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# Transversely hyperbolic 1-dimensional foliations. 

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In this paper we investigate 1-dimensional foliations with a transverse hyperbolic structure. There is a danger of confusion here, because of different meanings of the word "hyperbolic". What is meant in this paper by a transverse hyperbolic structure for on a 1dimensional foliation of a manifold of dimension $n$, is that the given foliation is given by local submersions into $\mathbf{H}^{\boldsymbol{n}-1}$, the hyperbolic space of dimension ( $n-1$ ), and that different submersions differ from each other on their common domain by composition with an isometry of $\mathbf{H}^{\boldsymbol{n - 1}}$.

There is a theory of transverse Riemannian structures on foliations, of which the above is a very special case. The first paper in this area was by Reinhart [9]. Amongst other contributors to the subject are Fedida [5] and Conlon [3]. The reader is referred to the papers of Molino, especially [8], for an elegant general treatment. Molino's idea of replacing the model transverse manifold by its associated bundle of frames is particularly illuminating. Papers by Carriere and Molino in these proceedings contain further details and references.

In this paper, we have thought it advisable to repeat some proofs of results due variously to Thurston, Carriere and Molino, in order to make the reader's task easier. Also, some of these results are not easily available for reference.

Our main result is the following generalization of a theorem due to Thurstion [11].
Main Theorem. Let $M$ be a closed $n$-manifold with a smooth 1 -dimensional foliation $\boldsymbol{\phi}$, with transverse hyperbolic structure. Then one of the following two possibilities must occur:

1) Each leaf of $\phi$ is a circle. The holonomy $\operatorname{map} h: \pi_{1} M \rightarrow$ IsomH $H^{n-1}$ has a discrete image and a non-trivial kernel. The holonomy associated to each leaf is finite (and is generically zero).
2) The manifold $M$ has dimension $n=3$ or 4 . The closure of each leaf is a torus of dimension 2 or 3 respectively. The holonomy representation is injective, and fixes a certain point on the boundary sphere of $\mathrm{H}^{\boldsymbol{n}-1}$. Transferring to the upper halfspace model, by putting this point at infinity, we find a similarity $S$ of the boundary of the upper halfspace, $R^{n-2}$, which has a change of scale $\lambda<1$, such that the image of $\pi_{1} M$ acts by elements of the form $z \rightarrow S^{k} z+b$. As we range over elements of $\pi_{1} M, k$ takes on all integral values, and the elements $b$ form $a$ dense subgroup of $R^{1}$ or $R^{2}$ respectively. This subgroup is invariant under $S$. $M$ is a fibre bundle, with fibre either $T^{2}$ or $T^{3}$ and each fibre is foliated by the leaves of 4 . A leaf is always dense in its fibre. The base space of the bundle is a circle, and the monodromy of the bundle is an isomorphism $A: T^{n} \rightarrow T^{n}$, where $A \in G L(n, Z)$ and $n=2$ or 3 . $A$ has one expanding direction, with eigenvalue $\pm \lambda^{-n+1}$ and either one or two contracting directions, according as $n=2$ or $n=3$. If $n=3$, then the contracting directions have eigenvalues which have equal absolute values. The foliation $\$$ consists of lines on $T^{n}$, parallel to the expanding direction of $A$.

The manifold and foliation also have an algebraic description. $M$ is the quotient of a simply connected solvable Lie group $G$ by a group $\Gamma$ of affine automorphisms of $C$, which acts freely on $C$. $\Gamma$ has a subgroup $\Gamma_{0}$ of index at most two which is a uniform discrete subgroup of $G$ acting on the right, and the foliation is given by a 1 -parameter subgroup acting on the left. Elements of $\Gamma$, which are not in $\Gamma_{0}$, reverse either the orientation of the leaves in $G$, or the transverse orientation.

## 81. Transverse Riemannian Structures.

Let $C$ be a group of isometries of a Riemannian manifold. Let $M$ be a smooth manifold and let $F$ be a smooth foliation. We say that $F$ is a $(C, X)$-foliation, if it is defined by smooth local submersions $f_{i}: U_{i} \rightarrow X$, where the $\left\{U_{i}\right\}$ are an open covering of $M$, and the leaves of $F$ are given locally as connected components of the inverse images of points of $X$. There is assumed to be a locally constant map $\gamma_{i j}: U_{i} \cap U_{j} \rightarrow G$. such that $f_{i}(x)=\gamma_{i j}(x) f_{j}(x)$ for $x \in U_{i} \cap U_{j}$. Clearly, $\gamma_{i j}$ is determined by $f_{i}$ and $f_{j}$. The $\left\{f_{i}\right\}$ are called admissible submersions. We will suppose that the family $\left\{f_{i}\right\}$ is maximal, with the object of making the structure unique, as is usual in manifold theory.

We now define the holonomy homomorphism and the developing map. Suppose $a: I \rightarrow M$ is a path, $u$ is the germ of an admissible submersion defined near $a(0)$ and $v$ is the germ of an admissible submersion defined near $a(1)$. We choose a partition $0=t_{0} \leq t_{1} \leq \cdots \leq t_{k}=1$ and admissible submersions $f_{i}: U_{i} \rightarrow X$, where $a\left[t_{i-1}, t_{i}\right] \subseteq U_{i}(1 \leq i \leq k)$. Let $f_{0}=u$ and $f_{k+1}=v$, and let $t_{-1}=t_{0}=0, t_{k+1}=t_{k}=1$. Let $\gamma_{i, i-1} \in C$ be defined by $\gamma_{i, i-1} f_{i-1}=f_{i}$ near $\alpha\left(t_{i-1}\right)$, for $1 \leq i \leq k+1$. We define

$$
h(\alpha, v, u)=\gamma_{k+1, k} \gamma_{k, k-1} \cdots \gamma_{k, 1} \gamma_{1,0} .
$$

We now have to show that $h(\alpha, u, v)$ is independent of the choices involved.
Step 1. If $0=t_{0} \leq t_{1} \leq \cdots \leq t_{k}=1$ is fixed, and $f_{i}: U_{i} \rightarrow X$ is changed to $f_{i}^{\prime}: U_{i}^{\prime} \rightarrow X$, then $h(\alpha, v, u)$ is unaltered.

Clearly, we may assume that only one $f_{i}$ is changed. Then $f_{i}=\gamma f_{i}$ on $\alpha\left[t_{i-1}, t_{i}\right]$, for some $\boldsymbol{\gamma} \in \mathcal{G}$. It follows that $\boldsymbol{\gamma}_{i, i-1}^{\prime}=\boldsymbol{\gamma} \boldsymbol{\gamma}_{i, i-1}$ and $\boldsymbol{\gamma}_{i+1, i}^{\prime}=\boldsymbol{\gamma}_{i+1, i} \boldsymbol{\gamma}^{-1}$, and so $\boldsymbol{h}(\alpha, v, u)$ is unaltered.

It follows that the definition of $h(\alpha, v, u)$ depends at most on the partition $0=t_{0} \leq t_{1} \leq \cdots \leq t_{k}=1$.
Step 2. Given a partition $0=t_{0} \leq t_{1} \leq \cdots \leq t_{k}=1$, and a computation of $h(a, v, u)$ using this partition, any finer partition gives the same answer.

We may assume that a single point is added, with $t_{i-1} \leq s \leq t_{i}$. The computation may be performed by associating each of the two intervals [ $t_{i-1}, s$ ] and [ $s, t_{i}$ ] with the same submersion $f_{i}: U_{i} \rightarrow X$. The corresponding coordinate transformation in $G$, coming from the point $s$, is the identity, so that $h(a, v, u)$ is unchanged.
$>$ From these two steps, it follows immediately that $h(a, v, u)$ is well-defined. We have the following easily verified properties:
1.1. $h\left(\alpha^{-1}, u, v\right)=h(\alpha, v, u)^{-1}$.
1.2. If $\alpha$ and $\beta$ are two paths and $\alpha(1)=\beta(0)$, then we define the path $\beta \alpha$ in the obvious way. Let $\boldsymbol{w}$ be a germ of an admissible submersion near $\beta(1)$. Then

$$
h(\beta \alpha, w, u)=h(\beta, w, v) h(\alpha, v, u) .
$$

1.3. If $\gamma_{0,} \gamma_{1} \in G$, then $h\left(\alpha, \gamma_{1} v, \gamma_{0} u\right)=\gamma_{1} h(\alpha, v, u) \gamma_{0}^{-1}$.
1.4. If $\alpha$ is homotopic to $\beta$, keeping endpoints fixed, then $h(\alpha, v, u)=h(\beta, v, u)$. The proof of this is that a very small movement of $\alpha$ can be dealt with without changing the $f_{i}: U_{i} \rightarrow X$.
1.5. Let $u$ be a germ of an admissible submersion at $m_{0} \in M$. Then $h_{u}: \pi_{1}\left(M, m_{0}\right) \rightarrow G$, defined by $h_{u}(\alpha)=h(\alpha, u, u)$. is a homomorphism. This homomorphism is called the holonomy homomorphism based on $u$ of the ( $C, X$ )-foliation.
1.6. $h_{\gamma u}=\gamma h_{u} \gamma^{-1}$ for $\gamma \in C$.

Let $\tilde{\boldsymbol{M}}$ be the universal covering of $\boldsymbol{M}$. The developing map $D_{u}: \tilde{M} \rightarrow X$, is defined as follows. We regard elements of $\tilde{M}$ as homotopy classes of paths $a: I, 0 \rightarrow M, m_{0}$. Using the notation above, we define

$$
D_{u}(\alpha)=h(\alpha, v, u)^{-1} v(\alpha(1)) .
$$

1.7. This map is a well-defined submersion $D_{u}: \tilde{M} \rightarrow X$ and

$$
D_{\gamma_{u}}(\alpha)=\gamma D_{u}(a)
$$

1.8. If $\beta$ is a loop based at $m_{0}, 1.2$ implies that

$$
\begin{aligned}
D(\alpha \beta, u) & =h(\alpha \beta, v, u))^{-1} v(\alpha(1)) \\
& =h(\beta, u, u)^{-1} D(\alpha, u) \\
\text { or } D_{u}(\tilde{m} \beta) & =h_{u}(\beta)^{-1} D_{u}(\tilde{m})
\end{aligned}
$$

Thus, transferring the action of $\pi_{1}\left(M, m_{0}\right)$ to the left of $\tilde{M}$ by the definition $\beta . a=a \beta^{-1}$, we obtain the equation

## 1.9. $D_{u}(\beta \tilde{m})=h_{u}(\beta) D_{u}(\tilde{m})$.

$A(G, X)$-foliation is said to be complete if $D_{u}: \tilde{M} \rightarrow X$ is a locally trivial fibre bundle for some (and hence for any) $u$. The following result is due to Thurston [11]. A version of it was proved earlier by Ehreamann [4], under much atronger assumptions.
1.10. Theorem. If $M$ is a closed manifold, the foliation is complete. If $X$ is simply connected, then each leaf of the foliation of $\tilde{M}$ is a fibre of $D_{u}: \tilde{M} \rightarrow X$ and conversely.
Proof. Define a smooth field $\tau$ of planes on $M$, which are transverse to the foliation and have the same dimension as $X$. (For example, take any smooth metric on $M$ and take the planes orthogonal to the foliation.) Use $\tau$ to construct a new Riemannian metric on $M$, which induces the same metric as before on each leaf, such that $\tau$ is orthogonal to the foliation, and such that each admissible local submersion $f$ maps $\tau_{z}(x \in U)$ by a linear isometry onto the tangent space to $X$ at $f \boldsymbol{x}$.
$\underset{\sim}{\text { A }}$ path in $M$ (or $\tilde{M}$ ) is said to be horizontal if it is tangent to the field $\tau$ (or the lifted field $\tilde{\tau}$ in $\tilde{\boldsymbol{u}}$ ) at each point of the path.
1.11. Lemma. If $M$ is closed, then, given any path $a:(a, b) \rightarrow X(-\infty \leq a<b \leq \infty)$ and any $c$ ( $a<c<b$ ), and an element $\tilde{\alpha}(c) \in \tilde{M}$, such that $D_{u} \tilde{\alpha}(c)=\alpha(c)$, there is a unique horizontal lifting $\tilde{\alpha}:(a, b) \rightarrow \tilde{M}$, such that $D_{u} \tilde{\alpha}=a$.
Proof. Paths can be lifted locally, using the differential equation $\frac{d \tilde{\alpha}}{d t}=\theta(\tilde{\alpha}(t)) \frac{d a}{d t}$, where $\theta(\tilde{m})$ is the linear isometry described above, from the tangent space to $X$ at $D_{u}(\tilde{m})$ to $\tau_{\tilde{m}}$. Clearly, the lifting is unique and $\alpha$ and $\tilde{\alpha}$ have the same length. Let ( $\left.a^{\prime}, b^{\prime}\right) \subset(a, b)$ be a maximal subinterval over which $\tilde{\alpha}$ is defined. Since $\boldsymbol{M}$ is compact, $\tilde{\boldsymbol{\nu}}$ is complete as a Riemannian manifold, and so, if $b^{\prime}<\dot{b}, \tilde{\alpha}(t)$ tends to a limit as $t$ tends to $b^{\prime}$. But then $\tilde{\alpha}$ can be extended beyond $b^{\prime}$. This contradiction shows that $b^{\prime}=b$. Similarly $a^{\prime}=a$. This completes the proof of the lemma.

It follows that a ball in $X$ with centre $t_{0}$ can be uniquely lifted into $\tilde{\boldsymbol{M}}$ so that radii are horizontal, once the lifting of the centre is fixed. The lifting is smooth (with no singularity at the centre) because solutions to a differential equation depend smoothly on parameters. This
gives a local product structure to the map $D_{u}: \tilde{M} \rightarrow X$ and completes the proof of Theorem 1.10. except for the special situation when $X$ is simply connected, which will be dealt with in Lemma 1.12 .

If $F$ is a foliation on a connected manifold $M$ with a transverse Riemannian structure, modelled on a Riemannian manifold $X$, then the developing map $D_{u}: \tilde{M} \rightarrow X$ maps into a single component of $X$. It follows that there is no loss of generality in supposing that $X$ is connected. Since the transverse structure is locally defined, we may also replace $X$ by its universal cover.

The following lemma is an immediate consequence of the homotopy exact sequence of the fibre bundle $D: \tilde{\boldsymbol{M}} \rightarrow X$, using exactness at $\pi_{1} F$, where $F$ is the fibre.
1.12. Lemma. Suppose $X$ is simply connected and $M$ is a closed manifold with a foliation modelled on $X$, then each fibre of $D_{z}: \tilde{M} \rightarrow X$ is connected.

The last sentence of Theorem 1.10 now follows.
1.13. Proposition. Let $M$ be a closed manifold and let $P$ be a foliation with a transverse Riemannian structure modelled on a connected Riemannian manifold $X$. Then there is a positive number I such that any ball of radius $I$ in $X$ is convex and is embedded Consequently, $X$ is complete.
Proof. Let $C_{1}, \cdots, C_{k}$ be a finite covering of $M$ by compact foliation charts. Let $f_{i}: C_{i} \rightarrow X$ be the associated submersion. Since $D: \tilde{\mathbb{M}} \rightarrow X$ is surjective, we see that each point $x \in X$ is the image of some point of $f_{i} C_{i}$ for some $i$, under an isometry of $X$. Since the radius of convexity has a positive lower bound on any compact set, the result followa.
1.14. Proposition. Let $M$ be a closed manifold with a foliation F. modelled on a simply connected manifold $X$. Let $h: \pi_{1} M \rightarrow \operatorname{Isom} X$ be the holonomy homomorphism, let $H$ be the closure of $h\left(\pi_{1} M\right)$ in Isom $X$, and let $H_{0}$ be the component of the identity in $H$. Then the following conditions are equivalent:

1. $H_{0}=\{i d\} ;$
2. $h\left(\pi_{1} M\right)$ is a discrete subgroup of lsom $X$;
3. $h\left(\pi_{1} M\right)$ is a closed subgroup of lsomX.
4. $H=h\left(\pi_{1} M\right)$;
5. Each leaf of $P$ is compact.

Proof. To see that 1) implies 2), suppose $H_{0}=\{i d\}$. Then $H$ is a discrete subgroup of lsomX, since lsom $X$ is a Lie group. Hence $h\left(\pi_{1} M\right)$ is also discrete. The fact that 2) implies 3) is atandard for subgroups of topological groups. It is immediate that 3) implies 4).

To see that 4) implies 5), note that $D: \tilde{M} \rightarrow X$ induces a map $M \rightarrow X / h\left(\pi_{1} M\right)$. The orbit space of $X$ under any closed subgroup of lsom $X$ is a Hausdorf space. Hence the inverse image of any point of $X / h\left(\pi_{1} M\right)$ is a closed subset This means that each leaf of $F$ is a closed, and hence compact, subset of $M$.

We show that 5) implies 1) by contradiction. We assume that $H_{0} \neq\left\{\right.$ id \}. Let $\alpha_{i} \in \pi_{1} M$, such that $h\left(a_{i}\right)$ tends to the identity in lsom $X$. We may choose a point $x_{0}$, such that the points $h\left(a_{i}\right) x_{0}$ are distinct. Let $\tilde{L}=D^{-1}\left(x_{0}\right)$ be the corresponding leaf of $\tilde{\mathcal{M}}$. Then the leaves $a_{i} \tilde{L}$ all project to the same leaf $L$. Locally $\tilde{\boldsymbol{M}}$ and $\boldsymbol{M}$ are isomorphic. It follows that any foliation chart meeting $L$ must contain an infinite number of plaques of $L$, and so $L$ is not compact.

## 82. One-dimensional foliations.

In this section, we prove a result due to Thurston [11] in the transversely hyperbolic case, and to Carrière [1,2] in the form stated. We follow Thurston's method, with improvements due to Carrière.
2.1. Theorem. Let $M$ be a connected, closed manifold and let $F$ be $a$-dimensional foliation with a transverse Riemannian structure, modelled on a simply connected manifold $X$. Let $h: \pi_{1} M \rightarrow$ Isom $X$ be the holonomy homomorphism, and let $H$ be the closure of $h\left(\pi_{1} M\right)$. Let $H_{0}$ be the component of the identity of $H$. Then $H_{0}$ is abelian. Moreover if $h$ is not injective, then the five equivalent conditions of Proposition 1.14 are satisfied and each leaf of $F$ is $a$ circle.

Proof. If $h: \pi_{1} M \rightarrow$ IsomX is not injective, let $\alpha \in \pi_{1} M$ be a non-trivial element in the kernel. From the equivariance of $D: \tilde{M} \rightarrow X$, we see that $a$ preserves each fibre. Since it also acts fixed point free, the quotient of the fibre by $a$ is a circle. This proves the last sentence of Theorem 2.1. By Proposition 1.14, $H_{0}=\{i d\}$.

So we may now assume that $h$ is injective. By Proposition 1.13, there is a leaf of $F$, which is a copy of $R$. But this means that $H_{0} \neq\{i d\}$. The fibre bundle $D: \tilde{M} \rightarrow X$ has contractible fibres and is therefore trivial. So $\tilde{M} \cong X \times R$ and $D$ corresponds to projection onto the first factor.

We may assume without loss of generality that the foliation has oriented leaves. The reason is that going to the double cover, which results from orienting the leaves, replaces $H$ by a subgroup of index at most two. But then the component of the identity of $H$ is unaltered.

We impose on $M$ the adapted metric used in the proof of Theorem 1.10 . Let $I>0$ be chosen so that every loop in $M$ of length at most $I$ is contractible. We choose a left invariant Riemannian metric on Isom $X$. If $\gamma \in \pi_{1} M$ and $x \in X$, we write $\gamma x$ instead of $h(\gamma) x$. We define $U_{\text {e }}$ to be the open ball in Isom $X$ of radius $\epsilon$. For each $\epsilon>0$, let $\Gamma_{e}=U_{6} \cap h\left(\pi_{1} M\right)$. Since $h$ is injective, this is isomorphic to $h^{-1}\left(U_{6}\right)$. We know from Proposition 1.13 that there is an $\epsilon_{0}$ such that each ball in $X$ of radius $4 \epsilon_{0}$ is convex, and such that $4 \epsilon_{0}<I$.

Given a compact connected subset $K$ of $X$, there is an $\epsilon(K)$ with the property that if $g_{1 . g_{2} \in U_{a}(K)}$ and $x \in K$, then $d\left(g_{1} x, g_{8} x\right)<\epsilon_{0}$.

We now order the elements of $\Gamma_{d}(x)$. Given $x \in K$ and $\gamma_{0}, \gamma_{1} \in \Gamma_{d}(x)$, we have $d\left(\gamma_{0} x, \gamma_{1} x\right)<\varepsilon_{0}$. Let $\alpha$ be a path in $X$ from $\gamma_{0} x$ to $\gamma_{1} x$ of length less than $4 \epsilon_{0}$, and let $\tilde{x} \in D^{-1}(x) \subset \tilde{M}$. Let $\tilde{a}$ be the horizontal lifting of $a$, with $\tilde{\alpha}(0)=\gamma_{0} \tilde{x}$. Then $\gamma_{1} \tilde{x}$ and $\tilde{\alpha}(1)$ both lie in the oriented real line $D^{-1}\left(\gamma_{1} x\right)$. We define $\gamma_{1}>\gamma_{0}$ if $\gamma_{1} \tilde{x}>\tilde{a}(1)$ and $\gamma_{1}<\gamma_{0}$ otherwise. Note that we can not have $\boldsymbol{\gamma}_{1} \tilde{x}=\tilde{a}(1)$, for otherwise $\tilde{a}$ would represent a non-trivial path in $\boldsymbol{M}$ of length less that $I$, and this is impossible.

Since $\tilde{\alpha}$ depends continuously on $\tilde{x}$ and $a$, and since equality $\gamma_{1} \tilde{x}=\tilde{\alpha}(1)$ is not possible, we see that the truth of the inequality $\gamma_{1}>\gamma_{0}$ or $\gamma_{1}<\gamma_{0}$ is independent of the homotopy class of $\alpha$ fixing the endpoints, provided the homotopy varies through paths of length less than $4 \varepsilon_{0}$. The homotopy class of $a$ is equal to that of the short geodesic from $\gamma_{0} \boldsymbol{x}$ to $\gamma_{1} x$ - a lengthdecreasing homotopy is given by taking the short geodesic from $\alpha(0)$ to $\alpha(t)$ and then the original path from $\alpha(t)$ to $\alpha(1)$. Also the inequality is independent of small movements of $x$. But since $K$ is connected, the inequality $\gamma_{1}>\gamma_{0}$ or $\gamma_{1}<\gamma_{0}$ depends only on $K$. We will write $\gamma_{1}>\gamma_{K} \gamma_{0}$ or
 ordering is independent of $K$, but we will not bother to prove this.)

We now verify a number of properties of the ordering.
2.2.1. We have $\gamma_{1}>_{x} \gamma_{0}$ if and only if $\gamma_{0}<_{x} \gamma_{1}$.

Proof. This follows from Diagram 1, where $\tilde{\alpha}$ and $\tilde{\alpha}^{\prime}$ are horizontal lifts of $\alpha$.

Diagram 1

2.2.2. If $\boldsymbol{\gamma}_{0}<\boldsymbol{x} \boldsymbol{\gamma}_{1}$ and $\boldsymbol{\gamma}_{1}<\boldsymbol{x} \boldsymbol{\gamma}_{\mathbf{2}}$, then $\boldsymbol{\gamma}_{0}<\boldsymbol{x} \boldsymbol{\gamma}_{\mathbf{2}}$.

Proof. This follows from Diagram 2.

2.2.3. If $K \subset L$ are compact sets, then $\Gamma_{f}(L) \subset \Gamma_{a}(K)$, and the two orderings agree on $\Gamma_{a(L)}$. It follows that the ordering is well-defined on the germ of $h\left(\pi_{1} M\right)$ near the identity in IsomX.
2.2.4. Let $K$ be a compact connected set which contains a ball of radius $\epsilon_{0}$. Let $U=U^{-1}$ be a neighbourhood of the identity in lsom $X$, such that $U^{2} \subset U_{0}(x)$. Let $\gamma_{1} \gamma_{0}, \gamma_{1} \in U$ and let $\gamma_{0}<\gamma_{1} \gamma_{1}$. Let $\tilde{\alpha}$ be a horizontal path in $\tilde{\boldsymbol{\mu}}$ from $\gamma_{0} \tilde{x}$ to $\tilde{\alpha}(1)<\gamma_{1} \tilde{x}$ and let $D \tilde{x}=x$.
2.2.4.1. We have $\gamma \gamma_{0}<\boldsymbol{K} \gamma \gamma_{1}$. To see this, note that $\gamma \tilde{\alpha}$ is a horizontal path from $\gamma \gamma_{0} \tilde{x}$ to $\boldsymbol{\gamma} \tilde{\alpha}(1)<\gamma \gamma_{1} \tilde{x}$.
2.2.4.2. We have $\gamma_{0} \gamma<k \gamma_{1} \gamma$. To see this, we suppose that the point $x$ defined above is the centre of a ball in $K$ of radius $\epsilon_{0}$. Then $\gamma x \in K$ and, writing $\tilde{y}=\gamma^{-1} \tilde{x}$, we see that $\tilde{\alpha}$ from $\gamma_{0} \gamma \tilde{y}$ to $\boldsymbol{\gamma}_{\mathbf{1}} \boldsymbol{\gamma} \tilde{y}$ can be used to show that $\boldsymbol{\gamma}_{\mathbf{0}} \boldsymbol{\gamma}<_{\boldsymbol{\kappa}} \boldsymbol{\gamma}_{\mathbf{1}} \boldsymbol{\gamma}$.

Let $\Gamma_{\epsilon}^{+}=\left\{\gamma \epsilon \Gamma_{\epsilon}: \gamma\right\rangle_{K}$ id $\}$, where $\epsilon<\epsilon(K)$. We call this the set of positive elements in $\Gamma_{\epsilon}$.
2.2.5. By 2.2.4, we see that if $\epsilon$ is small enough, then $\boldsymbol{\gamma}>_{K}$ id if and only if id $>_{K} \boldsymbol{\gamma}^{\boldsymbol{- 1}}$.
2.3. Lemma. If $K$ is a given compact connected set, then the ordering < ${ }_{K}$ on $\Gamma_{f}^{+}$, the set of positive elements of $\Gamma_{6}$, has the same order type as the positive integers.
Proof.

## Diagram 3



Since $4 \epsilon_{0}<I$, we see that for any ball $\tilde{B}$ in $\tilde{\boldsymbol{M}}$ of radius $2 \epsilon_{0}$. and any $\boldsymbol{\gamma} \neq \mathrm{id}$ in $\pi_{1} \boldsymbol{M}, \tilde{B} \cap \gamma \tilde{B}=\boldsymbol{\sigma}$. We fix our attention on a certain $x_{0} \in K$ and let $B(r)$ be the ball in $X$ of radius $r$ and centre $x_{0}$. Then $D^{-1} B \cong B \times R$ for $r<4 \epsilon_{0}$. Let $\tilde{x}_{0} \in D^{-1} x_{0}$. Let $\tilde{B}(r)$ be the lift of $B$, whose centre is at $\tilde{x}_{0}$, and such that each radius is horizontal. If $\gamma \in \Gamma_{\varepsilon}$ then $d\left(x_{0}, \gamma x_{0}\right)<\epsilon_{0}$, because $\epsilon<\epsilon(K)$. Therefore $B_{\gamma}=\gamma \tilde{B}\left(2 \epsilon_{0}\right) \cap D^{-1} B\left(\epsilon_{0}\right)$ is a disk mapped diffeomorphically by $D$ onto $\gamma B\left(2 \epsilon_{0}\right) \cap B\left(\epsilon_{0}\right)=B\left(\epsilon_{0}\right)$. Therefore $B_{\gamma}$ separates $D^{-1} B\left(\epsilon_{0}\right)=B\left(\epsilon_{0}\right) \times R$ into two cylinders. Note that, if $\gamma(1) \neq \gamma(2) \in \Gamma_{0}$, then $B_{\gamma^{(1)}} \cap B_{\gamma^{(2)}}=6$. Therefore the space between $B_{\gamma^{(1)}}$ and $B_{\left.\gamma^{2}\right)}$ in $D^{-1} B\left(\epsilon_{0}\right)$ is a relatively compact subset, which contains at most a finite number of translates of $\tilde{x}_{0}$ under $\Gamma_{6}$, since $\pi_{1}(M)$ acts properly discontinuously on $\tilde{\boldsymbol{M}}$. Since the set of translates is countable, the lemma follows.
2.4. Lemma. For any sufficiently small $\eta>0$, the group generated by $\Gamma_{\eta}$ is equal to $\Gamma=H_{0} \cap h\left(\pi_{1} M\right)$ and is dense in $H_{0}$ (See Theorem 2.1 for the definition of $H_{0}$.)
Proof. If $\eta$ is small enough, $U_{\boldsymbol{\eta}} \cap H=U_{\boldsymbol{\eta}} \cap H_{0}$. Therefore $\Gamma_{\eta}=U_{\boldsymbol{\eta}} \cap h\left(\pi_{1} M\right)$ is dense in $U_{\boldsymbol{\eta}} \cap H_{0}$. Now $U_{\boldsymbol{\eta}} \cap H_{0}$ generates $H_{0}$, since $H_{0}$ is connected. Hence, given $g \in H_{0}$, we can find a $k>0$ and $\gamma_{1}, \cdots, \gamma_{k} \in \Gamma_{\eta}$, such that $g\left(\gamma_{1} \cdots \gamma_{i}\right)^{-1} \in U_{\boldsymbol{\eta}}$. If $g \in \Gamma$, then $g\left(\gamma_{1} \cdots \gamma_{k}\right)^{-1} \in \Gamma_{\eta}$. This proves the result.

We can now prove Theorem 2.1. Let $K$ be any compact connected set in $X$ containing a ball of radius $\epsilon_{0}$. Let $U_{\text {a }}$ be an open neighbourhood of the identity in lsom $X$, such that $\epsilon<\epsilon(K)$,
where $\epsilon$ is small enough for 2.2.4 and 2.2.5 to be valid, whenever they are invoked in the rest of the proof.

We will prove by contradiction that all elements of $\Gamma_{\epsilon}^{+}$are in the centre of $\Gamma$. Having proved this, we will know by 2.2.5 that all elements of $\Gamma_{f}$ commute with each other. By Lemma 2.4, $\Gamma$ and hence $H_{0}$ will then be abelian. Let $\gamma \in \Gamma_{\dot{+}}^{+}$be the smallest element which is not in the centre of $\Gamma$. Since $U_{d}$ is open and $\gamma \in U_{d}$ there is a very small neighbourhood $U$ of the identity in lsom $K$, such that $U \subset U_{\mathrm{c}}, U=U^{-1}$ and $U \gamma \subseteq U_{\mathrm{c}}$. Let $\eta>0$ be small enough so that $U_{\boldsymbol{\eta}} \subset U$. By our choice of $\gamma$, and by Lemma 2.4, there is an element $a \in \Gamma_{\eta}$, such that $a \gamma^{-1} \neq \gamma$.

There are two possibilities: $\gamma<_{k} a \gamma \alpha^{-1}$ and $\left.a \gamma \alpha^{-1}\right\rangle_{k} \gamma$. In fact we may restrict to the second possibility, if we replace $a$ by $a^{-1}$. By 2.2.4, $\gamma>_{x}$ id implies that $a \gamma a^{-1} \nu_{k}$ id. By the definition of $\alpha$ this means that $\alpha \gamma \alpha^{-1}$ commutes with all elements of $\Gamma$. Therefore $\Gamma$ commutes with all elements of $\Gamma$. This contradiction shows that $H_{0}$ is abelian.

There are some general results which now apply. For example, one can prove that the closure of any leaf is a torus, and one can say a great deal about the foliation structure. For this we refer the reader to the articles by Carridre and Molino in these proceedings. We will discuss only the transversely hyperbolic situation, which is more special.
83. Abelian groups of isometries.
3.1. Lemma. Let $G$ be an abelian group of Euclidean isometries of affine Euclidean space of dimension $k$. Then we can choose an origin making the space into a vector space isomorphic to $R^{k}$, such that each $\phi \in G$ has the form $\phi(x)=T_{\phi} x+b_{\phi} T_{\phi} \in O(k), b_{\phi} \in R^{k}$ and $T_{\phi} b_{\phi}=b_{\phi}$. Moreover the union of all minimal $C$-invariant affine subspaces is

$$
M=\left\{x: T_{\phi} x=x \text { for all } \phi \in C\right\}
$$

and these subspaces are disjoint and have the same dimension.
Proof. We can write each $\phi$ in the form $\phi(x)=T_{\phi} x+b_{\phi}$. Suppose firat that each $T_{\phi}$ is the identity. Then the result is clear. So suppose that for some $\phi, T_{\phi} \neq i d$. Let $M_{1}=\left\{x: T_{\phi} x=x\right\}$ and let $\boldsymbol{M}_{2}$ be the orthogonal complement. Let $b_{p}=b_{1}+b_{2}$ with $b_{1} \in M_{1}$ and $b_{8} \in M_{2}$. We solve for $x_{\phi} \in M_{2}$, such that $T_{\phi} x_{p}=x_{\phi}-b_{2}$. Then $\phi\left(x+x_{\phi}\right)=T_{\phi} x^{+}+b_{z}+x_{\phi}$. Changing the origin to $x_{\phi}$, we obtain

$$
\phi(x)=T_{\phi} x+b_{1} \text { with } T_{\phi} b_{1}=b_{1}
$$

So $\phi$ induces an orthogonal transformation of $R^{k} / M_{1}$, which can be thought of as $T_{p} \mid M_{2}$. The only fixed point of $\phi$ acting on $R^{k} / M_{1}$ is the origin.

Any $\phi$-invariant affine subspace of $R^{k} / M_{1}$ must contain the origin, otherwise the nearest point to the origin would be fixed. Clearly, $M_{1}$ is the union of $\phi$-invariant affine subspaces which are either all of dimension zero or all of dimension one. Hence $\boldsymbol{M}_{1}$ is the union of all minimal $\phi$-invariant affine subspaces of $R^{k}$ and $\operatorname{dim} \boldsymbol{M}_{1}<\boldsymbol{k}$. Moreover $\boldsymbol{M}_{1}$ is $\boldsymbol{G}$-invariant.

The lemma now follows by induction on $k$, since every $G$-invariant subspace meets $M_{1}$, and hence every minimal $\boldsymbol{C}$-invariant affine subspace is contained in $\boldsymbol{M}_{\mathbf{1}}$.
3.2. Propoaition. Let $G$ be an abelian group of isometries of $H^{n}$ ( $n \geq 2$ ). Then all minimal $C$ invariant hyperbolic subspaces have the same dimension and they are disjoint. Their union $S$ is a hyperbolic subspace.
3.2.1. If the minimal invariant subspaces have dimension zero, then each element of $G$ is elliptic and contains $S$ in its fixed point set. We have $\operatorname{dim} S<n$.
3.2.2. If the minimal invariant subspaces have dimension one, then there is only one minimal invariant subspace. This case occurs if and only if $G$ contains a hyperbolic element $\phi$, and then $S$ is the axis of $\phi$. $C$ may contain elliptic elements, but it contains no parabolic elements.
3.2.3. If the minimal invariant subspaces have dimension at least two, then we can choose upper half space coordinates such that each $\phi \in G$ has the form $\phi(x)=T_{\phi} x+b_{\phi}$ where $T_{\phi} \in O(n-1), b_{\phi} \in R^{n-1}$ and $T_{\phi} b_{\phi}=b_{\phi}$. The space

$$
M=\left\{x \in \mathbb{R}^{n-1}: T_{\phi} x=x \text { for all } \phi \in C\right\}
$$

is an affine space which is the boundary of the hyperbolic subspace $S$. $G$ may contain elliptic elements $\left(b_{p}=0\right)$, but it contains no hyperbolic elements. At least one element of $C$ is parabolic.
Proof. Suppose there is an element $\phi \in G$, such that the union $Y$ of all minimal $\phi$-invariant hyperbolic subspaces is a hyperbolic subspace with $\operatorname{dim} Y<n . Y$ is clearly $G$-invariant. Any $G$-invariant subspace is $\phi$-invariant, and therefore meets $Y$. So any minimal $G$-invariant subspace must be contained in $Y$.

By induction, we may suppose that Proposition 3.2 holds for $G \mid Y$. If 3.2.1 or 3.2.2 apply to $C \mid Y$, they will apply to $G$ as well.

If 3.2.3 applies to $G \mid Y$, then $G$ contains no hyperbolic element, and it contains at least one parabolic element. Since a point at infinity in $\bar{Y}$ is fixed, we can choose an upper half space model so that every element $\psi \in C$ has the form $\psi(x)=T_{\psi} x+b_{\psi}$ with $T_{\psi} \in O(n-1)$ and $b_{v} \in R^{n-1}$. We can now apply Lemma 3.1. Since $G$ contains a parabolic element, any invariant hyperbolic subspace is a vertical halfplane. Case 3.2 .3 follows, provided a $\phi$ exists as in the first paragraph of this proof.

To complete the proof, we need to look at the case where, for every non-trivial isometry $\phi \in G$, the space $Y$, defined above, is the entire space. It follows that no element of the group is hyperbolic, no element is elliptic, and every parabolic element is a pure translation (see Lemma 3.1). This is case 3.2.3.

## 84. Proof of main theorem.

We suppose now that $M$ is a closed $n$-manifold with a transversely hyperbolic foliation whose leaves have dimension 1 . We have already dealt with the first case of the theorem, so we may assume that not every leaf is a circle. We have defined $D: \tilde{M}_{\boldsymbol{M}} \mathrm{H}^{\boldsymbol{n - 1}}$, the holonomy homomorphism $h: \pi_{1} M \rightarrow$ Isom $H^{n-1}$, the closure $H$ of $h\left(\pi_{1} M\right)$ and $H_{0}$, the component of the identity of $H$. By Theorem 2.1, we know that $H_{0}$ is abelian. By Proposition 1.14, we know that $H_{0}=\{\mathrm{id}\}$.
4.1. Lemma. The union of minimal $H_{0}$-invariant hyperbolic subspaces of $\mathbf{H}^{\boldsymbol{n - 1}}$ is equal to $\mathrm{H}^{\boldsymbol{n - 1}}$ and we have Case 3.2.3 of Proposition 3.2.

Proof. Let $S$ be the union of minimal $H_{0}$-invariant subspaces. It is invariant under $H$, since $H_{0}$ is a normal subgroup of $H$. If $S$ is not equal to $H^{\boldsymbol{n}-1}$. let $f(x)$ be the distance from $S$ to $x$. Then $f$ is an unbounded $H$-invariant function. In particular, it is $\pi_{1} M$-invariant. Hence $f \tilde{D}: \tilde{M} \rightarrow R$ is an unbounded $\pi_{1} \mathcal{M}$-invariant function. But this defines a continuous unbounded function on $M$, which is impossible. The lemma follows.
4.2. Lemma. $H_{0}$ consists of all translations of the upper halfspace - i.e. $H_{0} \cong \mathbb{R}^{n-2}$ and $H_{0}$ consists of all transformations of the form $x \rightarrow x+b\left(b \in R^{n-2}\right)$.
Proof. $H_{0}$ is connected and, by Proposition 3.2.3 and Lemma 4.1, consists of transformations of the form $x \rightarrow x+b$. Therefore $H_{0}$ consists of all transformations of the form $x \rightarrow x+b$, with $b \in V$, a vector subspace of $\mathrm{R}^{\boldsymbol{n}-2}$. We want to show that $V=\mathrm{R}^{\boldsymbol{n}-2}$. Since $H_{0}$ fixes a unique point at infinity, and $H_{0}$ is normal in $H$, every element of $H$ also preserves this point. Hence every element $\phi$ of $H$ has the form $x \rightarrow \lambda_{\phi} T_{\phi} x+c_{\phi}$ with $\lambda_{\phi}>0, T_{\phi} \in O(n-2), c_{\phi} \in R^{n-2}$. Moreover $V$ must be $T$-invariant. Since $\pi_{1} M \subseteq H$, we have a commutative diagram

|  |
| :---: |
| $\underset{\boldsymbol{M}}{\rightarrow} \mathrm{H}^{\mathbf{n - 1}}$ |
| $\boldsymbol{M} \rightarrow \mathrm{H}^{\boldsymbol{n}-1 / H}$ |

with $D$ surjective. It follows that $H^{\boldsymbol{n - 1}} / \boldsymbol{H}$ is compact. $H$ can not be a subgroup of the group $G$ of all Euclidean isometries of $\mathrm{R}^{n-2}$, since $\mathrm{H}^{n-1} / C \cong(0, \infty)$. Hence there must be an element $\phi \in H$, with $\lambda_{\phi}>1$. Such $a \phi$ is hyperbolic. We choose coordinates so that the axis of $\phi$ passes through the origin.

Let $H_{1}$ be the subgroup of $H$ consisting of $\psi$ such that $\lambda_{p}=1$. Clearly, $H_{1}$ is closed and normal in $H$ and is contained in the group of Euclidean isometries of $R^{n-2}$. Choose $x_{0}$ on the axis of $\phi$. Since $H_{0}$ is normal, the orbit of $x_{0}$ under $H$ consists of a discrete set of horizontal horospherical subspaces. The orbit of $x_{0}$ under $H_{1}$ consists of all such subspaces at the same Euclidean height as $x_{0}$. Let $x_{1} \in H_{1} x_{0}$ be a nearest point to $x_{0}$, not in $H_{0} x_{0}$, if such a point exists. Let $x_{1}=\psi x_{0}$ with $\psi \in H_{1}$. Now $\phi x_{0}=\lambda_{\phi} x_{0}$ and therefore

$$
d\left(x_{0 . \phi^{-1}} \psi \phi x_{0}\right)=d\left(\phi x_{\left.0, \psi \phi x_{0}\right)}=\frac{d\left(x_{0}, \psi x_{0}\right)}{\lambda_{\phi}}\right.
$$

by the definition of the hyperbolic metric in upper halfapace. By the definition of $\psi$, we then would have $\phi^{-1} \psi \phi x_{0}=x_{0}$, or $\psi \phi x_{0}=\phi x_{0}$. Since $\psi$ is a Euclidean isometry, this means that $\boldsymbol{v}_{\mathrm{x}}^{0}=x_{0}$ which is impossible. It follows that the $H_{1}$-orbit of $x_{0}$ is the same as the $H_{0}$-orbit.

$$
\text { Let } \psi_{1}(x)=\lambda_{1} T_{1} x+c_{1} \text { and } \psi_{2}(x)=\lambda_{2} T_{2} x+c_{2} \text { with } \psi_{1}, \psi_{2} \in H \text {. Then }
$$

$$
\begin{aligned}
{\left[\psi_{1}, \psi_{2}\right] } & =\psi_{1} \psi_{2} \psi_{1}^{-1} \psi_{2}^{-1}(x) \\
& =T_{1} T_{2} T_{1}^{-1} T_{2}^{-1}(x)-T_{1} T_{2} T_{1}^{-1}\left(c_{2}\right)-\lambda_{2} T_{1} T_{2} T_{1}^{-1}\left(c_{1}\right)+\lambda_{1} T_{1}\left(c_{2}\right)+c_{1}
\end{aligned}
$$

We take $\phi$ as above, $\lambda=\lambda_{\phi}>1, T=T_{\phi}, c_{\phi}=0$, and we define $\psi_{8}=\phi^{k}$, for some $k$. Then, since $T_{1}, T_{2} \in O(n-2)$ and $x_{0}$ lies above the origin, $T_{1} x_{0}=T_{2} x_{0}=x_{0}$. Also $c_{2}=0, T_{2}=T^{k}$ and $\lambda_{2}=\lambda^{k}$. Therefore

$$
\left[\psi_{1}, \psi_{2}\right]\left(x_{0}\right)=x_{0}-\lambda^{k} T_{1} T^{k} T_{1}^{-1} c_{1}+c_{1} .
$$

and $\left[\psi_{1}, \psi_{2}\right] \in H_{1}$. By taking $k$ large and negative, we see that $c_{1} \in V$. We have observed at the beginning of this proof that $T_{1}$ must preserve $V$. Since $\psi_{1} \in H$ is arbitrary, we see that, in terms of the action of $H$ on $\mathrm{R}^{\boldsymbol{n - 2}}, V$ is invariant under $H$. It follows that the hyperbolic subspace $S$ whose boundary is $V$, is invariant under $H$. As before, the distance from $S$ gives an unbounded function on $M$, and hence a contradiction, unless $V=R^{\boldsymbol{n - 2}}$. This proves the lemma.

We have a homomorphism $H \rightarrow R^{*}$, sending $\phi$ to $\lambda_{\phi}>0$. The image of this homomorphism is discrete, for suppose $\phi_{n} \in H, \phi_{n}(x)=\lambda_{n} T_{n} x+b_{n}$ and $\lambda_{n}$ converges through distinct values to 1 .

Since $V=R^{n-2}$, we may assume that $b_{n}=0$. We may also assume that $T_{n}$ converges to a limit $T$, since $O(n-2)$ is compact. Then $\phi_{n}$ converges to $\phi(x)=T x$ and $\phi \in H_{1}$. But this contradicts the fact that $H / H_{1}$ is discrete.

Let $\phi \in h\left(\pi_{1} M\right)$ be such that $\lambda=\lambda_{\phi}>1$ is minimal. Let $x_{0}$ be a point on the axis of $\phi$ and let $E_{t}$ be the horosphere at a hyperbolic distance $t$ above $x_{0}$. Then $\phi\left(E_{i v}\right)=E_{i+\log \lambda}$. We define

$$
f: \mathrm{H}^{n-1} \rightarrow S^{1}=\mathrm{R} / \mathrm{Z} \text { by } f(x)=t \log \lambda \text { if } x \in E_{t} .
$$

Then $f(\phi x)=f(x)+1$. Since $H_{0}$ and $H_{1}$ preserve each $E_{t}$. $f$ is $H$-invariant. We obtain a commutative diagram

| $\underset{\boldsymbol{M}}{ } \stackrel{D}{\rightarrow} \mathrm{H}^{\boldsymbol{n}-1}$ |
| :---: |
| $\downarrow$ \&f |
| $\boldsymbol{M}{ }^{\text {T }} S^{1}$. |

Since $D$ is a locally trivial flbre bundle, it is easy to see that $\pi$ is a locally trivial fibre bundle, whose fibre is equal to $R^{n-2} \times R$ modulo the action of $\Gamma_{1}=h^{-1}\left(H_{1}\right)$. Later we will show that $H_{1}=H_{0}$, so that $\Gamma_{0}=h^{-1}\left(H_{0}\right)=\Gamma_{1}$. We also write $\Gamma=\pi_{1} M$.

The following result is due to Fried [6].
4.4. Theorem. Let $M$ be a compact manifold, possibly with boundary, with an oriented 1 dimensional foliation. Let $p: \hat{M} \rightarrow M$ be an infinite cyclic covering such that the leaves of the induced foliation form the fibres of a smooth locally trivial flbre bundle with fibre a copy of $R$. Then there is a section of the fibre bundle which projects injectively to a section of the foliation on $M$.

The following result is now obvious.
4.5. Corollary. Under the hypotheses of Lemma 4.4, $M$ and its foliation are given by the mapping torus of a diffeomorphism of $B$ with itself, where $B$ is the quotient of $\hat{M}$ identifying each leaf to a point.

Let $R^{n-1}$ act on itself by left translation.
The author learnt of the following result, due to A.Verjovsky, by reading Carriere [1].
4.6. Theorem. (A.Verjovsky). Let $M$ be a closed manifold with a 1 -dimensional oriented foliation and a transverse ( $\mathrm{R}^{n-1}, \mathrm{R}^{n-1}$ )-structure. Suppose $\boldsymbol{M}$ has a dense leaf. Then one can impose a metric on $M$, which is adapted to the transverse structure as in the proof of Theorem 1.10, and in this metric $M$ is the flat torus and the foliation is linear.

Proof. We may suppose that $n>1$. We are suapending for the moment the hypothesis that the transverse structure is hyperbolic. Let $H$ and $H_{0}$ be defined as in 1.14. Then there is a commutative diagram

| $\tilde{M} \xrightarrow{D}$ | $\mathrm{R}^{n-1}$ |
| :--- | :--- |
| $\downarrow$ |  |
| $\dot{M}$ | $\rightarrow \mathrm{R}^{n-1} / \boldsymbol{H}$ |

such that every leaf in $M$ is mapped to a single point. Since there is a dense leaf, we see that $H=R^{n-1}=H_{0}$. >From Proposition 1.14 we know that $h: \pi_{1} M \rightarrow R^{n-1}$ is injective. Therefore $\pi_{1} M$ is free abelian. We choose a maximal set of generators whose images in $R^{n-1}$ are linearly independent over $R$. Since $h\left(\pi_{1} M\right)$ is dense, this set has exactly ( $n-1$ ) elements. Let $\Gamma_{1}$ be the
subgroup of $\pi_{1} M$ generated by these elements, and let $\tilde{\boldsymbol{M}}=\tilde{M} / \Gamma_{1}$ We may assume that $\pi_{1} M / \Gamma_{1}$ is torsionfree. We have a commutative diagram

 and $\pi_{1} M / \Gamma_{1}$ is a free abelian group acting as a group of covering translations of $\bar{M}$ with compact quotient. Therefore $\pi_{1} M / \Gamma_{1}$ has two ends and must be cyclic infinite. Thus Fried's Theorem (4.5) and Corollary 4.6 apply, and there is an embedding of $T^{n-1}$ in $M$, which is transverse to the foliation and consistent with the transverse Euclidean structure. It follows that, as a foliated manifold, $M$ is the mapping torus of a diffeomorphism $T^{n-1} \rightarrow T^{n-1}$, and this diffeomorphism is left translation by an element $\gamma$ of the group $T^{\boldsymbol{n - 1}}$. (The element $\gamma$ is a generator of the image of $\pi_{1} M / \Gamma_{1}$ in $R^{n-1} / \pi_{1} M_{1}$ under the holonomy homomorphism.)

It follows that $\boldsymbol{M}$ can be described as the quotient of $\mathbf{R}^{\boldsymbol{n}-1} \times \mathbf{R}$ by the group generated by $\Gamma_{1}$ and by $\left(-\gamma_{1}+1\right)$, where $+\gamma_{1}$ represents $\gamma \in R^{n-1} / \Gamma_{1}$. This proves Verjovsky's theorem. The transverse structure is given by projection onto $\mathbb{R}^{\boldsymbol{n}-1}$ in a direction parallel to $\left(-\gamma_{1}, 1\right)$.
4.7. Lemma. Let $T^{n}=R^{n} / Z^{n}$ be a torus foliated linearly by a dense line parallel to a non-zero vector $v \in \mathbb{R}^{n}$. The group of diffeomorphisms of $T^{n}$ respecting the foliation can be deformation retracted to the group of transformations of the form $x \rightarrow A x+b$, where $b \in T^{n}, A \in G L(n, Z)$ and $v$ is an eigenvector of $A$. The deformation $f_{t}$ of a diffeomorphism $f$ has the property that for any leaf $L, f_{t}(L)=f(L)$, for each time $t$.
Proof. The foliation represents a class in $H_{1}\left(T^{n} ; R\right)$, defined up to multiplication by a non-zero real number, and this homology class is an invariant of the foliation. This class was frst defined by Schwartzmann [10]. One takes a long piece of leaf and closes it up to a loop with a short path in $T^{\boldsymbol{n}}$. One then normalizes by dividing by the length of the loop. Finally, one takes the limit as the length tends to infinity. The class in $H_{1}\left(T^{n} ; R\right)$ is [ $v$ ], corresponding to $v \in R^{n}$ under the isomorphism $H_{1}\left(T^{n} ; R\right) \cong R^{n}$. Let $f: T^{n} \rightarrow T^{n}$ be a diffeomorphism respecting the foliation. Let $A \in G L(n, Z)$ be the $\operatorname{map} f_{*}: H_{1}\left(T^{n} ; Z\right) \rightarrow H_{1}\left(T^{n}: Z\right)$. Then $v$ is an eigenvector for $A$. Let $0 \in T^{n}$ be the identity element in the group $T^{n}=R^{n} /^{n}$. Let $f(0)=b$. Then $f$ is homotopic to $g$, defined by $g(x)=A x+b$, by a homotopy which keeps 0 at $b$ (but which may not respect the foliation). The diffeomorphism $h=f^{-1} g: T^{n} \rightarrow T^{n}$ preserves the foliation and the point 0 . Hence it sends the leaf through 0 to itself.

Consider the lifting of $h, \tilde{h}: \mathbb{R}^{\boldsymbol{n}} \rightarrow \mathrm{R}^{\boldsymbol{n}}$, such that $\tilde{h}(0)=0$. Then $\tilde{h} \mid Z^{n}$ is the identity. Hence every leaf through a point of $Z^{\boldsymbol{n}}$ is sent to itself. Since this set of leaves is dense, $\tilde{h}$ sends every leaf to itself. It follows that $f$ must preserve the transverse $R^{n-1}$ structure. (This result is a special case of a general result due to Molino [7,8]. However, Molino's method requires $f$ to be $C^{\infty}$, whereas here the method works even if $f$ is only a homeomorphism.)

Let $\tilde{g}, \tilde{f}: R^{n} \rightarrow R^{n}$ be liftings of $g, f$, such that $\tilde{f}(0)=\tilde{g}(0)$. Then for any leaf $L$ of $R^{n}$, $\tilde{g}(L)=\tilde{f}(L)$, as we have just seen. Since $g$ is homotopic to $f$, keeping 0 fixed, $\tilde{f}$ and $\tilde{g}$ will be equal on $\mathrm{Z}^{\boldsymbol{n}}$. Therefore either $\tilde{f}$ and $\tilde{g}$ both preserve the orientation of leaves, or $\tilde{f}$ and $\tilde{g}$ both reverse the orientation of leaves. Hence one can construct a linear homotopy from $\tilde{f}$ to $\tilde{g}$, and this homotopy will be $\mathbb{Z}^{\boldsymbol{n}}$-equivariant and will not move any leaf out of its image leaf. This completes the proof of the lemma.
4.8. Lemma. Let $f: T^{n} \rightarrow T^{n}$ preserve a linear foliation by dense lines, and suppose $f$ has finite order. Then $f$ induces the identity on $H_{1}\left(T^{n} ; Z\right)$. For some $b \in R^{n}$, we have a commutative diagram

$$
\begin{array}{ccc}
R^{n} & \stackrel{j}{\rightarrow} & R^{n} \\
D \downarrow & & \downarrow D \\
\mathbf{R}^{n-1} & +6 & \mathbf{R}^{n-1}
\end{array}
$$

where $D$ is the developing map.
Proof. Let $A \in G L(n, Z)$ be the map induced on $H_{1}\left(T^{n} ; Z\right)$. Then $A v=\lambda v$. where $v \in R^{n}$ is the direction of the foliation and $\lambda \in R$. Then $\lambda= \pm 1$. Let $R^{n}=V \oplus W$. where $V$ is the $\lambda$-eigenspace of $A$ and $W$ is an $A$-invariant complementary subspace. Since $\lambda$ is an integer, $V$ and $W$ can be defined over the rationals. In other words, we can find $v_{1}, \cdots, v_{k}, w_{1}, \cdots, w_{n-k} \in Z^{n}$, such that the $\left\{v_{i}\right\}$ form a basis for $V$ and the $\left\{w_{i}\right\}$ form a basis for $W$. But $v \in V$ and $v$ generates a line which is dense in $T^{n}$. Hence $\boldsymbol{W}=0$.

By the Lefachetz fixed point theorem, $\lambda=-1$ is impossible. This proves the result.
We can now go back to the transversely hyperbolic situation of the main theorem of this paper. We refer the reader to the definitions of $H_{0}$ and $H$ at the beginning of 84, to the definition of $H_{1}$ in the proof of Lemma 4.2, and to the definitions of $\Gamma_{0}, \Gamma_{1}$ and $\Gamma$ just before 4.4 . We recall that we have shown that $H$ consists of transformations of the form $x \rightarrow \lambda T x+b$ in the upper half space model, with $\lambda>0, T \in O(n-2)$ and $b \in R^{n-2}$, and that $H_{0}$ consists of all transformations of the form $x \rightarrow x+b$.
4.9. Lemma. $H_{0}=H_{1}$, and the fibre bundle $\pi: M \rightarrow S^{1}$ defined above has for its fibre a torus $T^{n-1}$. which is foliated linearly by dense lines. This foliation is locally constant.
Proof. We have the developing map $\bar{D}: \tilde{\boldsymbol{M}} \rightarrow \mathrm{H}^{\boldsymbol{n}}$. Let $\tilde{\boldsymbol{N}}$ be the inverse image in $\tilde{\boldsymbol{M}}$ of a horosphere in $\mathbf{H}^{\mathbf{n}}$, which is preserved by $\boldsymbol{H}_{0}$. Then the image $N$ of $\tilde{N}$ in $\boldsymbol{M}$ is a closed submanifold, namely a fibre of the fibre bundle $\pi: M \rightarrow S^{1}$ described above.

Let $\Gamma_{2}$ be the subgroup of $\Gamma_{0}$ of index at most two, preserving the orientation of the fibres of $D: \tilde{M} \rightarrow H^{n}$. Now $N=\tilde{N} / \Gamma_{1}$, and the covering with fundamental group $\Gamma_{2}$ has finite index. Now $\tilde{N} / \Gamma_{2}$ is a torus of dimension $(n-1)$ with a linear foliation by dense leavres. The group $\Gamma_{1} / \Gamma_{2}$ acts on this torus. By Lemma 4.8, the elements of $\Gamma_{1} \Gamma_{2}$ preserve the orientation of the foliation, and so $\Gamma_{0}=\Gamma_{2}$. According to Lemma 4.8, the elements of $\Gamma_{1} \Gamma_{0}$ are all translations. So this means that $\Gamma_{1}=\Gamma_{0}$.

We have now proved that the fibre bundle $M \rightarrow S^{1}$ has for its fibre a torus with a linear foliation having dense leaves. It follows that $\Gamma_{1} / \Gamma_{0} \tilde{\Xi}_{\underline{I}} H_{3} / H_{0}$ is cyclic infinite. However, we have not yet proved that the foliation is locally constant. This can be seen by improving Carriere and Verjovsky's theorem (4.6) to the situation where the transverse structure is an ( $R^{n-1}, R^{n-1} \times B$ )-structure, where $B$ is a ball on which $R^{n-1}$ acts trivially. We further suppose that the manifold is fibred by tori, one for each $x \in B$, and that each torus has a dense leaf. Going through the proof, simply multiplying by $B$ at appropriate points, we see that we have $B \times T^{n-1}$, where the foliation on $T^{n-1}$ is constant. An alternative approach is to follow Molino [7,8] (but then, as already remarked, one is limited to the $C^{\infty}$-case, whereas the above approach can be generalized).

Any fibre bundle $\pi: M \rightarrow S^{1}$ is determined by the monodromy, which is a diffeomorphism of the fibre to itself. In the situation under consideration, Lemma 4.7 shows that the monodromy diffeomorphism $\mu: T^{\boldsymbol{n - 1}} \rightarrow T^{\boldsymbol{n - 1}}$ can be chosen to be of the form $\mu(x)=A x+b$.

It follows that $\pi_{1} M \cong \Gamma$ is an extension of the free abelian group $\Gamma_{0}$ of rank ( $n-1$ ), by a cyclic infinite group, and that conjugation by a generator of the cyclic infinite group is equal to $A$. We consider $\Gamma_{0}$ and $\Gamma$ as groups of transformations of the upper halfspace of the form

$$
x \rightarrow \lambda T x+b\left(b \in \mathbb{R}^{n-2}, \lambda>0, T \in O(n-2)\right)
$$

Let $x \rightarrow \lambda_{0} T_{0} x$ be a generator in $\Gamma$ of the infinite cyclic group $H_{1} / H_{0}$, with $\lambda_{0}>1$. Then conjugation by this generator induces $\lambda_{0} T_{0}$ on $H_{0}$. We obtain a commutative diagram

$$
\begin{aligned}
& R^{n-1} \stackrel{u}{\rightarrow} \\
& A \downarrow \\
& R^{n-2} \\
& \downarrow \lambda_{0} T_{0} \\
& R^{n-1} \stackrel{u}{\rightarrow} R^{n-2}
\end{aligned}
$$

where $u$ is an $R$-linear surjection, induced by the holonomy homomorphism $h: \Gamma_{1}=Z^{n-1} \rightarrow R^{n-2}$. Hence $n-2$ of the eigenvalues of $A$ are equal to $\lambda_{0}$ in absolute value, since $A \in G L(n-1, Z)$, and the exceptional eigenvalue is $\mu= \pm \lambda_{0}^{-n+2}$.

The eigendirection for the exceptional eigenvector is $v$, the direction of the foliation, since $u: \mathrm{R}^{n-1} \rightarrow \mathrm{R}^{\boldsymbol{n - 2}}$ can be identified with the restriction of the developing map to the inverse image of a horizontal horosphere. We now claim that the characteristic polynomial of $A$ is irreducible over the integers. For suppose $f$ is a polynomial over the integers, and suppose the exceptional eigenvalue is a root of $f$. Then $f(A) v=0$. Since the foliation parallel to $v$ is dense, the induced map $f(A): T^{n-1} \rightarrow T^{n-1}$ is identically zero. Hence $f(A): R^{n-1} \rightarrow R^{n-1}$ is equal to a constant, which must also be zero. It follows that the minimum polynomial of $A$ is irreducible. Since the exceptional eigenvalue is a aimple root, the minimum polynomial is equal to the characteristic polynomial.
85. Algebraic number theory.

I would like to thank Simon Norton for the proof of the next theorem.
5.1. Theorem. Let $a_{0}+a_{1}+\cdots+a_{k} x^{k}$ be an irreducible polynomial with integral coefficients and roots $\alpha_{1}, \cdots, a_{k}$. Let $\left|\alpha_{1}\right|=\cdots\left|a_{k-1}\right| \neq\left|\alpha_{k}\right|$. Then $k \leq 3$.
Proof Suppose $k \geq 4$. Let $r=\left|\alpha_{1}\right|$. If $\alpha$ is a root, then so is $\bar{\alpha}$ and $|\alpha|=|\bar{\alpha}|$. Since $k \geq 4$, we may assume that $\bar{\alpha}_{1}$ and $\alpha_{1}$ are distinct roots. We may further assume that $\alpha_{2} \neq \bar{\alpha}_{1}$. It follows that $\bar{\alpha}_{2} \neq \alpha_{1}$. Futhermore, from the definition, $\alpha_{2} \neq \alpha_{1}$. We have the equation $\alpha_{1} \bar{\alpha}_{1}=\alpha_{2} \bar{\alpha}_{2}$. Let $\theta$ be an automorphism of the splitting field for the polynomial, taking $\alpha_{1}$ to $\alpha_{k}$. Then $\left|\theta a_{1}\right|=r$ for $1<i \leq k$, and, in particular, $\left|\theta a_{2}\right|=\left|\theta \sigma_{1}\right|=\left|\theta \sigma_{2}\right|=r$. We have

$$
\theta a_{1} \cdot \theta \bar{a}_{1}=\theta a_{2} \cdot \theta a_{2}
$$

and so $\left|\alpha_{k}\right| r=r^{2}$, which is a contradiction.
It follows from the concluding paragraph of 84 that $n-1 \leq 3$, which means $n \leqq 4$. To obtain examples for $n=3$ and $n=4$, we can take

$$
A=\left(\begin{array}{ll}
2 & 1 \\
1 & 1
\end{array}\right) \text { and } A=\left(\begin{array}{ccc}
0 & 0 & 1 \\
1 & 0 & -1 \\
0 & 1 & 0
\end{array}\right)
$$

In the second case, the characteristic equation is $\lambda^{3}+\lambda+1$, which has one real root $\mu$ and two complex roots $\lambda_{0} e^{-i 0}$ and $\lambda_{0} e^{i 0}$, with $\lambda_{0}>0$.

All examples of closed manifolds with transversely hyperbolic 1 -dimensional foliations can be described explicitly. We describe the 4-dimensional case with a notation that is consistent with the example just looked at, and leave to the reader the trivial task of decreasing appropriate integers by 1 for the 3 -dimensional case. Let $A \in G L(3, Z)$ have one real eigenvalue $\mu>1$ and two other eigenvalues of equal absolute value $\lambda_{0}<1$. (These will be complex conjugate in the transversely oriented case. In the transversely non-oriented case they are real with opposite signs. They can not be real with the same sign, since $A$ acts irreducibly, as we saw at the end of 84 .) Let $B=A^{2}$ if either $\mu<0$ or if the other two eigenvalues are real, equal and opposite in sign. Otherwise, let $B=A$. Let $G$ be the simply connected 4 -dimensional solvable Lie group, which is a split extenaion

$$
0 \rightarrow R^{S} \rightarrow C \rightarrow R \rightarrow 0
$$

where the element 1 in $R$ acts on $R^{3}$ via $B$. $G$ is diffeomorphic to $R^{4}$. Let $\Gamma$ be the split extension

$$
0 \rightarrow Z^{s} \rightarrow \Gamma \rightarrow Z \rightarrow 0
$$

where the generator of the quotient acts via $A$. Let $\Gamma_{0}$ (not the same $\Gamma_{0}$ as was defined previously) be the subgroup of index at most two, defined in the same way as $\Gamma$, but with $B$ acting instead of $A$. racts on $C$ through right multiplication by $A$ on the quotient copy of the reals ( $B$ is thought of as the number 1 , and $A$ as the number $1 / 2$ ), and by the action of $A$ as a matrix on $\mathbb{R}^{3}$. The action of $\Gamma_{0}$ on $C$ is by right translation, but not the action of $r$, aince $A$ is not in $C$. There is a surjective homomorphimm $G \rightarrow G_{1}$, obtained by taking the quotient of $R^{3}<C$ by the normal subgroup which is the $\mu$-eigendirection of $A$. Then $C_{1}$ is a aplit extension

$$
0 \rightarrow R^{2} \rightarrow G_{1} \rightarrow R \rightarrow 0
$$

and $G_{1}$ can be thought of as a simply transitive group of isometries of upper halfapace $H^{3}$, which keep 00 fixed. The subgroup $\mathrm{R}^{2}$ consiste of parabolic translations, and the element 1 of $R$ acts by a hyperbolic transformation, whose translation distance is $\log \lambda_{0}$ or $2 \log \lambda_{0}$. depending on whether $A=B$ or $A^{2}=B . G_{1}$ is diffeomorphic to $H^{3}$. The homomorphiam $G \rightarrow G_{1}$ is the developing map. The manifold $M$ is $G T$.

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