Annali della Scuola Normale Superiore di Pisa Classe di Scienze

ERIC BEDFORD

Stability of the polynomial hull of T^2

Annali della Scuola Normale Superiore di Pisa, Classe di Scienze $4^e\,$ série, tome $8, n^o\,2$ (1981), p. 311-315

http://www.numdam.org/item?id=ASNSP_1981_4_8_2_311_0

© Scuola Normale Superiore, Pisa, 1981, tous droits réservés.

L'accès aux archives de la revue « Annali della Scuola Normale Superiore di Pisa, Classe di Scienze » (http://www.sns.it/it/edizioni/riviste/annaliscienze/) implique l'accord avec les conditions générales d'utilisation (http://www.numdam.org/conditions). Toute utilisation commerciale ou impression systématique est constitutive d'une infraction pénale. Toute copie ou impression de ce fichier doit contenir la présente mention de copyright.



Article numérisé dans le cadre du programme Numérisation de documents anciens mathématiques http://www.numdam.org/

Stability of the Polynomial Hull of T^2 .

ERIC BEDFORD

1. - Introduction.

As is well known, the polynomial hull of the standard 2-torus $T^2 = \{(z_1, z_2) \in C^2 \colon |z_1| = |z_2| = 1\}$ is the closure of the unit polydisk $\Delta^2 = \{z \in C^2 \colon |z_1|, |z_2| < 1\}$. The existence of the hull is seen because the topological boundary of Δ^2 consists of two 1-parameter families of disks, namely $\partial \Delta \times \Delta$ and $\Delta \times \partial \Delta$, whose boundaries lie in T^2 . Alexander [1] has shown that under a small deformation of T^2 , there continue to exist two 1-parameter families of (deformed) disks, whose boundaries lie in the deformed torus. Here we extend that work somewhat and show that these deformed disks give exactly the polynomial hull. Our method is similar in spirit to that of [1]: we solve a functional equation that is analogous to the one used by Bishop [3] to construct disks near a «vanishing» disk. We also adopt the functional analysis approach to this problem developed by Hill and Taiani [5].

Given complex functions $\psi = (\psi_1, \psi_2) \in C^{m+3}(T^2)^2$, we may extend them to $(C \setminus \{0\})^2$ by making them constant in the variables $|z_1|$ and $|z_2|$. Let us define the map $\Psi = (C \setminus \{0\})^2 \to C^2$ by setting $\Psi = (\Psi_1, \Psi_2)$ with

(1)
$$\Psi_{i}(z) = z_{i}(1 + \psi_{i}(z)).$$

Let T_{φ}^2 denote the image of T^2 under Ψ .

We will prove that the polynomial hull of T^2 is stable in the following sense.

THEOREM. For m > 1 and $1 > \delta > 0$, there exists an $\varepsilon > 0$ such that if $\psi \in C^{m+3}(\mathbf{T}^2)^2$ and $\|\psi\|_{C^{m+3}} < \varepsilon$, then there exist

$$F_{_{m v}}^{(1)}=F^{(1)} \quad \ \ and \quad \ F_{_{m v}}^{(2)}=F^{(2)}\,, \quad \ F^{(1)}\colon \partialarDelta imes \overline{arDelta} o m{C}^{_2}\,, \quad \ F^{(2)}=\overline{arDelta} imes \partialarDelta o m{C}^{_2}$$

Pervenuto alla Redazione il 16 Maggio 1980.

21 - Ann. Scuola Norm. Sup. Pisa Cl. Sci.

312 ERIC BEDFORD

with the following properties:

- (2a) $||F^{(j)}(z)-z||_{C^m} < \delta$ (and thus F is a diffeomorphism) for j=1,2.
- (2b) $F^{(j)}$ is holomorphic in $\zeta \in \Delta$ for fixed $\tau \in \partial \Delta$, j = 1, 2.
- $(2c) F^{(1)}(\partial \Delta \times \partial \Delta) = F^{(2)}(\partial \Delta \times \partial \Delta) = T_w^2.$
- (2d) If Ω is the bounded component of $C^2 \setminus (F^{(1)}(\partial \Delta \times \overline{\Delta}) \cup F^{(2)}(\overline{\Delta} \times \partial \Delta))$, then $\overline{\Omega}$ is the polynomial hull of T_v^2 .

2. - Construction of disks.

It will be more convenient for us to use Ψ^{-1} rather than Ψ in (1). If $\|\psi\|_{C^1}$ is small, then Ψ gives a diffeomorphism between T^2 and T^2_{ψ} . If we write $z^* = \Psi(z)$, then there exists $\varphi \in C^{m+3}(T^2)^2$ such that $\Phi(z^*) = z$ for $z \in T^2$. For points $z^* \in T^2_{\psi}$, we may write φ as

$$arphi_{\scriptscriptstyle j}(z^*) = rac{-\,\psi_{\scriptscriptstyle j}(z)}{1\,+\,\psi_{\scriptscriptstyle j}(z)}\,.$$

Thus there is an open set $U \subset C^1(T^2)^2$ containing 0 such that we may define

$$S: U \cap C^{m+3}(T^2)^2 \to C^{m+2}(T^2)^2$$

given by $S(\psi) = \varphi$, where $\Phi|_{T_{\psi}^2} = \Psi^{-1}$. By Lemma 5.1 of [5] S is a mapping of class C^1 . We note also that at $\psi = 0$, the differential of this Banach space mapping is the negative of the identity i.e. $dS(0, \chi) = -\chi$.

Now let us consider a fixed mapping $G(\tau, \zeta) = (g_1, g_2) \in C^{m,\alpha}(\partial \Delta \times \overline{\Delta})^2$ such that G is holomorphic in $\zeta \in \Delta$. We assume also that $G(\partial \Delta \times \partial \Delta) \subset T_0^2$. For small ψ we wish to find $F_{\psi} \in C^{m,\alpha}(\partial \Delta \times \overline{\Delta})^2$ such that $F_{\psi}(\partial \Delta \times \partial \Delta) \subset T_{\psi}^2$, and $F_{\psi}(\tau, \zeta)$ is holomorphic in $\zeta \in \Delta$. With our notation, this means that we want

$$\Phi(F_{\psi}) \in \mathbf{T}_0.$$

Following [2], we write $F_{\psi} = (f_1, f_2)$ in «polar» coordinates as

$$f_i(\phi, \theta) = g_i(\phi, \theta) \exp{(I + i\Upsilon)\varrho_i(\phi, \theta)}$$

where $\tau = |\tau|e^{i\theta}$, $\zeta = |\zeta|e^{i\theta}$, and Υ denotes the harmonic conjugate operator acting in the ζ -variable. Thus for all functions ϱ_i , $(I + i\Upsilon)\varrho_i$ is holomorphic

in ζ . We let $C_{\mathbf{R}}^{m,\alpha}(\mathbf{T}^2)$ denote the real valued functions in $C^{m,\alpha}(\mathbf{T}^2)$. It is well known that Υ is a bounded operator from $C_{\mathbf{R}}^{m,\alpha}(\mathbf{T}^2)$ to itself for $0 < \alpha < 1$.

We consider the mapping

$$E \colon C^{m,\alpha}_{\boldsymbol{R}}(\boldsymbol{T}^2)^2 \times C^{3m+3}(\boldsymbol{T}^2)^2 \to C^{m,\alpha}_{\boldsymbol{R}}(\boldsymbol{T}^2)^2$$

given by

$$E_i(\varrho, \psi) = \log |\Phi_i(F_{\psi})| = \log |f_i(1 + \varphi_i(F_{\psi}))|$$

 \mathbf{or}

(4)
$$E_{i}(\varrho, \psi) = \varrho_{i} + \log|1 + \varphi_{i}(g \exp(I + i\Upsilon)\varrho)|.$$

Thus (3) is equivalent to

$$(5) E(\varrho, \psi) = 0.$$

It follows from Lemma 5.1 of [5] that E is a Banach space mapping of class C^1 . When $\psi = 0$, $\varphi = 0$, so $d_1E(d\varrho, 0) = d\varrho$. It follows by the implicit function theorem that for ψ near 0 in C^{m+3} there is a $\varrho_{\psi} \in C^{m,\alpha}$ solving (5), and the correspondence $\psi \to \varrho_{\psi}$ is continuous.

Proof of (2a), (2b), and (2c) of the Theorem.

Let us set $G: \partial \Delta \times \Delta \to \mathbb{C}^2$ equal to the identity mapping $G(\tau, \zeta) = (\tau, \zeta)$. By the argument above, we have $F_{\psi}^{(1)}: \partial \Delta \times \Delta \to \mathbb{C}^2$. To obtain $F_{\psi}^{(2)}: \Delta \times \partial \Delta \to \mathbb{C}^2$, we replace Y_{θ} in (4) by Y_{θ} , the conjugate operator in in the τ -variable. By the continuity of $\psi \to (F_{\psi}^{(1)}, F_{\psi}^{(2)})$, we have (2a). Now (2b) follows from the definition of f_j , and (2c) follows from (3).

3. - Polynomial hull.

We write $M_1=M_1(\psi)=F_{\psi}^{(2)}(\partial\Delta\times\Delta)$ and $M_2=M_2(\psi)=F_{\psi}^{(1)}(\Delta\times\partial\Delta)$. Since $\overline{M}_1(0)$ and $\overline{M}_2(0)$ intersect transversally at T_0^2 , it follows from (2a) and (2c) that $\overline{M}_1(\psi)$ and $\overline{M}_2(\psi)$ are transverse at T_{ψ}^2 . It follows from the transversality, then, that $\overline{M}_1(\psi)\cap\overline{M}_2(\psi)=T_{\psi}^2$. Thus $M_1(\psi)\cup M_2(\psi)\cup T_{\psi}^2$ is homeomorphic to S^3 , and it separates C^2 into two components. Let $\Omega(\psi)$ denote the bounded component of $C^2\setminus(\overline{M}_1(\psi)\cup\overline{M}_2(\psi))$. Clearly $M_1(\psi)$ and $M_2(\psi)$ are Levi flat surfaces, and thus they are pseudoconvex from both sides. It follows that $\overline{M}_1(\psi)\cup\overline{M}_j(\psi)$ is pseudoconvex from the « acute » side of the intersection, and so $\Omega(\psi)$ is pseudoconvex.

314 ERIC BEDFORD

In order to show that $\overline{\Omega(\psi)}$ is polynomially convex, we will construct a family $\{\Omega^t\}$ of pseudoconvex domains with the properties:

(6a)
$$\Omega^{0} = \Omega(\psi), \quad \bar{\Omega}(\psi) = \bigcap_{s>0} \Omega^{s}.$$

$$(6b) \hspace{3cm} \varOmega^s \subset \varOmega^t \quad \text{ if } s < t$$

(6c)
$$\bigcup_{s < t} \Omega^s = \Omega^t \quad \text{and} \quad \bigcup_{t > \infty} \Omega^t = C^2$$
(6d)
$$\inf \cap \Omega^s = \Omega^t$$

$$\inf_{s>t} \Omega^s = \Omega^t.$$

When the family $\{\Omega^t\}$ has been constructed, the polynomial convexity of $\bar{\Omega}^0$ will follow from the Docquier-Grauert Theorem [4].

To construct the domain Ω^t , we set

$$\psi_t = \psi + t$$

and

$$\tilde{\psi}_t = (1+t)^{-1} \psi .$$

Thus $\|\tilde{\psi}_t\|_{C^{2m+2}} \leq \|\psi\|_{C^{2m+3}}$ so by Section 2, we have a domain $\Omega(\tilde{\psi}_t)$ satisfying (2a), (2b), and (2c) of the Theorem. Now we set

$$\Omega^t = (1+t) \, \Omega(ilde{\psi}_t)$$
 .

In order to verify $(6 \ a-d)$ we need only verify (6b).

To show (6b) we look at the behavior of $M_1(\psi_s)$ as s increases. It will suffice to show that for t > s, |t - s| small, $F_t^{(1)} - F_s^{(1)}$ is transverse to $\overline{M}_1(\psi_s)$ and points outward.

Let us compute the differential $dE(\varrho, \psi; \chi_{\varrho}, \chi_{\psi})$ of E with respect to the variables ϱ and ψ in the directions χ_{ϱ} and χ_{ψ} , respectively. We find that $dF(\varrho; \chi_{\varrho}) = F(I + iY)\chi_{\varrho}$ and thus

(7)
$$dE_{j}(\varrho, \psi; \chi_{\varrho}, \chi_{\psi}) = \chi_{\varrho} + |1 + \varphi_{j}(F)|^{-1} \times \left[(1 + \operatorname{Re} \varphi_{j}(F)(\operatorname{Re} dS(\psi; \chi)(F) + \operatorname{Im} \varphi_{j}(F) \operatorname{Im} dS(\psi; \chi_{\psi})(F) + \nabla |1 + \varphi_{j}(F)| \cdot (F(I + iY)\chi_{\varrho}) \right]$$

where ∇ denotes the gradient of φ_j as a function on $\mathbb{R}^4 = \mathbb{C}^2$, and \cdot is the Euclidean inner product on \mathbb{R}^4 , where we have identified (a_1, b_1, a_2, b_2) with $(a_1 + ib_1, a_2 + ib_2)$.

Now let us set (7) equal to zero and consider the mapping $R: \chi_{\psi} \to \chi_{\ell}$. For $\psi = 0$, we have $\varphi = 0$ and $dS(0, \chi_{\psi}) = -\chi_{\psi}$; thus $\chi_{\ell} = \text{Re } \chi_{\psi}$. Now for $\varepsilon > 0$ small, we have $|\nabla \varphi| \| \Upsilon \| \ll 1$, and so R is a small perturbation of the real part operator. We wish to compare the sets

$$\Omega^s = (1+s) \Omega(\tilde{\psi}_s)$$

and

$$arOmega^t = (1+s)arOmega\Big(ilde{\psi}_s + rac{t-s}{1+s}\Big),$$

so we take

$$\chi_{oldsymbol{arphi}} = ilde{\psi}_s + rac{t-s}{1+s} - ilde{\psi}_s = rac{t-s}{1+s} \,.$$

Since R is a small perturbation of the identity operator it follows that $\chi_{\varrho} > 0$ when $\chi_{\psi} = (t - s)/(1 + s)$.

Thus to first order in χ_{ϱ} we have

$$egin{aligned} F^{(1)} - F_s^{(1)} &pprox au(\exp{(I+i\varUpsilon)}(arrho_s + \chi_{arrho}) - \exp{(I+i\varUpsilon)}arrho_s) \ &pprox au(\exp{(I+i\varUpsilon)}arrho_s((I+i\varUpsilon)\chi_{arrho}\,. \end{aligned}$$

When $\psi = 0$, the outward normal to $M_1 = \partial \Delta \times \Delta$ at (τ, ζ) is τ . Since $Y_{\chi_{\ell}}$ is bounded in terms of χ_{ℓ} and since $\chi_{\ell} > 0$, it follows that $|\text{Arg}(I + i\Upsilon)\chi_{\ell}| < \kappa < \pi/2$. Thus by (2a), $F_t^{(1)} - F_s^{(1)}$ is transverse to $M_1(\psi_s)$, and so (6b) holds, which completes the proof.

Remark added in proof. The polynomial convexity of $\overline{\Omega(\psi)}$ may also be seen because it is starshaped with respect to 0.

REFERENCES

- [1] H. ALEXANDER, Hulls of deformations in \mathbb{C}^n .
- [2] E. Bedford B. Gaveau, Envelopes of holomorphy of certain 2-spheres in \mathbb{C}^2 .
- [3] E. BISHOP, Differentiable manifolds in complex Euclidean space, Duke Math. J., 32 (1965), pp. 1-21.
- [4] F. Docquier H. Grauert, Levisches Problem and Rungescher Satz für Teilgebiete Steinscher Mannigfaltigkeiten, Math. Ann., 140 (1960), pp. 94-123
- [5] C. D. HILL G. TAIANI, Families of analytic disks in Cⁿ with boundaries in a prescribed CR manifold, Ann. Scuola Norm. Sup. Pisa, 5 (1978), pp. 327-380.

Princeton University, Department of Mathematics Fine Hall - Box 37 Princeton, New Jersey 08544