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FREE BOUNDARY PROBLEM IN FLUID DYNAMICS

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PART I: ONE FLUID PROBLEMS.

Let N be a $C^{1+\alpha}$ curve x = g(y) $(b \le y < \infty)$ with b > 0, g(b) = 0 and lim $g(y) = -\infty$. Consider the 2-dimensional symmetric jet problem: Find a function $y \rightarrow \infty$ u and a curve Γ in $\{0 < y \le b\}$ satisfying

(1.1) $N \cup \Gamma$ is a continuous curve, such that with G denoting the domain bounded by $N \cup \Gamma$ and the x-axis I_{Ω} , the following properties hold:

(1.2) 0 < u < 1 in G ,

(1.3) $\Delta u = 0$ in G ,

(1.4) u = 0 on I₀,

(1.5) u = 1 on $N \cup \Gamma$,

(1.6) $\frac{\partial u}{\partial u} = \lambda$ on NUT;

finally, Γ is required to be smooth, say in $\mbox{c}^{1+\delta}$, and

(1.7) $N \cup \Gamma$ is a C^1 curve in $B_{\delta}(A)$, u is in $C^1(\overline{G} \cap B_{\delta}(A))$

for some $\delta > 0$, where A = (0,b) and $B_r(X)$ denotes the disc of radius r and center X. The parameter λ is to be determined together with u, Γ .

This problem was solved by Leray [21], Serrin [22] and others; see [11] [20] and the references given there. The methods used by most authors are based on

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reducing the problem by means of the hodograph variables to a nonlinear integral equation, and then solving the equation with the aid of the Leray-Schauder fixed point theorem. There are however some other methods, based on variational principles; see Garabedian and Spencer [18] and Garabedian, Lewy and Schiffer [17].

A new variational approach was introduced by Alt, Caffarelli and Friedman (ACF) [2]; it exploits the paper of Alt and Caffarelli [1] who studied the following variational problem. Let

(1.7)
$$J(v) = \int_{\Omega} \left(\left| \nabla v \right|^2 + Q(x) I_{\{v > 0\}} \right) dx$$

and let

$$K = \left\{ v \in H^{1,2}(\Omega), v = u^{0} \text{ on a part } S \text{ of } \partial \Omega \right\},$$

.

where Q is a given positive C^{α} function in $\overline{\Omega}$, $\Omega \subset R^{n}$ and $u^{0} \geq 0$. Consider the problem of finding $u \in K$ such that

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$$J(u) = \min J(v)$$

v \in K

It is proved in [1] that any minimizer u is Lipschitz continuous, and the free boundary $\Gamma = \partial \{u > 0\}$ is smooth if n = 2 (analytic if Q is analytic). Further

$$\frac{1}{r} \int_{B_r(x^0)} u \ge c \quad (c > 0) \quad \text{if } x_0 \in \Gamma \quad (\text{non-degeneracy})$$

Theorem 1.1 [2]. There exists a unique solution of problem (1.1)-(1.7).

Uniqueness is well known [19] and is based on a comparison argument. To prove existence, set

$$I_1 = \{(x,b); x > 0\}$$

and denote by Ω the domain bounded by ${\tt NUI}_1$ and ${\tt I}_0.$ For any $\mu>0$, set

$$\boldsymbol{\Omega}_{\boldsymbol{\mu}} \; = \; \boldsymbol{\Omega} \; \boldsymbol{\cap} \; \{ \mathbf{x} > -\boldsymbol{\mu} \} \quad \text{,}$$

$$K_{\mu} = \left\{ v \in H^{1,2}(\Omega_{\mu}); v = 0 \text{ on } I_{0}, v = 1 \text{ on } N \cup I_{1}, v = h_{\mu}(y) \text{ on } x = -\mu \right\},$$

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where $h_{ij}(y)$ is increasing, $h_{ij}(0) = 0$, $h_{ij} = Q$ at $N \cap \{x = -\mu\}$.

Consider the truncated functional

(1.8)
$$J_{\lambda,\mu}(\mathbf{v}) = \int_{\Omega_{\mu}} |\nabla \mathbf{v} - \lambda \mathbf{I}_{\{\mathbf{v} < 1\} \cap \mathbf{E}} e^{|^2} d\mathbf{x} d\mathbf{y}$$

where e = (0,1) , E = {(x,y); -∞<x<∞, 0<y<b}. If $\lambda>1/b$ then we can construct a v_0 in K_1 with

$$v_0 = \min\{\lambda y, 1\}$$
 if $x > 1$

For such v_0 , $J_{\lambda,\mu}(v_0) < \infty$. Consequently, there exists a minimizer $u_{\lambda,\mu}$ of

$$v \rightarrow J_{\lambda,\mu}(v)$$
, $v \in K_{\mu}$.

Lemma 1.2. The minimizer is unique.

Indeed, suppose u1, u2 are two minimizers and introduce $u_1^{\varepsilon}(x,y) = u_1(x-\varepsilon,y)$ and

$$\mathbf{v}_1 = \mathbf{u}_1^{\varepsilon} \wedge \mathbf{u}_2$$
, $\mathbf{v}_2 = \mathbf{u}_1^{\varepsilon} \vee \mathbf{u}_2$.

Denote by J^{ε} the functional $J = J_{\lambda,\mu}$ corresponding to the translation $\mathbf{x} \rightarrow \mathbf{x} + \varepsilon$ of Ω_{11} , K_{11} . One verifies that

$$J^{\varepsilon}(u_{1}^{\varepsilon}) + J(u_{2}) = J^{\varepsilon}(v_{1}) + J(v_{2})$$

which implies that $J(u_2) = J(v_2)$, i.e., $u_1^{\varepsilon} \vee u_2$ is a minimizer. Consequently $u_1^{\varepsilon} \vee u_2$ is smooth, which implies that either $u_1^{\varepsilon} \ge u_2$ or $u_1^{\varepsilon} \le u_2$ everywhere. Since $u_1^{\varepsilon} < u_2$ near the boundary, we deduce that $u_1^{\varepsilon} < u_2$ throughout the domain. Taking $\varepsilon \neq 0$ we get $u_1 \leq u_2$, and similarly $u_2 \leq u_1$.

Taking $u_1 = u_2$ in the above argument we get:

(1.9)
$$\frac{\partial}{\partial \mathbf{x}} \mathbf{u}_{\lambda,\mu} \geq 0$$
.

Thus the analytic free boundary $\Gamma = \Gamma_{\lambda_{-11}}$ has the form

(1.10) $\Gamma_{\lambda, u} : x = f_{\lambda, u}(y)$.

Next we have:

Lemma 1.3. $f_{\lambda,\mu}(y)$ is continuous and finite if and only if h < y < b, where $h = 1/\lambda$.

Lemma 1.4. $\lambda \rightarrow f_{\lambda, U}(b)$ is continuous.

Using the Lipschitz continuity estimate on $\mbox{ u}_{\lambda,\mu}$ and non-degeneracy, we establish:

Lemma 1.5. If λ is sufficiently large then $f_{\lambda,\mu}(b) < 0$; if $\lambda > 1/b$ and $\lambda - 1/b$ is small enough, then $f_{\lambda,\mu}(b) > 0$.

From Lemmas 1.4, 1.5 we deduce that there is a value $\lambda = \lambda(\mu)$ such that $f_{\lambda,\mu}(b) = 0$, i.e., there is a "continuous fit" at A. For this value of λ , $(u_{\lambda,\mu}, \Gamma_{\lambda,\mu})$ "almost" solve the jet problem. In order to complete the construction of a solution we let $\mu \rightarrow \infty$, $\lambda(\mu) \rightarrow \lambda$ and denote the limiting $u_{\lambda,\mu}, \Gamma_{\lambda,\mu}$ by u,Γ . Then (1.1)-(1.6) are satisfied. Finally: Lemma 1.6. Continuous fit implies "smooth fit", i.e., it implies (1.7).

The above outline of the proof of Theorem 1.1 is a special case of ACF [2] who actually considered the corresponding 3-dimensional axially symmetric jet problem, whereby one replaces

$$\Delta u \quad by \quad \mathbf{f} u \equiv \Delta u - \frac{1}{y} u_{y}$$

and

$$\frac{\partial u}{\partial v} = \lambda$$
 by $\frac{1}{y} \frac{\partial u}{\partial v} = \lambda$.

For this problem the classical methods do not apply.

The variational approach of ACF [2] has been extended to more difficult jet

problems. We shall mention a few. In ACF [3] the plane asymmetric jet problem is considered, whereby the nozzle N is made up of two curves N_1 and N_2 , given by $y = g_i(x)$ $(-\infty < x \le 0)$ and $g_1(x) > g_2(x)$. Setting $A_i = (0, g_i(0))$, one seeks two curves Γ_1 , Γ_2 of the form $\Gamma_i : y = f_i(x)$ $(0 \le x \le \infty)$ with $f_1(x) > f_2(x)$, such that,

$$f_{i}(0) = g_{i}(0)$$
 ,

and, with G denoting the domain bounded by $N_1^{} \cup \Gamma_1^{}$, $N_2^{} \cup \Gamma_2^{}$,

 $\begin{array}{l} -1 < u < 1 \ , \ \Delta u = 0 \quad \text{in } G \ , \\ \\ u = 1 \quad \text{on } \ \Gamma_1 \ , \ u = -1 \quad \text{on } \ \Gamma_2 \ , \\ \\ \left| \frac{\partial u}{\partial \nu} \right| = \lambda \quad \text{on } \ \Gamma_1 \cup \Gamma_2 \ , \end{array}$

 $\lim_{x \to \infty} f'_1(x) = \lim_{x \to \infty} f'_2(x) ,$

and both limits exist, and, finally, there is smooth fit at A_1 and A_2 .

In this problem both λ and the direction of the jet at $x = \infty$ are not given, and are to be found together with u, Γ_1 , Γ_2 .

One works with the truncated functional

$$\int_{\Omega_{U}} |\nabla \mathbf{v} - \lambda \mathbf{I} \{ |\mathbf{v}| < 1 \} \cap \mathbf{E}^{\mathbf{e}^{\perp}} |^{2} d\mathbf{x} d\mathbf{y}$$

where $E = \{x > 0\}$, e is unspecified unit vector (e_1, e_2) with $e_1 > 0$, and e^{\perp} is obtained by rotating e counterclockwise by $\pi/2$.

Notice that the present situation is a 2-parameter problem, with parameters λ ,e ; these must be chosen so as to achieve continuous (and smooth) fit at A_1 and A_2 . For details see ACF [3].

In ACF [4] a jet in a gravity field is considered. Here, roughly speaking,

$$\left|\frac{\partial \mathbf{u}}{\partial \mathbf{v}}\right| = \lambda \sqrt{|\mathbf{y}|}$$

on the free boundary, which means that we replace λ by $\lambda \sqrt{|\mathbf{y}|}$ in the variational functional. An interesting "threshold" phenomenon occurs: If $\alpha \leq 120^{\circ}$ then there exists a $Q_0 > 0$ such that a solution exists if and only if the flux Q is $> Q_0$ (for $\alpha > 120^{\circ}$ there exists a solution for any Q > 0); see Figure 1.



Figure 1

We turn to the axially symmetric cavity problem past a nose N : x = g(y) $(0 \le y \le 1)$, with g(y) < 0, g(0) = -a. Set $I_{=} = \{(x,0), x \le -a\}$. We seek a curve Γ initiating at (0,b) and lying in $\{x > 0, y \ge b\}$ such that, if G is the domain bounded by $N \cup \Gamma$ and I, then:

$$Lu = 0$$
, $u > 0$ in G,

(1.11) $\begin{array}{c} u = 0 \quad \text{on} \quad \partial G \quad ,\\ \frac{1}{y} \cdot \frac{\partial u}{\partial v} = 1 \quad \text{on} \quad \Gamma \quad , \end{array}$

$$\frac{\nabla u}{y} \rightarrow (0,1) \quad \text{if} \quad x^2 + y^2 \rightarrow \infty, \ (x,y) \in G$$

and there is smooth fit at (0,b).

This problem was solved by Caffarelli and Friedman [12] (see also [14] and [9]). One first considers a truncated problem, such as the one obtained by looking at the same problem in a channel of width 2H, setting $u = Qy^2/2$ on the boundary of the channel. Then, with a suitable Q = Q(H) one can achieve a solution with smooth fit. Finally one takes $H \rightarrow \infty$ and shows that $Q(H) \rightarrow 1$. This fact is used in order to prove the last condition in (1.11) for the limiting (u,Γ) . In this manner we obtain a solution of (1.11) with smooth fit at (0,b); further, for large x, Γ has the form

 Γ : y = f(x) with f'(x) $\rightarrow 0$ if $x \rightarrow \infty$.

The above results have recently been extended in ACF [9] to compressible flows; the corresponding quasi-linear functional was studied in ACF [8].

We finally mention that axially symmetric cavities for rotational flow in a channel were studied by Friedman [15], and irrotational flow in a channel with oscillatory wall was studied by Friedman and Vogel [16].

PART II: TWO FLUID PROBLEMS.

Let N_1 : y = H, I_0 the x-axis, and N_2 : y = g(x) $(-\infty < x \le 0)$ with 0 < g(x) < H, and set A = (0, g(0)). Consider the following problem: Find a curve Γ ,

(2.1) Γ : y = f(x) $(0 \le x \le \infty)$, f(0) = g(0), f continuous, $0 \le f(x) \le H$,

and a function u , u = u₁ in the domain Ω_1 bounded by N₁ and N₂ U Γ , u = u₂ in the domain Ω_2 bounded by I₀ and N₂ U Γ , such that the following is true:

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$$\begin{cases} u_{1} = Q \text{ on } N_{1} \\ u_{1} = u_{2} = 0 \text{ on } N_{2} \cup \Gamma \\ u_{2} = -1 \text{ on } I_{0} \\ 0 < u_{1} < Q \text{ in } \Omega_{1} \\ -1 < u_{2} < 0 \text{ in } \Omega_{2} \\ \Delta u_{i} = 0 \text{ in } \Omega_{i} ; \end{cases}$$

further,

(2.3)
$$\nabla u$$
 is bounded in $B_{\xi}(A)$, $N_{2}U\Gamma$ has tangent at A

for some $\delta > 0$, and

(2.4)
$$|\nabla u_1|^2 - |\nabla u_2|^2 = \lambda$$
 on Γ .

Here λ is a constant which must be found together with $\,u\,$ and $\,\Gamma.\,$

The jump relation (2.4) is the new feature of this problem. In ACF [5] the functional

$$J(v) = \int \left[\left| \nabla v \right|^2 + Q^2(x) \lambda^2(v) \right] dx$$

was introduced with

$$\lambda^{2}(\mathbf{v}) = \begin{cases} \lambda_{1}^{2} & \text{if } \mathbf{v} < 0\\ \lambda_{2}^{2} & \text{if } \mathbf{v} > 0 \end{cases}$$

and $\lambda_1^2 - \lambda_2^2 \neq 0$, with the idea of applying it to study 2-fluid problems, such as (2.1)-(2.4). It was proved that any minimizer is Lipschitz continuous, a non-degeneracy property holds, and the free boundary is in C^1 in case n = 2. These results are used in order to establish:

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<u>Theorem 2.1</u> (ACF [6]). There exists a unique solution of the problem (2.1)-(2.4), and Γ is in C^1 .

To prove the theorem we introduce a truncated functional

$$\begin{split} \mathbf{J}_{\lambda,\mu}(\mathbf{v}) &= \int_{\Omega_{\mu}} \left| \nabla \mathbf{v} - \left(\lambda_2 \mathbf{I}_{\{\mathbf{v} < 0\}} + \lambda_1 \mathbf{I}_{\{\mathbf{v} > 0\}} + \lambda_0 \mathbf{I}_{\{\mathbf{v} = 0\}} \right) \mathbf{I}_{\{\mathbf{x} > 0\}} \mathbf{e} \right|^2 d\mathbf{x} d\mathbf{y} \\ \mathbf{e} &= (0,1) \ , \ \ \Omega_{\mu} = \{ -\mu < \mathbf{x} < \infty \ , \ 0 < \mathbf{y} < \mathbf{H} \} \ , \end{split}$$

, 1 , 0 , 2 , 2 , . . .

$$\lambda_2 = \frac{1}{h}$$
, $\lambda_1 = \frac{Q}{H-h}$, $\lambda = \lambda_2^2 - \lambda_1^2$, $\lambda_0 = \min(\lambda_1, \lambda_2)$

and introduce the admissible set

where

$$K_{\mu} = \left\{ v \in H^{1,2}(\Omega_{\mu}); v = -1 \text{ on } I_{0}, v = 0 \text{ on } N_{1}, -1 \leq v \leq 0 \text{ below } N_{2}, \\ 0 \leq v \leq Q \text{ above } N_{2}, v = h(y) \text{ on } x = -\mu \right\}$$

with h(y) suitable monotone increasing function. The problem

$$v \rightarrow \min J_{\lambda,\mu}(v)$$
, $v \in \kappa_{\mu}$

has a unique solution u with u ≥ 0 (cf. Lemma 1.2). Thus the free boundary is a curve

$$\Gamma_{\lambda,\mu}$$
: $y = f_{\lambda,\mu}(x)$

Notice that h is the asymptotic height of the free boundary at $x = \infty$.

We now let h vary and show that for some value of h, say $h = h(\mu)$, $f_{\lambda,\mu}(0) = b$, that is, there is a continuous fit at A. We finally let $\mu \neq \infty$ in order to complete the existence proof; for more details see ACF [6].

In principle, all the steps in the proof of Theorem 2.1 have their counterparts in the proof of Theorem 1.1, but they require a more refined analysis.

A significantly harder problem occurs when the upper fluid is not everywhere confined by $\{y = H\}$, that is, N_1 consists of $\{y = H, x \le 0\}$ and one seeks, in addition to Γ , another free boundary Γ_1 initiating at (0,H) such that

$$\frac{\partial u_1}{\partial v} = \overline{\lambda} \quad \text{on} \quad \Gamma_1$$

This is a 2-parameter problem (with parameters λ , $\overline{\lambda}$) and they must be chosen in such a way as to achieve a continuous fit at both A and (0,H).

This problem was solved in ACF [7]. The proof involves quantitative estimates on the location of the free boundaries Γ and Γ_1 , depending on the relations between λ and $\overline{\lambda}$. Some of these estimates are derived by comparison arguments; the flows used in the comparison are constructed by solving one-fluid jet problems.

Some of the techniques developed for 2-fluid jet problems can be applied to other 2-fluid problems. We briefly mention the 2-fluid dam problem (see Figure 2).



Figure 2

Denote by $\phi_i = p + \delta_i y$ the piezometric head of the *i*-th fluid and assume that $\delta_2 > \delta_1$. We introduce the stream function ψ (that is, $\phi - i\psi$ is holomorphic). Then in terms of ψ the problem reduces to

$$\Delta \psi = \frac{\partial}{\partial \mathbf{x}} H(\psi)$$
 in the dam,

where

$$H(t) = \begin{cases} 0 & \text{if } t < 0 , \\ -\delta_2 + \delta_1 & \text{if } 0 < t < Q_1 , \\ -\delta_2 & \text{if } t \ge Q_1 ; \end{cases}$$

here $\psi_2 = -Q_2$ at the bottom of the dam, and $\psi = Q_1$ at the top. On the top free boundary $\Gamma_{0.1}$:

$$\psi = Q_1 \quad \text{and} \quad \frac{\partial \psi_1}{\partial \nu} = \delta_1 \frac{\partial \mathbf{x}}{\partial \nu} ,$$

and on the intermediate free boundary $\Gamma_{1,2}$:

$$\psi_{i} = 0$$
, $\frac{\partial \psi_{1}}{\partial v} - \frac{\partial \psi_{2}}{\partial v} = (\delta_{1} - \delta_{2}) \frac{\partial \mathbf{x}}{\partial v}$

 ψ also satisfies suitable Dirichlet and Neumann conditions.

<u>Theorem 2.2</u> (ACF [10]). There exists a solution $(\Psi, \Gamma_{0,1}, \Gamma_{1,2})$ of the 2-fluid dam problem with $\Gamma_{0,1}, \Gamma_{1,2}$ analytic and c^1 respectively, and

$$\Gamma_{0,1} : y = f_1(x) , \Gamma_{1,2} : y = f_2(x)$$

where $f_i(x)$ are Lipschitz continuous and strictly monotone decreasing functions. Partial results are obtained in ACF [10] for general 2-dimensional dams.

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