f_{i} \otimes \cdots \otimes f_{p}. \tag{**}$$

Let us consider for instance the term i = 2. Setting $X_i \cdot f_2 = g_2$, it reads

$$\mu_{t} \otimes f_{1}g_{2}\lambda_{t}X_{t} \cdot \mu_{t} \otimes f_{3} \otimes \cdots \otimes f_{p}$$

$$= \frac{1}{2}(\mu_{t} \otimes f_{1}g_{2}\lambda_{t}X_{t} \cdot \mu_{t} \otimes f_{3} \otimes \cdots + f_{1}g_{2}\lambda_{t}X_{t} \cdot \mu_{t} \otimes \mu_{t} \otimes f_{3} \otimes \cdots)$$

$$+ \frac{1}{2}(\mu_{t} \otimes f_{1}g_{2}\lambda_{t}X_{t} \cdot \mu_{t} \otimes f_{3} \otimes \cdots - f_{1}g_{2}\lambda_{t}X_{t} \cdot \mu_{t} \otimes \mu_{t} \otimes f_{3} \cdots).$$

The last term is antisymmetric in the two first arguments, hence may be neglected. The other one can be written, setting $\frac{1}{2}g_2X_t = X_t'$,

$$\mathcal{L}_{f_1\lambda_tX_i'}(\mu_t\otimes\mu_t\otimes f_3\otimes\cdots)$$

$$-\sum_{i>2}\mu_t\otimes\mu_t\otimes f_3\otimes\cdots\otimes f_2\lambda_tX_t'\cdot f_i\otimes\cdots$$

In the terms we had to consider in (**), one of the arguments was μ_t , another one had λ_t as a factor. In the terms which we are left to consider, we now have two arguments equal to μ_t and one more divisible by λ_t . This shows the outline of the proof, which will now be achieved by proving the following, by induction on k: if one of the f_i 's is divisible by $\lambda_t f$ ($f \in C_{\infty}(M)$) and p - k others are equal to μ_t , then

$$f_1 \otimes \cdots \otimes f_p - \sum_i \mathcal{L}_{fX_i} (f_{i1} \otimes \cdots \otimes f_{ip}) \in A_p$$

for suitable $X_i \in \mathcal{H}(M)$ and $f_{ij} \in C_{\infty}(M)$, independent of f. For k = 1, assuming for instance that $f_1 = \lambda_i f g$ and $f_i = \mu_i (i > 1)$,

$$f_{1} \otimes \cdots \otimes f_{p} = fg\lambda_{t}X_{t} \cdot \mu_{t} \otimes \mu_{t} \otimes \cdots \otimes \mu_{t}$$

$$= \frac{1}{p} \mathcal{L}_{fg\lambda_{t}X_{t}} (\mu_{t} \otimes \cdots \otimes \mu_{t})$$

$$+ \frac{1}{p} \sum_{i>1} (fg\lambda_{t}X_{t} \cdot \mu_{t} \otimes \cdots \otimes \mu_{t} - \underbrace{\mu_{t} \otimes \cdots \otimes fg\lambda_{t}}_{i}X_{t}\mu_{t} \otimes \cdots)$$

has the required form.

In general, if the property holds true for k, assuming for simplicity that $f_{k+1} = \lambda_i f g_{k+1}$ and $f_i = \mu_i$ for i > k+1, and setting $f_1 \otimes \cdots \otimes f_k = T$,

$$f_{1} \otimes \cdots \otimes f_{k+1} \otimes \cdots \otimes \mu_{t} = \frac{1}{p-k} \mathcal{L}_{fg_{k+1}\lambda_{t}X_{t}} (T \otimes \mu_{t} \otimes \cdots \otimes \mu_{t})$$

$$+ \frac{1}{p-k} \sum_{i \geq k+1} (T \otimes f_{k+1} \otimes \cdots \otimes \mu_{t} - T \otimes \mu_{t} \otimes \cdots \otimes f_{k+1} \otimes \cdots)$$

$$(i)$$

$$- \frac{1}{p-k} \sum_{i \leq k} f_{1} \otimes \cdots \otimes fg_{k+1}\lambda_{t}X_{t} \cdot f_{i} \otimes \cdots \otimes f_{k} \otimes \mu_{t} \otimes \cdots \otimes \mu_{t}$$

hence the conclusion, by induction.

Applying this to (*) for $f = f_1$ and k = p yields the lemma.

PROPOSITION 2.3: Let $P: C_{\infty}(M) \times \cdots \times C_{\infty}(M) \to C_{\infty}(M)$ be a p-linear symmetric map. If $ad(\mathcal{L}_X) P = 0$ for each $X \in \mathcal{H}(M)$, then

$$P(f_1,\ldots,f_p)=k\ f_1\cdots f_p$$

for some $k \in \mathbb{R}$.

PROOF: Since P is symmetric, P vanishes on A_p . Using lemma 2.2.,

$$P(f_1, \ldots, f_p) = \sum_{i} P \circ \mathcal{L}_{f_1 X_i}(f_{i1} \otimes \cdots \otimes f_{ip}) = \sum_{i} \mathcal{L}_{f_1 X_i} \circ P(f_{ij}, \ldots, f_{ip})$$
$$= f_1 \cdot \left[\sum_{i} X \cdot P(f_{i1}, \ldots, f_{ip}) \right],$$

where the X_i 's and f_{ij} 's do not depend on f_1 . Therefore

$$P(f_1,...,f_p) = f_1 P(1,f_2,...,f_p).$$

It is clear that $P(1, f_2, ..., f_p) = P'(f_2, ..., f_p)$ satisfies again $ad(\mathcal{L}_X)P' = 0$, thus, by induction,

$$P(f_1,...,f_p) = f_1...f_p \cdot P(1,...,1).$$

The condition $ad(\mathcal{L}_X)P = 0$ clearly shows that P(1, ..., 1) is constant, hence the result.

RESULT 2.4: The symmetry assumption on P is necessary.

Indeed, consider a compact, connected, oriented manifold M of dimension p-1 and take the map P:

$$(f_1,\ldots,f_p)\to\int f_1\,\mathrm{d}f_2\wedge\cdots\wedge\mathrm{d}f_p.$$

It is clear that p is such that $ad(\mathcal{L}_X)P = 0$ for all $X \in \mathcal{H}(M)$. However, $P \neq 0$, thus P is not even local.

3. Characterization of the algebraic structure of $\mathcal{H}(M)$

PROPOSITION 3.1: Let $B: \mathcal{H}(M) \times \mathcal{H}(M) \to \mathcal{H}(M)$ be a bilinear map such that

$$\mathscr{L}_X B(Y,Z) = B(\mathscr{L}_X Y,Z) + B(Y,\mathscr{L}_X Z), \ \forall \ X, \ Y, \ Z \in \mathscr{H}(M). \tag{*}$$

Then there exists $k \in \mathbb{R}$ such that

$$B(X, Y) = k[X, Y], \forall X, Y \in \mathcal{H}(M).$$

A similar result is proved by Van Strien in [4]. The assumption (*) is replaced by the "naturality" of B, which means the following: B is supposed to be defined on every manifold M and, for every smooth open imbedding φ , the diagram

$$\mathcal{H}(M) \times \mathcal{H}(M) \xrightarrow{B_M} \mathcal{H}(M)$$

$$\downarrow^{\varphi_* \times \varphi_*} \qquad \qquad \downarrow^{\varphi_*}$$

$$\mathcal{H}(N) \times \mathcal{H}(N) \xrightarrow{B_N} \mathcal{H}(N)$$

commutes (see [3]). It is clear that the naturality implies the locality of B and, using the pseudo-group of X, it also implies (*).

LEMMA 3.2: If $X \in \mathcal{H}(M)$ vanishes in an open subset U of M, for each $x \in U$, there exists a neighborhood ω of x and vector fields $X_i, X_i'(i \leq N)$ such that $X = \sum_{i \leq N} [X_i, X_i']$ and X_i, X_i' vanish in ω .

PROOF: Fix ω relatively compact in U. Choose ρ_{it} as in lemma 2.1 and $\varphi_{it} \in C_{\infty}(M)$ with compact support in $U_{it} \setminus \omega$ and equal to 1 in a neighborhood of supp $\rho_{it} X$. Then, if (x^1, \ldots, x^n) are local coordinates in U_{it} ,

$$\rho_{it}X = \sum_{k \leq n} [X_{tik}, X'_{tik}],$$

where

$$X_{tik} = \varphi_{it}D_{x^k}$$
 and $X'_{tik} = \varphi_{it}\int_0^{x^k} \rho_{it} X^k \varphi_{it}^{-2} dx^k \cdot D_{x^k}$,

 X^k being the k's component of the corresponding local form of X. In the integral, the function is extended by 0 outside the image of supp $\rho_{it}X$.

The vector fields

$$X_{tk} = \sum_{i \in \mathbb{N}} X_{tik}$$
 and $X'_{tk} = \sum_{i \in \mathbb{N}} X'_{tik}$

are vanishing in ω and moreover,

$$X = \sum_{t \leq r} \sum_{i \in \mathbb{N}} \rho_{it} X = \sum_{t \leq r} \sum_{k \leq m} [X_{tk'} X'_{tk}],$$

hence the lemma.

PROOF QF PROPOSITION 3.1: We first prove that B is a local map. By Peetre's theorem (for the multilinear version, see [1]), it will then be a differential bilinear operator.

Suppose that $X \in \mathcal{H}(M)$ vanishes in an open subset U. For each $x_0 \in U$, there exist ω such that $x_0 \in \omega \subset U$ and X_i, X_i' vanishing in ω such that

$$X = \sum_{i} [X_{i}, X'_{i}].$$

Choose $Z \in \mathcal{H}(M)$ with support in ω and in a domain of chart V of M, such that $Z_{x_0} = 0$ and $D_{x_0}Z = I$ for a coordinate system of V. Then

$$B(X, Y) = \sum_{i} [\mathcal{L}_{X_{i}}B(X'_{i}, Y) - B(X'_{i}, \mathcal{L}_{X_{i}}Y)]$$
$$= -\sum_{i} B(X'_{i}, \mathcal{L}_{X_{i}}Y)$$

in ω and

$$\begin{split} B(X,Y)_{x_0} &= \mathcal{L}_Z B(X,Y)_{x_0} = \sum_i \mathcal{L}_Z B(X_i',\mathcal{L}_{X_i}Y)_{x_0} \\ &= \sum_i \left[B(\mathcal{L}_Z X_i',\mathcal{L}_{X_i}Y)_{x_0} - B(X_i',\mathcal{L}_Z \mathcal{L}_{X_i}Y)_{x_0} \right] = 0 \end{split}$$

because $\mathcal{L}_Z Z' = 0$ whenever Z' = 0 in ω . Thus X = 0 on U implies that B(X, Y) = 0 on U and B is local.

The end of the proof consists in computations on the differential operator B. The arguments of Van Strien would easily adapt to the present situation. A slightly different approach is given here for the sake of completeness.

Let us decompose B in its symmetric and antisymmetric parts, which both verify the assumption of prop. 3.1.

Fix a coordinate system $(U, x^1, ..., x^n)$ of M and compute B in these coordinates. Taking for X the fields D_{x^i} and $\sum_i x^i D_{x^i}$ shows that, for some A independent of $(x^1, ..., x^n)$,

$$B(X, Y) = A(X, D_{x}Y) \pm A(Y, D_{x}X)$$

(everything is now written in local coordinates) according to B is symmetric or antisymmetric.

The assumption on B reads then

$$D_{x}X \cdot A(Y, D_{x}Z) - A(D_{x}X \cdot Y, D_{x}Z) - A(Y, [D_{x}X, D_{x}Z])$$

$$\pm \{D_{x}X \cdot A(Z, D_{x}Y) - A(D_{x}X \cdot Z, D_{x}Y) - A(Z, [D_{x}X, D_{x}Y])\} \quad (*)$$

$$= A(Y, Z \cdot D_{x}X) \pm A(Z, Y \cdot D_{x}X).$$

If we choose $X, Y \in \mathcal{H}(M)$ such that $D_{x^i}D_{x^i}X = 0$ at x and $Y_x = 0$, it follows that

$$D_xX \cdot A(Z, D_xY) = A(D_xX \cdot Z_x, D_xY) + A(Z_x, [D_xX, D_xY])$$

and thus that the bilinear form $A: \mathbb{R}^n \times gl(n, \mathbb{R}) \to \mathbb{R}^n$ verifies

$$PA(u, O) = A(Pu, O) + A(u, [P, O]).$$

In other words, $Q \to A(., Q) \in L(gl(n, \mathbb{R}))$ belongs to the centralizer of the adjoint action of $gl(n, \mathbb{R})$. It is then easily seen that

$$A(u, Q) = k\left(Q - \frac{1}{n}\operatorname{tr} Q \cdot I\right) + \frac{1}{n}\operatorname{tr} Q \cdot I,$$

for some $k, l \in \mathbb{R}$. Substituting this in (*), it follows that k = l = 0 if B is symmetric and that k = l if B is antisymmetric. Thus

$$B(X, Y) = k[X, Y],$$

hence the result.

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