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MAXWELL O. READE

ELIGIUSZ ZLOTKIEWICZ

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ON VALUES OMITTED BY UNIVALENT FUNCTIONS  
WITH TWO PRE-ASSIGNED VALUES

by

Maxwell O. Reade<sup>1</sup> and Eligiusz Złotkiewicz<sup>2</sup>

1. Introduction

Let  $\mathfrak{M}$  denote the set of all functions  $f(Z)$  which are analytic and univalent in the unit disc  $\Delta$  and which are normalized by the conditions  $f(0) = 0$  and  $f(Z_0) = Z_0$ ; here  $Z_0$  is a fixed point in  $\Delta$ ,  $Z_0 \neq 0$ . For the class  $\mathfrak{M}$ , the following result was established recently.

LEMMA. *If  $f \in \mathfrak{M}$ , then the image domain  $f(\Delta)$  contains the disc  $[W || W| < \frac{1}{4}(1 - |Z_0|)^2]$ . The constant  $\frac{1}{4}(1 - |Z_0|)^2 \equiv R_0$  is the best possible one [2,3].*

Let  $C_R$  denote the circle  $[W || W| = R]$ , let  $f \in \mathfrak{M}$ . and let  $m(R, f) \equiv m[C_R \setminus f(\Delta) \cap C_R]$  be the Lebesgue measure of the set of values on  $C_R$  not taken on by  $f(z)$ . It follows from the Lemma that  $m(R, f) = 0$  for  $0 \leq R < R_0$  and  $m(R, f) = 2\pi R$  for  $R > 1$ .

In this note we shall evaluate the expression

$$(1) \quad m(R) \equiv \sup [m(R, f) | f \in \mathfrak{M}]$$

for  $R$  fixed,  $R_0 \leq R < 1$ . The result we obtain is analogous to one obtained by Jenkins [1]: he considered the class  $S$  of univalent functions  $f(z)$  subject to the usual normalization  $f(0) = 0$  and  $f'(0) = 1$ . Our result reduces to that of Jenkins if we allow  $Z_0 \rightarrow 0$ .

2. The principal result

If  $\Omega$  is a simply-connected domain in the complex domain  $S^2$ , and if  $a$  and  $b$  are two points in  $\Omega$ , then  $\rho(a, b, \Omega)$  will denote the hyperbolic distance between the points  $a$  and  $b$  with respect to  $\Omega$ .

If  $\Omega$  is a simply-connected domain in the complex domain, and if  $\Omega$  contains the points  $a$  and  $b$ , then  $\Omega^*$  denotes the domain obtained from

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$\Omega$  by circular symmetrization with respect to the half-line  $[a, b, \infty]$ , which has its finite end-point at  $a$  and passes through the point  $b$ .

The symbol  $J(R, t)$  denotes the ‘fork-domain’ defined by

$$J(R, t) \equiv S^2 \setminus [ [-\infty, -R) \cup \{w | w = Re^{i\varphi}, t \leq \varphi \leq 2\pi - t\} ].$$

Here  $R$  is fixed,  $R_0 \leq R < 1$ , and  $t$  is fixed,  $0 \leq t < \pi$ .

Our principal result is the following one.

**THEOREM.** *The bound in (1) is given by the formula*

$$(2) \quad m(R) = 2R \arccos(1 - 2D^2),$$

where

$$(3) \quad D = \frac{2(1-d)(R-d) + 8d\sqrt{R}}{(1+d)^2\sqrt{R}} - 1, \quad d \equiv |z_0|,$$

for  $R$  fixed,  $\frac{1}{4}(|-1Z_0|)^2 \equiv R_0 \leq R < 1$ . The extremal function for this problem maps  $\Delta$  onto a suitably-chosen fork-domain.

**PROOF.** Compactness considerations yield the result that there exists at least one extremal function; later considerations will show that there is only one extremal function.

Let  $f(Z)$  be an extremal function for the bound (1). In view of the conformal invariance of the hyperbolic distance, we have

$$(4) \quad \operatorname{arctanh} |Z_0| = \rho(0, Z_0, \Delta) = \rho(0, Z_0, f(\Delta)).$$

If  $f(\Delta)^*$  is the domain obtained from  $f(\Delta)$  by circular symmetrization with respect to the half-line  $[0, Z_0, \infty)$ , then it is well-known that

$$(5) \quad \rho(0, Z_0, f(\Delta)) \geq \rho(0, Z_0, f(\Delta)^*)$$

holds. Now it is geometrically clear that  $f(\Delta)^*$  is contained in a fork-domain  $J(R, t)$  for some  $t$ , and for this  $J(R, t)$  we have

$$(6) \quad \rho(0, Z_0, f(\Delta)^*) \geq \rho(0, Z_0, J(R, t)).$$

From (4), (5) and (6) we obtain the inequality

$$(7) \quad \rho(0, Z_0, \Delta) \leq \rho(0, Z_0, J(R, t)),$$

which is our fundamental one. Since  $\rho(0, Z_0, J(R, t))$  is an increasing function of  $t$ , it follows from (7) that in order to determine  $m(R)$  it is sufficient to determine  $t_0$  so that

$$(8) \quad \operatorname{arc} \tanh |Z_0| = f(0, Z_0, \Delta) = \rho(0, Z_0, J(R, t_0))$$

holds. In order to do this, we shall find a function  $f \in \mathfrak{M}$  that maps  $\Delta$  onto the fork-domain  $J(R, t_0)$ . It is easy to show that the function is unique.

There is no loss in generality in taking  $Z_0 = d > 0$ . Now we obtain the function that maps  $\Delta$  onto  $J(R, t_0)$  as a composition  $W(Z) = W(\zeta(Z))$ , where  $\zeta = \zeta(Z)$  and  $W = W(\zeta)$  are determined by

$$(9) \quad \frac{(1+\zeta)^2}{\zeta} = \frac{(1+z)^2(1+D)^2}{4zD}$$

and

$$(10) \quad w = \frac{R\zeta(1-D\zeta)}{(D-\zeta)},$$

respectively. Here  $D$  is a real constant,  $0 < D < 1$ , to be determined by the condition

$$(11) \quad W(d) = W(\zeta(d)) = d.$$

The function  $\zeta = \zeta(Z)$  in (9) maps  $\Delta$  onto the slit-disc

$$\Delta^* = [\zeta|\zeta| < 1] \setminus [\zeta|D < \zeta < 1].$$

The function  $W = W(\zeta)$  in (10) maps  $\Delta^*$  onto the fork-domain  $J(R, t_0)$  with  $t_0 = 2D^2 - 1$ . The requirement (11), with (9) and (10), now yields (2). This completes the proof.

**COROLLARY.** *If  $f \in S$ , then*

$$m(R) = 2R \arccos(8\sqrt{R} - 8R - 1), \quad \frac{1}{4} \leq R \leq 1.$$

**PROOF.** If we take  $Z_0 = 0$  in the preceding theorem, then  $\mathfrak{M}$  becomes the well-known class  $S$ , while  $R_0 = \frac{1}{4}$  and  $D = 2\sqrt{R} - 1$ . Thus we obtain the earlier result due to Jenkins, alluded to in a preceding paragraph, from the present one by a simple limiting process.

### 3. Final Remark

It is well-known that circular symmetrization preserves the starlikeness of a domain. Hence it is possible to try to obtain the analogue of our theorem for the class of starlike functions  $\mathfrak{M}^*$ , a subclass of  $\mathfrak{M}$ . However the calculations are so formidable, that we have not been able to complete them.

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MAXWELL O. READE AND ELIGIUSZ ZŁOTKIEWICZ

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The University of Michigan  
Ann Arbor, Michigan 48104  
U.S.A.

and  
Universitatis Mariae Curie-Sklodowska  
Lublin, Poland