## UNIQUENESS AND STABILITY OF REGIONAL BLOW-UP IN A POROUS-MEDIUM EQUATION

## UNICITÉ ET STABILITÉ DE L'EXPLOSION RÉGIONALE DANS UNE ÉQUATION DES MILIEUX POREUX

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AbStract. - We study the blow-up phenomenon for the porous-medium equation in $\mathbf{R}^{N}$, $N \geqslant 1$,

$$
u_{t}=\Delta u^{m}+u^{m},
$$

$m>1$, for nonnegative, compactly supported initial data. A solution $u(x, t)$ to this problem blows-up at a finite time $\bar{T}>0$. Our main result asserts that there is a finite number of points $x_{1}, \ldots, x_{k} \in \mathbf{R}^{N}$, with $\left|x_{i}-x_{j}\right| \geqslant 2 R^{*}$ for $i \neq j$, such that

$$
\lim _{t \rightarrow \bar{T}}(\bar{T}-t)^{\frac{1}{m-1}} u(t, x)=\sum_{j=1}^{k} w_{*}\left(\left|x-x_{j}\right|\right)
$$

Here $w_{*}(|x|)$ is the unique nontrivial, nonnegative compactly supported, radially symmetric solution of the equation $\Delta w^{m}+w^{m}-\frac{1}{m-1} w=0$ in $\mathbf{R}^{N}$ and $R^{*}$ is the radius of its support. Moreover $u(x, t)$ remains uniformly bounded up to its blow-up time on compact subsets of $\mathbf{R}^{N} \backslash \bigcup_{j=1}^{k} \bar{B}\left(x_{j}, R^{*}\right)$. The question becomes reduced to that of proving that the $\omega$-limit set in the problem $v_{t}=\Delta v^{m}+v^{m}-\frac{1}{m-1} v$ consists of a single point when its initial condition is nonnegative and compactly supported.

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RÉSUMÉ. - Nous étudions le phénomène d'explosion pour l'équation des milieux poreux dans $\mathbf{R}^{N}, N \geqslant 1$,
$$
u_{t}=\Delta u^{m}+u^{m},
$$
$m>1$, pour une donnée initiale positive ou nulle, à support compact. Une solution $u(x, t)$ de ce problème explose en temps fini $\bar{T}>0$. Notre principal résultat établit qu'il existe un nombre fini de points $x_{1}, \ldots, x_{k} \in \mathbf{R}^{N}$, with $\left|x_{i}-x_{j}\right| \geqslant 2 R^{*}$ avec $i \neq j$, tels que
$$
\lim _{t \rightarrow \bar{T}}(\bar{T}-t)^{\frac{1}{m-1}} u(t, x)=\sum_{j=1}^{k} w_{*}\left(\left|x-x_{j}\right|\right)
$$

Ici $w_{*}(|x|)$ est l'unique solution non triviale, positive ou nulle, à support compact et à symétrie radiale de l'équation $\Delta w^{m}+w^{m}-\frac{1}{m-1} w=0$ dans $\mathbf{R}^{N}$ et $R^{*}$ est le rayon de son support. De plus, $u(x, t)$ reste uniformément bornée jusqu'à son temps d'explosion sur des sous-ensembles compacts de $\mathbf{R}^{N} \backslash \bigcup_{j=1}^{k} \bar{B}\left(x_{j}, R^{*}\right)$. La question est ramenée à la démonstration que l'ensemble $\omega$-limite du problème $v_{t}=\Delta v^{m}+v^{m}-\frac{1}{m-1} v$ est constitué d'un seul point quand sa donnée initiale est positive ou nulle et à support compact.
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## 1. Introduction

This paper deals with the description of the blow-up phenomenon in the porousmedium equation in $\mathbf{R}^{N}, N \geqslant 1$,

$$
\begin{align*}
& u_{t}=\Delta u^{m}+u^{m}  \tag{1.1}\\
& u(x, 0)=u_{0}(x) \tag{1.2}
\end{align*}
$$

where $m>1$ and $u_{0}(x)$ is a compactly supported, not identically zero nonnegative function whose regularity will be specified later. The porous-medium equation $u_{t}=\Delta u^{m}$ and its variations represent simple dissipative models for quantities which diffuse slowly. In fact this simple degenerate equation exhibits, unlike the heat equation, finite speed of propagation, which amounts in (1.1) to the fact that the support in space variable of the solution remains bounded at all times where the solution is defined. On the other hand, the presence of the superlinear term $u^{m}$ as a source makes possible finite time blowup, for instance the space-independent solution $(m-1)^{-\frac{1}{m-1}}(T-t)^{-\frac{1}{m-1}}$. Actually, the (unique) solution of (1.1)-(1.2) always blows-up in finite time. This is the case for any nonzero initial data in the more general problem

$$
\begin{equation*}
u_{t}=\Delta u^{m}+u^{p} \tag{1.3}
\end{equation*}
$$

as long as $1<p<m+\frac{2}{N}$, as established in [12], a generalization of the classical Fujita's result for $m=1$ [10]. The power $p=m$ is certainly special since diffusion and source share the same nonlinear growth. This gives rise to the interesting phenomenon
of regional blow-up, meaning this blow-up taking place only in a compact set with nonempty interior. This is in sharp contrast with phenomena typically exhibited for other powers in the source term: In fact, while for $p<m$ blow-up occurs in entire space, as established in [27], for $p>m$ blow-up is expected to occur only at a lower dimensional set, and generically only at isolated points. Fine knowledge is today available on the blow-up profiles of (1.3) when $m=1$ and $1<p<\frac{N+2}{N-2}$, a basic problem that has been the object of extensive study, see $[9,15,16,24,25,29]$ and the references therein. Of course if $m=p=1$ no blow-up occurs at all, so that the phenomenon here described seems quite characteristic of porous-media type equations.

The purpose of this paper is to describe completely the blow-up in (1.1)-(1.2) in the following sense: we show that for any initial condition the solution $u$ develops (exactly) a finite number of similar spherical hot spots: more precisely, there is a finite number of disjoint balls with common radii $R^{*}$ outside which the solution remains uniformly bounded, while inside each of them it develops a common self-similar radially symmetric profile $(\bar{T}-t)^{-\frac{1}{m-1}} w_{*}(r)$, where $r$ is the distance to the center of these balls and $w_{*}$ is a strictly positive function. Moreover, we show that one-ball blow-up is stable in the sense that for a given initial data leading to one-ball blow-up, all neighboring data exhibit the same phenomenon, with blow up taking place "approximately" in the same ball. While $k$-ball blow-up is in general unstable, it becomes stable within the class of initial data leading to blow-up with exactly $k$ balls.

The presence of regional blow-up in this equation was first observed and studied in the case $N=1$ in [11]. The elliptic problem found when searching by separation of variables a solution of the form

$$
u(x, t)=(\bar{T}-t)^{-\frac{1}{m-1}} \theta(x)
$$

has been studied for radial symmetry in [1-3,17].
This paper is a continuation of our previous work [4] where the following partial result was established: Let $\bar{T}>0$ be the time at which blow-up occurs. Let $t_{n}$ be any sequence $t_{n} \uparrow \bar{T}$. Then there is a subsequence of $t_{n}$ which we still denote $t_{n}$, and a nontrivial compactly supported solution $w(x)$ of the elliptic equation

$$
\begin{equation*}
\Delta w^{m}+w^{m}-\frac{1}{m-1} w=0 \tag{1.4}
\end{equation*}
$$

such that

$$
\left(\bar{T}-t_{n}\right)^{\frac{1}{m-1}} u\left(x, t_{n}\right) \rightarrow w(x)
$$

uniformly. On the other hand, it was established in [2] that the components of the support of $w$ are balls of the same radii and that the solution is radially symmetric inside each of them. This radially symmetric solution turns out to be unique, as established in [3]. Let $B U\left(u_{0}\right)$ be the set of blow-up points of $u$, namely the set of points $x$ for which there are sequences $x_{n} \rightarrow x$ and $t_{n} \rightarrow \bar{T}$ such that $u\left(x_{n}, t_{n}\right) \rightarrow+\infty$. It was also shown in [4] that this set is compact and it is precisely constituted by the union of the supports of all possible limiting $w$ 's. The important point unsolved in [4] was whether there is an actual unique blow-up profile, rather than oscillation between different limiting configurations.

The question turns out to be rather subtle, and we answer it affirmatively in the following result.

THEOREM 1.1. - Let $u(x, t)$ be the solution of (1.1)-(1.2), where $u_{0}(x)$ is compactly supported, continuous and such that $u_{0}^{m} \in H^{1}\left(\mathbf{R}^{N}\right)$. Let $\bar{T}>0$ be the blow-up time of this solution. Then there are points $x_{1}, \ldots, x_{k} \in \mathbf{R}^{N}$ such that

$$
\lim _{t \rightarrow \bar{T}}(\bar{T}-t)^{\frac{1}{m-1}} u(t, x)=\sum_{j=1}^{k} w_{*}\left(\left|x-x_{j}\right|\right)
$$

uniformly. Here $w_{*}(|x|)$ is the unique compactly supported, radially symmetric solution of (1.4). If $R^{*}$ is the radius of its support then we also have $\left|x_{i}-x_{j}\right| \geqslant 2 R^{*}$ for $i \neq j$. Moreover $u(x, t)$ remains uniformly bounded up to its blow-up time on compact subsets of $\mathbf{R}^{N} \backslash \bigcup_{j=1}^{k} \bar{B}\left(x_{j}, R^{*}\right)$. In other words,

$$
B U\left(u_{0}\right)=\bigcup_{j=1}^{k} \bar{B}\left(x_{j}, R^{*}\right)
$$

In light of this result, it is natural to ask for stability of the regional blow-up phenomenon. The one-ball blow-up turns out to be stable in the following sense.

THEOREM 1.2. - Assume that $u_{0}$ compactly supported, with support contained in $B(0, M)$, is such that $k=1$ in the above theorem, let us say

$$
B U\left(u_{0}\right)=\bar{B}\left(\bar{x}, R^{*}\right)
$$

Then, given $\varepsilon>0$, there exists a $\delta>0$ such that for any $u_{1}$ continuous, compactly supported in $B(0, M)$ which besides satisfies

$$
\left\|u_{0}^{m}-u_{1}^{m}\right\|_{H^{1}\left(\mathbf{R}^{N}\right)}<\delta
$$

we have that

$$
B U\left(u_{0}\right)=\bar{B}\left(\bar{x}_{1}, R^{*}\right),
$$

for some point $\bar{x}_{1}$ with $\left|\bar{x}-\bar{x}_{1}\right|<\varepsilon$.
In [4] it is established that the solution $u(x, t)$ is decreasing in the radial direction outside the smallest ball which contains the support of $u_{0}$. From here and the fact that $w_{*}$ is radially decreasing, it follows that a sufficient condition for one-ball blow-up to occur is that this support lies inside a ball of radius less than $R^{*}$.

Instead, the two-ball blow-up is not stable as the following example shows. Let us fix points $x_{1}$ and $x_{2}$ with $\left|x_{1}-x_{2}\right|>2 R^{*}$. Then the function

$$
u(x, t)=\left(\bar{T}_{1}-t\right)^{-\frac{1}{m-1}} w_{*}\left(\left|x-x_{1}\right|\right)+\left(\bar{T}_{2}-t\right)^{-\frac{1}{m-1}} w_{*}\left(\left|x-x_{2}\right|\right)
$$

solves Eq. (1.1) for $0<t<\min \left\{\bar{T}_{1}, \bar{T}_{2}\right\}$. If $\bar{T}_{1}=\bar{T}_{2}$, then two-ball blow-up takes place, which however disappears as soon as $\bar{T}_{1}$ and $\bar{T}_{2}$ differ, no matter how close they are.

This example suggests that one-ball blow-up may actually hold for "generic" initial data. $k$-ball blow-up is however stable within the class of initial data leading to blow-up in $k$ balls, class which may be conjectured to be a codimension $k-1$ manifold.

THEOREM 1.3. - Assume that $u_{0}$ is compactly supported in $B(0, M)$ and such that

$$
B U\left(u_{0}\right)=\bigcup_{i=1}^{k} \bar{B}\left(x_{i}, R^{*}\right)
$$

Let $u_{1}$ be another initial condition supported in $B(0, M)$, with

$$
B U\left(u_{1}\right)=\bigcup_{i=1}^{k} \bar{B}\left(x_{i}^{1}, R^{*}\right)
$$

Then, given $\varepsilon>0$, there exists $a \delta>0$ such that if $\left\|u_{0}^{m}-u_{1}^{m}\right\|_{H^{1}\left(\mathbf{R}^{N}\right)}<\delta$, then $\left|x_{i}-x_{i}^{1}\right|<$ $\varepsilon$ for all $i=1, \ldots, k$.

It is worthwhile mentioning the apparent analogy of this stability-unstability phenomenon with that for single and multiple-point blow-up in (1.3) for $m=1,1<p<\frac{N+2}{N-2}$, analyzed in the works [9,24,25].

Now that the blow-up set is fully characterized, further questions arise, for instance that of finding the exact behavior of the solution on the boundary of the balls determining the blow up. On the other hand, the solution remains bounded up to the blow-up instant outside these balls, so one may wonder whether the solution keeps evolving in some sense after blow-up occurs. The general question of "continuation after blow-up" has been treated for a class of related equations in [14].

Next we describe the proof of the above results. Let us introduce the change of variables

$$
\begin{equation*}
v(x, t)=\left.(\bar{T}-\tau)^{\frac{1}{m-1}} u(x, \tau)\right|_{\tau=\bar{T}\left(1-\mathrm{e}^{-t}\right)} . \tag{1.5}
\end{equation*}
$$

It is readily checked that $v$ satisfies the equation

$$
\begin{align*}
& v_{t}=\Delta v^{m}+v^{m}-\frac{1}{m-1} v  \tag{1.6}\\
& v(x, 0)=\bar{T}^{\frac{1}{m-1}} u_{0}(x) \tag{1.7}
\end{align*}
$$

From Proposition 4.1 in [4], we know that given a sequence $t_{n} \rightarrow+\infty$ there is a subsequence, which we denote in the same way, and a nontrivial, compactly supported solution of (1.4) so that

$$
v\left(x, t_{n}\right)^{m} \rightarrow w(x)^{m} \quad \text { as } n \rightarrow \infty,
$$

both in uniform and $H^{1}$-senses. Thus our task in establishing Theorem 1.1 is precisely to prove that the limit $w(x)$ is actually the same along every sequence $t_{n} \rightarrow+\infty$. A main feature of Eq. (1.6) is the presence of a Lyapunov functional for it, namely

$$
\begin{equation*}
J(z)=\frac{1}{2} \int\left(\left|\nabla z^{m}\right|^{2}-z^{2 m}\right) \mathrm{d} x+\frac{m}{m^{2}-1} \int z^{m+1} \mathrm{~d} x . \tag{1.8}
\end{equation*}
$$

In fact we have that the application $s \mapsto J(v(\cdot, t))$ is decreasing on $t>0$ and

$$
\lim _{t \rightarrow+\infty} J(v(\cdot, t))=J(w)
$$

Here and in what follows the integral symbol without limits specified means integration on the whole $\mathbf{R}^{N}$. The presence of this functional implies that limit points of the trajectory must be steady states. The problem of uniqueness of asymptotic limits in nonlinear heat equations under the presence of a Lyapunov functional has been analyzed in a number of works. A general result due to L. Simon [28] shows the uniqueness of the limit for uniformly parabolic equations in the case of uniform real analytic data on a compact manifold. Uniform analiticity cannot be lifted in general in this result, at least in the nonautonomous setting, as shown in [26]. Needless to say, the compactly supported setting we deal with makes our situation highly nonanalytic.

Other uniqueness results in parabolic problems, nondegenerate and degenerate, are contained in the works [5-8,13,19,18,22]. In the latter work, a renormalization method based on L. Simon's ideas, used in classifying singularities in an elliptic problem in [20] was adapted to a semilinear heat equation. The general framework of this method is what we will use here. Alternative methods for degenerate equations of porous-medium type, in one and higher dimensions, have been devised in [7,8]. Those techniques do not apply to the nonlinearity of Eq. (1.7), in particular those in [8], based on analiticity, because of the presence of compactly supported steady states. This is explicitly commented in [8] and posed as an open question.

A main technical difficulty arises when the support of the limit $w$ contains balls that are tangent, for this introduces a noise in the analysis which is rather delicate to get rid of.

In the next section we explain in further detail our method. In particular we derive the main results as corollaries of a more general fact, Theorem 2.1 whose proof is carried out by means of the renormalization approach mentioned above, whose basic scheme is set up by Proposition 2.1. The remaining sections of the paper are devoted to the proof of that intermediate result.

## 2. Proof of the main results

The theorems stated in the previous section will be direct consequences of the following result:

THEOREM 2.1. - Given numbers $M>0, K>0$, there exist numbers $T>0$ and $t^{*}>0$ such that given $\varepsilon>0$, there exists $a \delta>0$ with the following property: Let $v$ be any globally defined solution of $(1.7)$ in $[0, \infty)=$ such that

$$
\begin{align*}
& \operatorname{supp}(v(\cdot, 0)) \subset B(0, M)  \tag{2.1}\\
& \left\|v(\cdot, 0)^{m}\right\|_{L^{\infty}\left(\mathbf{R}^{N}\right)}+\left\|v(\cdot, 0)^{m}\right\|_{H^{1}\left(\mathbf{R}^{N}\right)} \leqslant K \tag{2.2}
\end{align*}
$$

and

$$
\lim _{t \rightarrow \infty} J(v(\cdot, t))=k J\left(w_{*}\right)
$$

Then the following holds: If $w$ is a compactly supported steady state of (1.7) such that for some $t_{0}>t^{*}$

$$
\left(\sup _{t_{0} \leqslant t<t_{0}+T} \int\left(v(x, t)^{m}-w(x)^{m}\right)(v(x, t)-w(x)) \mathrm{d} x\right)^{1 / 2}<\delta
$$

then

$$
\left.\left(\sup _{t_{0} \leqslant t<\infty} \int\left(v(x, t)^{m}-w(x)^{m}\right)(v(x, t)-w(x)) \mathrm{d} x\right)^{1 / 2}\right)^{1 / 2}<\varepsilon
$$

The proof of this result is based on the following
Proposition 2.1. - There exist positive numbers $T, \delta, C$ and $t^{*}$ with the following property. Let $v(x, t)$ be any solution of (1.7), defined in $0<t<\infty$ as in the statement of the above theorem. Consider points $x_{1}, \ldots, x_{k}$ and set

$$
w(x)=\left(\sum_{i=1}^{k} w_{*}\left(\left|x-x_{i}\right|\right)^{m}\right)^{1 / m}
$$

Assume that $t_{0}>t^{*}$ is such that

$$
\eta=\left(\sup _{t_{0} \leqslant t \leqslant t_{0}+T} \int\left(v(x, t)^{m}-w(x)^{m}\right)(v(x, t)-w(x)) \mathrm{d} x\right)^{1 / 2}<\delta
$$

Then there exist points $\bar{x}_{i}$ with $\left|\bar{x}_{i}-x_{i}\right| \leqslant C \eta$ such that

$$
\left(\sup _{t_{0}+T \leqslant t \leqslant t_{0}+2 T} \int\left(v(x, t)^{m}-\bar{w}(x)^{m}\right)(v(x, t)-\bar{w}(x)) \mathrm{d} x\right)^{1 / 2} \leqslant \frac{\eta}{2}
$$

where

$$
\bar{w}(x)=\left(\sum_{i=1}^{k} w_{*}\left(\left|x-\bar{x}_{i}\right|\right)^{m}\right)^{1 / m}
$$

Let us see how Theorem 2.1 follows from this assertion.
Proof of Theorem 2.1. - Let $\varepsilon$ be given and let us write $w$ as

$$
w(x)=\sum_{i=1}^{k} w_{*}\left(\left|x-x_{i}\right|\right)=\left(\sum_{i=1}^{k} w_{*}\left(\left|x-x_{i}\right|\right)^{m}\right)^{1 / m}
$$

for points $x_{i}$ with $\left|x_{i}-x_{j}\right| \geqslant 2 R^{*}$. Let $\delta_{0}<\delta$, with $\delta$ the number predicted by Proposition 2.1. Assume that for some $t_{0}$ we have

$$
\eta_{1} \equiv \sup _{t_{0} \leqslant t \leqslant t_{0}+T}\left(\int\left(v(x, t)^{m}-w(x)^{m}\right)(v(x, t)-w(x)) \mathrm{d} x\right)^{1 / 2}<\delta_{0}
$$

where $T$ is the number given by Proposition 2.1. We find then that there are points $x_{11}, \ldots, x_{k 1}$ with $\left|x_{i}-x_{i 1}\right| \leqslant C \eta_{1}$ such that

$$
\eta_{2} \equiv\left(\sup _{t \in\left[t_{0}+T, t_{0}+2 T\right]} \int\left(v(x, t)^{m}-w_{1}(x)^{m}\right)\left(v(x, t)-w_{1}(x)\right) \mathrm{d} x\right)^{1 / 2} \leqslant \frac{\eta_{1}}{2}
$$

where

$$
w_{1}(x)=\left(\sum_{i=1}^{k} w_{*}\left(\left|x-x_{i 1}\right|\right)^{m}\right)^{1 / m}
$$

Since $\eta_{2} \leqslant \eta_{1} / 2<\delta$, we can apply again Proposition 2.1 to find points $x_{i 2}$ with now $\left|x_{i 2}-x_{i 1}\right| \leqslant C \frac{\eta_{1}}{2}$ such that

$$
\eta_{3}=\left(\sup _{t \in\left[t_{0}+2 T, t_{0}+3 T\right]} \int\left(v(x, t)^{m}-w_{2}(x)^{m}\right)\left(v(x, t)-w_{2}(x)\right) \mathrm{d} x\right)^{1 / 2} \leqslant \frac{\eta_{2}}{2} \leqslant \frac{\eta_{1}}{4}
$$

where

$$
w_{2}(x)=\left(\sum_{i=1}^{k} w_{*}\left(\left|x-x_{i 2}\right|\right)^{m}\right)^{1 / m}
$$

Iterating this procedure we find a sequence $x_{i j}, j=1,2, \ldots$, such that $\left|x_{i j}-x_{i(j-1)}\right| \leqslant$ $C \frac{\eta}{2^{j}}$ and

$$
\left(\sup _{t \in\left[t_{0}+j T, t_{0}+(j+1) T\right]} \int_{\mathbf{R}^{N}}\left(v(x, t)^{m}-w_{j}(x)^{m}\right)\left(v(x, t)-w_{j}(x)\right) \mathrm{d} x\right)^{1 / 2} \leqslant \frac{\eta_{1}}{2^{j}}
$$

with $x_{i 0}=x_{i}$ and

$$
w_{j}(x)=\left(\sum_{i=1}^{k} w_{*}\left(\left|x-x_{i j}\right|\right)^{m}\right)^{1 / m}
$$

The following fact is easily checked: there exists a constant $D>0$ depending only on $m>1$ such that for all nonnegative numbers $a, b, c$ one has

$$
\left(a^{m}-c^{m}\right)(a-c) \leqslant D\left\{\left(a^{m}-b^{m}\right)(a-b)+\left(b^{m}-c^{m}\right)(b-c)\right\}
$$

Now let $t$ be any number greater than $t_{0}$. Then $t \in\left(t_{0}+j T, t_{0}+(j+1) T\right]$ for some $j$ and

$$
\begin{aligned}
g(t) \equiv & \int_{\mathbf{R}^{N}}\left(v(x, t)^{m}-w(x)^{m}\right)(v(x, t)-w(x)) \mathrm{d} x \\
\leqslant & D\left\{\sup _{\bar{t} \in\left[t_{0}+j T, t_{0}+(j+1) T\right]} \int\left(v(x, \bar{t})^{m}-w_{j}(x)^{m}\right)\left(v(x, \bar{t})-w_{j}(x)\right) \mathrm{d} x\right. \\
& \left.+\int\left(w(x)^{m}-w_{j}(x)^{m}\right)\left(w(x)-w_{j}(x)\right) \mathrm{d} x\right\}
\end{aligned}
$$

Now, we have that $w_{*}$ is uniformly Hölder continuous for any $m>1$, hence

$$
\left|\left(w(x)^{m}-w_{j}(x)^{m}\right)\left(w(x)-w_{j}(x)\right)\right| \leqslant C \max _{i}\left|x_{i j}-x_{i}\right|^{a}
$$

for some numbers $a, C>0$. It follows that

$$
g(t) \leqslant A\left\{\left(\frac{\eta_{1}}{2^{j}}\right)^{2}+\max _{i}\left|x_{i j}-x_{i}\right|^{a}\right\},
$$

for certain positive constants $A, a$. Finally,

$$
\left|x_{i j}-x_{i}\right| \leqslant C \sum_{l=1}^{\infty} \eta_{1} 2^{-l}=C \eta_{1}
$$

from where it follows that

$$
g(t) \leqslant A\left\{\left(\eta_{1}\right)^{2}+C^{a} \eta_{1}^{a}\right\}<A\left\{\delta_{0}^{2}+C^{a} \delta_{0}^{a}\right\}<\varepsilon
$$

provided that $\delta_{0}$ was chosen sufficiently small. This concludes the proof.
Proof of Theorem 1.1. - From Proposition 4.1 in [4], there is a sequence $t_{n} \rightarrow \infty$ such that $v\left(x, t_{n}+\tau\right) \rightarrow w(x)$ for some nontrivial solution of (1.4), uniformly in $x$ and for $\tau$ in bounded intervals. We recall that the space support of $v$ is contained inside a ball independent of the time variable. It follows that, given $\varepsilon>0$, there exists a number $t_{0}>0$ such that

$$
\eta_{1}=\left(\sup _{t \in\left[t_{0}, t_{0}+T\right]} \int\left(v(x, t)^{m}-w(x)^{m}\right)(v(x, t)-w(x)) \mathrm{d} x\right)^{1 / 2}<\delta,
$$

where $T$ and $\delta$ are the numbers given by Theorem 2.1. Thus,

$$
\left(\int\left(v(x, t)^{m}-w(x)^{m}\right)(v(x, t)-w(x)) \mathrm{d} x\right)^{1 / 2}<\varepsilon
$$

for all $t \geqslant t_{0}$. Since $\varepsilon$ is arbitrary, we have actually established that

$$
\lim _{t \rightarrow+\infty} \int\left(v(x, t)^{m}-w(x)^{m}\right)(v(x, t)-w(x)) \mathrm{d} x=0
$$

hence $w$ is the unique limit point of the trajectory $v(\cdot, t)$, and the proof of the theorem is complete.

Proof of Theorems 1.2 and 1.3. - Assume we are in the situation of Theorem 1.3 for the initial condition $u_{0}$. Let $u_{0 n}$ be a sequence of initial conditions such that $u_{0 n}^{m}$ converges uniformly and in $H^{1}$-sense to $u_{0}^{m}$, and with supports contained in some common ball. Let $\bar{T}_{n}$ be the blow-up time for $u_{n}$, the solution with initial condition $u_{0 n}$ and $\bar{T}$ that for $u_{0}$. We claim that $\bar{T}_{n} \rightarrow \bar{T}$. Let $T^{*}$ be a limit point for $\bar{T}_{n}$. After
scaling, we end up with the following situation: There is a globally defined solution $\tilde{v}$ of (1.7) with $\tilde{v}(0, x)=T^{*} u_{0}(x)$ which converges as $t \rightarrow \infty$ to a nontrivial steady state. But this implies, scaling back, that the blow-up time for $u$ cannot be other than $T^{*}$. Hence $T^{*}=\bar{T}$. Assume now additionally that $u_{n}$ as well as $u$ have $k$-ball blow-up for any $n$. Let $v_{n}$ be the solution of (1.7) defined as

$$
v_{n}(x, s)=\left.\left(\bar{T}_{n}-t\right)^{\frac{1}{m-1}} u_{n}(x, t)\right|_{t=\bar{T}_{n}\left(1-\mathrm{e}^{-s}\right)} .
$$

Then $J\left(v_{n}(\cdot, t)\right) \rightarrow k J\left(w_{*}\right)$ as $t \rightarrow \infty$. Since $\bar{T}_{n} \rightarrow \bar{T}$, we will have, on the one hand, $v(x, t)$ close to $w(x)$ for all $t>t_{0}$, while we can also make, by continuity, $v_{n}(x, t)$ as close as we wish in compact intervals in time to $v$. As a consequence, $v_{n}$ will also be close to $w$ in an interval of length $T$ after $t_{0}$, so that Theorem 2.1 applies in this situation as well, so proving the stated result. Finally, for Theorem 1.2 it suffices to observe that for $k=1$ in the above situation, and an arbitrary sequence of initial conditions converging to $u_{0}$, one has that if $J(v(\cdot, \bar{t}))<\frac{3}{2} J\left(w_{*}\right)$ then $J\left(v_{n}(\cdot, \bar{t})\right)<\frac{3}{2} J\left(w_{*}\right)$ for all sufficiently large $n$. It follows then that $J\left(v_{n}(\cdot, t)\right) \rightarrow J\left(w_{*}\right)$ as $t \rightarrow+\infty$, hence one-ball blow-up holds for any initial condition close to $u_{0}$ and Theorem 1.3 applies in this situation.

The remaining of this paper will be devoted to the proof of Proposition 2.1. To do this, we will restate it in the next section in a more convenient form.

## 3. Preliminaries and a key inequality

Our task in what follows is to prove Proposition 2.1. After an indirect argument, it is easy to see that this result follows from the following

Proposition 3.1. - There exist positive numbers $T$ and $C$ such that if $\tilde{v}_{n}$ is a sequence of solutions of Eq. (1.7) defined on $0 \leqslant t<+\infty$, satisfying the constraints (2.1), (2.2), and such that for some sequence $t_{n} \rightarrow+\infty$, setting

$$
\begin{gathered}
v_{n}(x, t) \equiv \tilde{v}_{n}\left(x, t_{n}+t\right) \\
w_{n}(x)=\left(\sum_{i} w_{*}\left(\left|x-x_{i n}\right|\right)^{m}\right)^{1 / m}
\end{gathered}
$$

one has

$$
\begin{equation*}
\eta_{n} \equiv\left(\sup _{t \in[0, T]} \int\left(v_{n}(x, t)^{m}-w_{n}(x)^{m}\right)\left(v_{n}(x, t)-w_{n}(x)\right) \mathrm{d} x\right)^{1 / 2} \rightarrow 0 \tag{3.1}
\end{equation*}
$$

as $n \rightarrow \infty$. Assume besides that for each $n$,

$$
\lim _{t \rightarrow \infty} J\left(v_{n}(\cdot, t)\right)=k J\left(w_{*}\right)
$$

where $J$ is the Lyapunov functional (1.8). Then there exist points $\bar{x}_{i n}$ with $\left|\bar{x}_{i n}-x_{i n}\right| \leqslant$ $C \eta_{n}$ and

$$
\begin{equation*}
\left(\sup _{t \in[T, 2 T]} \int\left(v_{n}(x, t)^{m}-\bar{w}_{n}(x)^{m}\right)\left(v_{n}(x, t)-\bar{w}_{n}(x)\right) \mathrm{d} x\right)^{1 / 2} \leqslant \frac{\eta_{n}}{2} \tag{3.2}
\end{equation*}
$$

for all $n$ sufficiently large, and where

$$
\bar{w}_{n}(x)=\left(\sum_{i} w_{*}\left(\left|x-\bar{x}_{i n}\right|\right)^{m}\right)^{1 / m}
$$

Let $v_{n}$ be a sequence as in the statement of the above result. Then we have that $v_{n}(x, t)^{m}-w_{n}(x)^{m} \rightarrow 0$ in $L^{\infty}$ and $H^{1}$-senses in $\mathbf{R}^{N}$, uniformly locally in time $t \in$ $[0, \infty)$. In fact, the estimates leading to convergence up to subsequences to steady states derived in [4] depend only on bounds for the initial condition and on the radius of the smallest ball containing the initial condition (in fact the size support of the solution at all times turns out to depend only on this radius). For $T>0$ fixed, which we will choose later, we use in what follows the following notation:

$$
\begin{equation*}
\phi_{n}(x, t) \equiv \frac{v_{n}(x, t)-w_{n}(x)}{\eta_{n}} \tag{3.3}
\end{equation*}
$$

Then $\phi_{n}$ satisfies the equation

$$
\begin{equation*}
\frac{\partial \phi_{n}}{\partial t}=m \Delta\left(\tilde{w}_{n}^{m-1} \phi_{n}\right)+m \tilde{w}_{n}^{m-1} \phi_{n}-\frac{1}{m-1} \phi_{n}+\eta_{n}^{-1} z_{n} \tag{3.4}
\end{equation*}
$$

where

$$
\begin{equation*}
\tilde{w}_{n}(x, t)^{m-1} \equiv \int_{0}^{1}\left(w_{n}(x)+t\left(v_{n}(x, t)-w_{n}(x)\right)\right)^{m-1} \mathrm{~d} t \tag{3.5}
\end{equation*}
$$

and

$$
z_{n}(x)=\sum_{i} w_{*}\left(\left|x-x_{i n}\right|\right)-w_{n}(x)
$$

Let us observe that, by definition of the number $\eta_{n}$ we have that

$$
\left(m \int w_{n}(x, t)^{m-1} \phi_{n}(x, t)^{2} \mathrm{~d} x\right)^{1 / 2} \leqslant 1
$$

for all $t \in[0, T]$. Notice also that $z_{n}$ is supported only near the boundary of the balls. Indeed, in the limit $w_{n}$ must converge (up to subsequences) to a steady state $w$ of Eq. (1.4), hence the distance between the centers $x_{i n}$ must be in the limit no less than $2 R^{*}$.

These facts suggest that on interior sets of the support of the limit $w(x)$ of the $w_{n}$, which is the uniform limit of $w_{n}$, we should see convergence in certain sense of $\phi_{n}$ to a
solution of the degenerate parabolic equation

$$
\begin{equation*}
(\phi)_{t}=m \Delta\left(w^{m-1} \phi\right)+m w^{m-1} \phi-\frac{1}{m-1} \phi \tag{3.6}
\end{equation*}
$$

The proof of Proposition 2.2 has as its key element the analysis of this convergence, and in particular in finding the form of its limit. Thus we assume in what follows the validity of the conditions of Proposition 2.2. We introduce some notation, and establish in Lemma 3.1 below an inequality which will play a crucial role in the analysis of the next sections. Following the notation of the previous section we write $w_{i n}=w_{*}\left(\left|x-x_{i n}\right|\right)$, so that $w_{n}=\left(\sum_{i=1}^{k} w_{i n}^{m}\right)^{1 / m}$. Let us also consider the functions

$$
\begin{gather*}
\psi_{n}=\frac{v_{n}^{m}-w_{n}^{m}}{\eta_{n}},  \tag{3.7}\\
G_{n}=\frac{1}{\eta_{n}^{2}}\left\{\frac{v_{n}^{m+1}}{m+1}-\frac{w_{n}^{m+1}}{m+1}-w_{n}^{m}\left(v_{n}-w\right)\right\},  \tag{3.8}\\
H_{n}=\frac{(m-1)\left(v_{n}^{m+1}-w_{n}^{m+1}\right)+(m+1)\left(v_{n} w_{n}^{m}-v_{n}^{m} w_{n}\right)}{\eta_{n}^{2}} . \tag{3.9}
\end{gather*}
$$

It is easily checked the existence of constants $C_{1}$ and $C_{2}$, depending only on $m$ such that the following inequalities hold:

$$
\begin{equation*}
C_{1} G_{n} \leqslant \frac{\left(v_{n}^{m}-w_{n}^{m}\right)\left(v_{n}-w_{n}\right)}{\eta_{n}^{2}} \leqslant C_{2} G_{n} \tag{3.10}
\end{equation*}
$$

We observe that the already defined quantity

$$
\begin{equation*}
z_{n}=\sum_{i=1}^{k} w_{i n}-w_{n} \tag{3.11}
\end{equation*}
$$

measures the "overlap" of the supports of the $w_{i n}$.
We also note that there exists a constant $C>0$, depending on $k$ and $m$, such that

$$
\begin{equation*}
w_{n} \leqslant \sum_{i=1}^{k} w_{i n} \leqslant C w_{n} \tag{3.12}
\end{equation*}
$$

In particular $0 \leqslant z_{n} \leqslant C w_{n}$ for another constant $C$.
The following relation among the above defined objects may be regarded as the key step in the proof of Proposition 2.2.

Lemma 3.1. - The following relation holds:

$$
\frac{1}{(m-1) \eta_{n}^{2}} \int\left(v_{n}^{m}-w_{n}^{m}\right) z_{n} \leqslant-\int \frac{\partial}{\partial t} G_{n}+\frac{1}{m^{2}-1} \int H_{n}-\frac{m}{\left(m^{2}-1\right) \eta_{n}^{2}} \int w_{n}^{m} z_{n}
$$

Proof. - Let $J$ be the Lyapunov functional for (1.6) given by (1.8). Let us set

$$
I=2\left(J\left(v_{n}\right)-\sum_{i=1}^{k} J\left(w_{i n}\right)\right)
$$

Then $I \geqslant 0$ and we have

$$
\begin{aligned}
I= & \int\left(\left|\nabla v_{n}^{m}\right|^{2}-\left|\nabla\left(w_{n}^{m}\right)\right|^{2}\right)-\int\left(v_{n}^{2 m}-w_{n}^{2 m}\right) \\
& +\frac{2 m}{m^{2}-1} \int\left(v_{n}^{m+1}-\sum_{i=1}^{k} w_{i n}^{m+1}\right)+\int\left(\sum_{i \neq j} \nabla w_{i n} \cdot \nabla w_{j n}\right)-\sum_{i \neq j} w_{i n}^{m} w_{j n}^{m}
\end{aligned}
$$

After integrating by parts and using the equations we get

$$
\begin{aligned}
I= & -\int\left(\Delta v_{n}^{m}+\Delta w_{n}^{m}\right)\left(v_{n}^{m}-w_{n}^{m}\right)-\int\left(v_{n}^{2 m}-w_{n}^{2 m}\right) \\
& +\frac{2 m}{m^{2}-1} \int\left(v_{n}^{m+1}-\sum_{i=1}^{k} w_{i n}^{m+1}\right)-\frac{1}{m-1} \int \sum_{i \neq j} w_{i n}^{m} w_{j n} .
\end{aligned}
$$

Thus

$$
\begin{aligned}
I= & -\int v_{n t}\left(v_{n}^{m}-w_{n}^{m}\right)-\frac{1}{m-1} \int\left(v_{n}+\sum_{i=1}^{k} w_{i n}\right)\left(v_{n}^{m}-w_{n}^{m}\right) \\
& -\frac{1}{m-1} \int \sum_{i \neq j} w_{i}^{m} w_{j}+\frac{2 m}{m^{2}-1} \int\left(v_{n}^{m+1}-\sum_{i=1}^{k} w_{i n}^{m+1}\right) .
\end{aligned}
$$

So we obtain, after recalling that $\eta_{n}^{2} \frac{\partial G_{n}}{\partial t}=v_{n t}\left(v_{n}^{m}-w_{n}^{m}\right)$,

$$
I=-\eta_{n}^{2} \frac{\partial G_{n}}{\partial t}+\frac{1}{m-1} \int\left(v_{n} w_{n}^{m}-v_{n}^{m} \sum_{i=1}^{k} w_{i n}\right)+\frac{1}{m+1} \int\left(v_{n}^{m+1}-\sum_{i=1}^{k} w_{i n}^{m+1}\right)
$$

Since the functional $J$ is nonincreasing along trajectories we obtain, after some algebraic manipulations and recalling the definition of $H_{n}$ and $z_{n}$, that

$$
\begin{aligned}
0 \leqslant & -\frac{\partial G_{n}}{\partial t}+\frac{1}{m^{2}-1} \int H_{n}+\frac{1}{\eta_{n}^{2}} \int \frac{w_{n}^{m+1}-\left(\sum_{i=1}^{k} w_{i n}^{m+1}\right)}{m+1} \\
& -\frac{1}{m-1} \frac{1}{\eta_{n}^{2}} \int\left(v_{n}^{m}-w_{n}^{m}\right)\left(\sum_{i=1}^{k} w_{i n}-w_{n}\right)-\frac{1}{m-1} \int w_{n}^{m} \frac{z_{n}}{\eta_{n}^{2}}
\end{aligned}
$$

It follows from Lemma A.1, in the appendix, that

$$
\begin{equation*}
\left(w_{n}^{m+1}-\sum_{i=1}^{k} w_{i n}^{m+1}\right) \leqslant \frac{1}{m-1}\left(w_{n}^{m} z_{n}\right) \tag{3.13}
\end{equation*}
$$

Hence

$$
\begin{aligned}
0 \leqslant & -\frac{\partial G_{n}}{\partial t}+\frac{1}{m^{2}-1} \int H_{n} \\
& -\frac{1}{m-1} \frac{1}{\eta_{n}^{2}} \int\left(v_{n}^{m}-w_{n}^{m}\right)\left(\sum_{i=1}^{k} w_{i n}-w_{n}\right)-\frac{m}{m^{2}-1} \int w_{n}^{m} \frac{z_{n}}{\eta_{n}^{2}}
\end{aligned}
$$

which yields the desired result.
The result just proven plays an essential role in the analysis to follow in the next sections. In Section 4 we will obtain estimates which will lead in particular to convergence of $\phi_{n}$ in a suitable sense in Section 5. An important step is to obtain a proper control on the size of $\eta_{n}^{-1} z_{n}$, which is measuring the degree of superposition of the balls constituting the support of $w_{n}$. In Section 6 we will express the limit $\phi$ of the $\phi_{n}$ 's in terms of eigenvalues and eigenfunctions of the elliptic operator in Eq. (3.6). The fact that the operator does not degenerate in the interior of the support of $w$ yields strong smooth convergence there. However a finer understanding of the behavior of $\phi_{n}$ near the boundary of the support of $w$ is needed, and found in Section 7.

It should be remarked that a particularly delicate situation is the case that $w$ has adjacent balls in their support, since the effect of superposition is in fact present up to the limit, and that has to been taken care of. This is perhaps the main difficulty overcame in this paper.

## 4. Further estimates

In this section we establish, as consequences of Lemma 3.1, some important estimates which will lead in particular to convergence of $\phi_{n}$ in a suitable sense. Our first result provides a uniform control on the overlap of the supports of the $w_{i n}$ by means of the following estimate for $z_{n}$.

LEmmA 4.1. - There is a $C>0$ such that for all $n$ we have

$$
\begin{equation*}
\eta_{n}^{-2} \int w_{n}^{m} z_{n} \leqslant C \tag{4.1}
\end{equation*}
$$

Proof. - Integrating in time from 0 to $T$ the inequality of Lemma 3.1 we obtain

$$
\begin{aligned}
0 \leqslant & \int\left(G_{n}(x, 0)-G_{n}(x, T)\right)+\int_{0}^{T} \int H_{n} \\
& -\frac{1}{m-1} \frac{1}{\eta_{n}^{2}} \int_{0}^{T} \int\left(v_{n}^{m}-w_{n}^{m}\right)\left(\sum_{i=1}^{k} w_{i n}-w_{n}\right)-\frac{m}{m^{2}-1} \int_{0}^{T} \int w_{n}^{m} \frac{z_{n}}{\eta_{n}^{2}}
\end{aligned}
$$

Recalling now that, $\int G_{n}(x, t) \leqslant C$ for all $0 \leqslant t \leqslant T$ and that $H_{n} \leqslant C G_{n}$, we obtain

$$
\frac{m}{m^{2}-1} \int_{0}^{T} \int w_{n}^{m} \frac{z_{n}}{\eta_{n}^{2}} \leqslant C-\frac{1}{m-1} \frac{1}{\eta_{n}^{2}} \int_{0}^{T} \int\left(v_{n}^{m}-w_{n}^{m}\right)\left(\sum_{i=1}^{k} w_{i n}-w_{n}\right)
$$

where the constant $C$ depends now also in $T$. On the other hand,

$$
\frac{1}{\eta_{n}^{2}} \int_{0}^{T} \int\left(v_{n}^{m}-w_{n}^{m}\right)\left(\sum_{i=1}^{k} w_{i n}-w_{n}\right) \geqslant I
$$

where

$$
I=\frac{1}{\eta_{n}^{2}} \int_{0}^{T} \int_{\left\{x \mid v_{n}(x)<\sum_{i=1}^{k} w_{i n}(x)\right\}}\left(v_{n}^{m}-w_{n}^{m}\right)\left(\sum_{i=1}^{k} w_{i n}-w_{n}\right)
$$

Now, using (3.10) and (3.12), after an application of the mean value theorem we get

$$
\begin{aligned}
|I| & \leqslant\left|\int_{0}^{T} \int \frac{\left(v_{n}^{m}-w_{n}^{m}\right)}{\eta_{n}^{2}}\left(v_{n}-w_{n}\right)\right|^{1 / 2}\left|\int_{0}^{T} \int_{\left\{x \mid v(x)<\sum_{i=1}^{k} w_{i n}(x)\right\}} \frac{\left(v_{n}^{m}-w_{n}^{m}\right)}{\left(v-w_{n}\right)} \frac{z_{n}^{2}}{\eta_{n}^{2}}\right|^{1 / 2} \\
& \leqslant C\left|\int_{0}^{T} \int_{\left\{x \mid v(x)<\sum_{i=1}^{k} w_{i n}(x)\right\}} m w_{n}^{m-1} \frac{z_{n}^{2}}{\eta_{n}^{2}}\right|^{1 / 2} \leqslant C\left|\int w_{n}^{m} \frac{z_{n}}{\eta_{n}^{2}}\right|^{1 / 2}
\end{aligned}
$$

Hence

$$
\frac{m}{m^{2}-1} \eta_{n}^{-2} \int w_{n}^{2} z_{n} \leqslant C+C\left|\int_{0}^{T} \int w_{n}^{m} \frac{z_{n}}{\eta_{n}^{2}}\right|^{1 / 2}
$$

From here the proposition immediately follows.
Examining the above proof, now applied integrating between 0 and any $t>0$, and using the result just proved we see that we have actually established the following bound.

Corollary 4.1. - We have that there is a constant $C$ such that for all $t>0$ one has

$$
\begin{align*}
0 \leqslant & \int\left(G_{n}(x, 0)-G_{n}(x, t)\right) \\
& +\frac{1}{m^{2}-1} \int_{0}^{t} \int H_{n}+C \int_{0}^{t}\left(\int G_{n}(x, s) \mathrm{d} x\right)^{1 / 2} \mathrm{~d} s+C t+C \tag{4.2}
\end{align*}
$$

As a further consequence, we see that since $\int G_{n}(x, 0) \leqslant C$, and as we have said, $\left|H_{n}\right| \leqslant C G_{n}$, the following fact holds.

Corollary 4.2. - There are constants $a, b>0$ such that for all $n, t$,

$$
\begin{equation*}
\int G_{n}(x, t) \leqslant b \mathrm{e}^{a t} \tag{4.3}
\end{equation*}
$$

## 5. Convergence

We will use here the results of the previous section to establish convergence of the quantities $\psi_{n}$ and $\phi_{n}$ in the appropriate sense. Let us note that $\psi_{n}$ defined by (3.7)
satisfies the equation

$$
\begin{equation*}
\left(\phi_{n}\right)_{t}=\Delta \psi_{n}+\psi_{n}-\frac{1}{m-1} \phi_{n}+\frac{z_{n}}{(m-1) \eta_{n}} \tag{5.1}
\end{equation*}
$$

Integrating (5.1) against $\psi_{n}$, recalling that $\frac{\partial}{\partial t} G_{n}=\psi_{n} \frac{\partial \phi_{n}}{\partial t}$, we obtain

$$
\begin{align*}
\frac{\partial}{\partial t} \int G_{n} \mathrm{~d} x & =\int \frac{\partial \phi_{n}}{\partial t} \psi_{n} \mathrm{~d} x \\
& =-\int\left|\nabla \psi_{n}\right|^{2} \mathrm{~d} x+\int \psi_{n}^{2}-\frac{1}{m-1} \int \phi_{n} \psi_{n}+\frac{1}{m-1} \int \frac{z_{n}}{\eta_{n}} \psi_{n} \tag{5.2}
\end{align*}
$$

LEmmA 5.1. - There exists a constant $C>0$ such that

$$
\int \frac{z_{n}}{\eta_{n}} \psi_{n}-\int \phi_{n} \psi_{n} \leqslant C
$$

Proof. - We have

$$
\begin{aligned}
\int \frac{z_{n}}{\eta_{n}} \psi_{n} & =\int_{\left\{x / z_{n}(x) \leqslant\left(v_{n}-w_{n}\right)(x)\right\}} \frac{z_{n}}{\eta_{n}} \psi_{n}+\int_{\left\{x / z_{n}(x)>\left(v_{n}-w_{n}\right)(x)\right\}} \frac{z_{n}}{\eta_{n}} \psi_{n} \\
& \leqslant \int \phi_{n} \psi_{n}+\int_{\left\{x / z_{n}(x)>\left(v_{n}-w_{n}\right)(x)\right\}} \frac{z_{n}}{\eta_{n}^{2}}\left(v_{n}^{m}-w_{n}^{m}\right) \\
& \leqslant \int \phi_{n} \psi_{n}+C \frac{1}{\eta_{n}^{2}} \int w_{n}^{m} z_{n}
\end{aligned}
$$

where the last inequality holds by (3.12). Now the lemma follows by Proposition 4.1.

As a consequence of the above result, we can establish the following estimate (local in time) for $\psi_{n}$, from where convergence in the appropriate sense of $\phi_{n}$ will follow.

Lemma 5.2. - Given $t>0$, there exists $C(t)>0$ such that

$$
\begin{equation*}
\int_{0}^{t} \int\left(\left|\nabla \psi_{n}(\cdot, s)\right|^{2}+\left|\psi_{n}(\cdot, s)\right|^{2}\right) \mathrm{d} s \leqslant C(t) \tag{5.3}
\end{equation*}
$$

for all $n$.
Proof. - Let us recall that

$$
\int G_{n}(s, x) \mathrm{d} x \leqslant b \mathrm{e}^{a s}
$$

Since the function $v$ is bounded we see that $\left|\psi_{n}\right| \leqslant C\left|\phi_{n}\right|$. Hence, using (3.10), we get $\psi_{n}^{2} \leqslant C G_{n}$. Now integrating relation (5.2) in time, between $s=0$ and $s=t$ and using

Lemma 5.2 and Corollary 4.2 we get

$$
\int_{0}^{t} \int\left|\nabla \psi_{n}(\cdot, s)\right|^{2} \leqslant C \mathrm{e}^{a t}
$$

and the result is thus proven.
As a consequence of the last result, the sequence $\psi_{n}$ can be assumed, after passing to a subsequence, weakly convergent in $L^{2}\left((0, S) ; H^{1}\left(\mathbf{R}^{N}\right)\right)$ for each $S>0$. Let $\psi(s, x)$ be this limit. Assume now that

$$
w(x)=\sum_{i=1}^{k} w_{*}\left(\left|x-x_{i}\right|\right)
$$

so that the support of $w$ is the union of disjoint balls $B\left(x_{i}, R^{*}\right), i=1, \ldots, k$. Let $\mathcal{A}=\bigcup_{i=1}^{k} B\left(x_{i}, R^{*}\right)$. Then if we define $\phi=w^{-(m-1)} \psi$ on $\mathcal{B}=(0, \infty) \times \mathcal{A}$ then

$$
\int_{0}^{S} \int_{\mathcal{A}}\left|\nabla\left(w^{m-1} \phi\right)\right|^{2}+\left|w^{m-1} \phi\right|^{2}<+\infty
$$

for each $S>0$. In the next lemma we study further this convergence.
LEMMA 5.3. - The function $\phi$ is of class $C^{1}$ in $\mathcal{B}$ and $\phi_{n}(t, x) \rightarrow \phi(t, x)$ in the uniform $C^{1}$-sense over compact subsets of $\mathcal{B}$. Moreover $\phi$ solves on $\mathcal{B}$ the equation

$$
\begin{equation*}
\phi_{t}=m \Delta w^{m-1} \phi+m w^{m-1} \phi-\frac{1}{m-1} \phi \tag{5.4}
\end{equation*}
$$

Besides the map $t \rightarrow \int w^{m-1}(x) \phi^{2}(t, x) \mathrm{d} x$ is continuous and

$$
\begin{align*}
& \int_{\mathcal{A}} w^{m-1}(x) \phi^{2}\left(t_{1}, x\right) \mathrm{d} x-\int_{\mathcal{A}} w^{m-1}(x) \phi^{2}\left(t_{2}, x\right) \mathrm{d} x \\
& \quad=2 \int_{t_{1}}^{t_{2}} \int_{\mathcal{A}}\left(m\left|\nabla\left(w^{m-1} \phi\right)\right|^{2}-m\left(w^{m-1} \phi\right)^{2}+\frac{1}{m-1} \phi^{2}\right) \mathrm{d} x \mathrm{~d} t . \tag{5.5}
\end{align*}
$$

Additionally, for any function $\zeta \in C^{1}(\mathcal{A})$ with $\left.\left.\int_{\mathcal{A}}\left(w^{m-1} \zeta^{2}+\mid \nabla w^{m-1} \zeta\right)\right|^{2}\right) \mathrm{d} x<+\infty$

$$
\begin{align*}
& \int_{\mathcal{A}} w^{m-1}(x) \phi\left(t_{1}, x\right) \zeta(x) \mathrm{d} x-\int_{\mathcal{A}} w^{m-1}(x) \phi\left(t_{2}, x\right) \zeta(x) \mathrm{d} x \\
& \quad=\int_{t_{1}}^{t_{2}} \int_{\mathcal{A}}\left(m \nabla\left(w^{m-1} \phi\right) \nabla \zeta-m w^{m-1} \phi \zeta+\frac{1}{m-1} \phi \zeta\right) \mathrm{d} x \mathrm{~d} t \tag{5.6}
\end{align*}
$$

Proof. - We recall that $\phi_{n}$ satisfies the equation

$$
\begin{equation*}
\left(\phi_{n}\right)_{t}=\Delta\left(a_{n} \phi_{n}\right)+a_{n} \phi_{n}-\phi_{n}+\frac{z_{n}}{(m-1) \eta_{n}} \tag{5.7}
\end{equation*}
$$

where $a_{n}=\frac{v_{n}^{m}-w^{m}}{v_{n}-w}$. Then $a_{n} \rightarrow m w^{m-1}$ uniformly. Hence over compacts of $\mathcal{B}$ the coefficient $a_{n}$ is uniformly positive and bounded, and $z_{n} \equiv 0$ there for large $n$. The standard theory for quasilinear nondegenerate parabolic equations, see [21], gives that this convergence is also uniform in the $C^{1}$-sense over compacts of $\mathcal{B}$, so that $\nabla a_{n}$ is also bounded there. From Lemma 2.1, it follows that $L^{2}$ norm on any parabolic cube compactly contained in $\mathcal{B}$. Again the theory for nondegenerate parabolic equations in [21] provides uniform estimates for $C^{1, \alpha}$ norms over compacts of $\mathcal{B}$, from where $C^{1}$ convergence follows.

Now, given $\delta>0$ let us consider a smooth cut-off $0 \leqslant \eta(x) \leqslant 1$ compactly supported in $\mathcal{A}$ with $\eta(x)=1$ if $\operatorname{dist}(x, \mathcal{A})>\delta$ and $|\nabla(x)| \leqslant C / \delta$ for all $x$. Let us integrate Eq. (5.7) against $\eta^{2} \psi_{n}$ in space and in time between $t=t_{1}$ and $t=t_{2}$ to obtain

$$
\begin{aligned}
& \int G_{n}\left(t_{1}, x\right) \eta(x) \mathrm{d} x-\int G_{n}\left(t_{2}, x\right) \eta(x) \mathrm{d} x \\
& \quad=\int_{t_{1}}^{t_{2}} \int \eta^{2}\left(\left|\nabla \psi_{n}\right|^{2}-\psi_{n}^{2}+\frac{1}{m-1} \psi_{n} \phi_{n}\right) \mathrm{d} x \mathrm{~d} t+\int_{t_{1}}^{t_{2}} \int 2 \eta \nabla \eta \psi_{n} \nabla \psi_{n} \mathrm{~d} x
\end{aligned}
$$

where $\psi_{n}$ and $G_{n}$ are defined in (3.7) and (3.8). Now we let $n \rightarrow \infty$ and get

$$
\begin{aligned}
& \int w(x)^{m-1} \phi^{2}\left(t_{1}, x\right) \eta(x) \mathrm{d} x-\int w(x)^{m-1} \phi^{2}\left(t_{2}, x\right) \eta(x) \mathrm{d} x \\
& =\int_{t_{1}}^{t_{2}} \int \eta^{2}\left(\left|\nabla w^{m-1} \phi\right|^{2}-\left(w^{m-1} \phi\right)^{2}+\frac{1}{m-1} w^{m-1} \phi^{2}\right) \mathrm{d} x \mathrm{~d} t \\
& \quad+\int_{t_{1}}^{t_{2}} \int 2 \eta \nabla \eta \phi w^{m-1} \nabla\left(w^{m-1} \phi\right) \mathrm{d} x=I+I I
\end{aligned}
$$

Now, let us write $\mathcal{A}_{\delta}=\{x \in \mathcal{A} \mid \operatorname{dist}(x, \partial \mathcal{A}) \leqslant \delta\}$. Since $w^{m-1}$ vanishes quadratically on the boundary of $\mathcal{A}$, then $w^{(m-1) / 2} \leqslant C \delta$ on $\mathcal{A}_{\delta}$. It follows that

$$
|I I| \leqslant C \int_{t_{1}}^{t_{2}} \int_{\mathcal{A}_{\delta}} \phi w^{(m-1) / 2} \nabla\left(w^{m-1} \phi\right) \mathrm{d} x \mathrm{~d} t \leqslant C \int_{t_{1}}^{t_{2}} \int_{\mathcal{A}_{\delta}}\left\{\phi^{2} w^{m-1}+\left|\nabla\left(w^{m-1} \phi\right)\right|^{2}\right\} \mathrm{d} x .
$$

Since the function inside the integral is indeed integrable by construction, it follows that $|I I| \rightarrow 0$ as we let $\delta \rightarrow 0$. Let us recall that for each $t>0 \int G_{n}(t, x) \mathrm{d} x \leqslant C(t)$, from where it follows that $\int \phi^{2}(t, x) w^{m-1}(x) \mathrm{d} x$ is finite. Then, letting $\delta$ go to zero in the above equality, relation (5.5) thus follows. The proof of the remaining assertion of the lemma is similar, so that we omit it.

## 6. The spectral problem

In this section we will analyze the spectrum of the linear elliptic operator associated to Eq. (5.4). The purpose of this is to find an expansion of $\phi$ in terms of eigenvalues and eigenfunctions of this operator.

Thus we consider the eigenvalue problem

$$
\begin{equation*}
m \Delta\left(w^{m-1} \phi\right)+m w^{m-1} \phi-\frac{1}{m-1} \phi+\lambda \phi=0 \tag{6.1}
\end{equation*}
$$

with $\phi$ such that $w^{m-1} \phi \in H^{1}(B)$ and $w^{\frac{m-1}{2}} \phi \in L^{2}(B)$. Here $w(x)=w_{*}(|x|)$ and $B=B\left(0, R^{*}\right)$. Equivalently, the problem can be restated as

$$
\begin{equation*}
m \Delta \psi+m \psi-\frac{1}{m-1} w^{-(m-1)} \psi+\lambda w^{-(m-1)} \psi=0 \tag{6.2}
\end{equation*}
$$

with $\psi \in H$ where

$$
H=H^{1}(B) \cap L_{w}^{2}(B)
$$

with

$$
L_{w}^{2}(B)=\left\{\psi \in L^{2}(B) \mid \int_{B} w^{-(m-1)} \psi^{2}<+\infty\right\}
$$

Now we make the following observation: for a given $\lambda \leqslant 0$, the set of distributional solutions $\psi \in H$ of (6.2) is finite-dimensional. In fact, using $\psi \eta$ as a test function, where $\eta \in C^{\infty}(\Omega)$ is such that $\eta(x)=1$ for $\operatorname{dist}(x, \partial B)>\delta$ and $|\nabla \eta| \leqslant C / \delta$ then

$$
\begin{aligned}
& m \int_{B}|\nabla \psi|^{2} \eta+\left(\frac{1}{m-1}-\lambda\right) \int w^{-(m-1)} \psi^{2} \eta \\
& \quad=-m \int_{B} \psi \nabla \eta \nabla \psi+m \int|\psi|^{2} \eta
\end{aligned}
$$

Now, since $w^{m-1}$ vanishes quadratically on $\partial B$, as the above lemma states, it follows that $\left|w^{(m-1) / 2} \nabla \eta\right| \leqslant C$. Thus

$$
\begin{aligned}
& \left|\int_{B} \eta\left(m|\nabla \psi|^{2}+\left(\frac{1}{m-1}-\lambda\right) w^{-(m-1)} \psi^{2}\right)-m \int \psi^{2} \eta\right| \\
& \quad \leqslant C\left(\int_{R^{*}-\delta<|x|<R^{*}} w^{-(m-1)}|\psi|^{2}\right)^{1 / 2}
\end{aligned}
$$

Letting $\delta \rightarrow 0$ we get

$$
\begin{equation*}
\int_{B} m|\nabla \psi|^{2}+\left(\frac{1}{m-1}-\lambda\right) \int w^{-(m-1)} \psi^{2}=m \int \psi^{2} \tag{6.3}
\end{equation*}
$$

It follows that the unit ball in $L^{2}$-norm of the corresponding eigenspace is bounded in $H^{1}$-norm, hence compact, so that the multiplicity of the eigenvalue is finite. Moreover, only a finite number of eigenvalues $\lambda \leqslant 0$ may exist. In fact, if an infinite number of them exist, then one can construct an infinite orthonormal sequence of eigenfunctions that must converge producing a contradiction.

Let $\mathcal{N}$ be the finite-dimensional vector space spanned by all eigenfunctions in $H$ associated to nonpositive eigenvalues. Let us consider the number $\lambda^{*}$ given by

$$
\begin{align*}
& \lambda^{*}=\frac{1}{m-1}+m \inf \left\{\int_{B}|\nabla \psi|^{2}-\int \psi^{2} / \int w^{-(m-1)} \psi^{2}=\right. 1 \\
&\left.\qquad \int w^{-(m-1)} \psi \zeta=0, \forall \zeta \in \mathcal{N}\right\} \tag{6.4}
\end{align*}
$$

We claim that $\lambda^{*}>0$. In fact, assume $\lambda^{*} \leqslant 0$ and let $\psi_{n}$ be a minimizing sequence of the above quantity. It follows that $\psi_{n}$ is bounded in the space $H$. Let $\psi$ be the weak limit in $H$ of some subsequence. Then

$$
\frac{1}{m-1}+m \int_{B}|\nabla \psi|^{2}-m \int \psi^{2} \leqslant \lambda^{*} \leqslant 0
$$

Hence $\psi \neq 0$ and $\int w^{-(m-1)} \psi^{2} \leqslant 1$. The definition of $\lambda^{*}$ gives then that necessarily $\int w^{-(m-1)} \psi^{2}=1$, and hence $\psi$ attains the infimum. It easily follows that $\lambda^{*}$ is an eigenvalue of problem (6.2), with $\psi$ as associated eigenfunction. Since $\int_{B} w^{-(m-1)} \psi \zeta=$ 0 for all $\zeta \in \mathcal{N}$, it follows that $\lambda^{*}>0$, a contradiction which proves the desired result.

In what follows we shall label the first (possibly repeated) $k_{0}$ negative eigenvalues of problem (6.1) as

$$
\lambda_{1} \leqslant \lambda_{2} \leqslant \cdots \leqslant \lambda_{k_{0}}<0
$$

with associated eigenfunctions $\phi_{1}, \ldots, \phi_{k_{0}}$, orthonormalized so that

$$
\int_{B} \phi_{i} \phi_{j}=\delta_{i j}
$$

We observe also that $\lambda=0$ is an eigenvalue and that $\frac{\partial w^{m}}{\partial_{x_{i}}}$ are associated eigenfunctions for $i=1, \ldots, N$. Besides, as proved in Lemma A. 3 in the appendix, the only eigenfunctions of (6.1) for $\lambda=0$ are linear combinations of the functions $\frac{\partial w}{\partial x_{i}}$.

Remark 6.1. - Assume that $\lambda<0$ is an eigenvalue of problem (6.1) and $\phi$ an associated eigenfunction. For further purposes, we want to estimate the size of $\phi$ near the boundary. We have that $u=-\frac{\partial w}{\partial r}>0$ satisfies

$$
m \Delta\left(w^{m-1} u\right)+m w^{m-1} u-\frac{1}{m-1} u+\lambda u<0
$$

in $B\left(0, R^{*}\right) \backslash\{0\}$. Hence, near the boundary, $\phi$ can be estimated in absolute value by a suitable multiple of $u$. It follows, from Lemma A.2, that

$$
|\phi(x)| \leqslant C\left(R^{*}-|x|\right)^{\frac{3-m}{m-1}} \leqslant C w(|x|)^{\frac{3-m}{2}},
$$

where $C$ depends for instance on $\int w^{m-1} \phi^{2}$.

Now let $\phi(x, t)$ be the function found in Lemma 4.1. Let $B$ be one of the balls constituting the set $\mathcal{A}$. Let us consider the expansion in $B$,

$$
\phi(x, 0)=\sum_{i=1}^{k_{0}} C_{i} \phi_{i}+\sum_{i=1}^{N} D_{i} \frac{\partial w}{\partial x_{i}}+\theta(x)
$$

where

$$
\begin{equation*}
\int_{B} \theta \phi_{i}=\int_{B} \theta \frac{\partial w}{\partial x_{j}}=0 \tag{6.5}
\end{equation*}
$$

for all $i, j$. Now let us consider the function

$$
\tilde{\phi}(x, t)=\phi(x, t)-\sum_{i=1}^{k_{0}} C_{i} \mathrm{e}^{-\lambda_{i} t} \phi_{i}-\sum_{i=1}^{N} D_{i} \frac{\partial w}{\partial x_{i}} .
$$

Let us observe that

$$
\sum C_{i}^{2}+\sum D_{i}^{2} \leqslant \int_{B} w^{m-1} \phi^{2}(0) \mathrm{d} x \leqslant 1
$$

Clearly $\tilde{\phi}(x, t)$ satisfies the equation

$$
(\tilde{\phi})_{s}=m \Delta w^{m-1} \tilde{\phi}+m w^{m-1} \tilde{\phi}-\frac{1}{m-1} \tilde{\phi}
$$

on $B \times(0, \infty)$. Our first claim is that

$$
\int_{B} \tilde{\phi}(\cdot, s) \phi_{i}=\int_{B} \tilde{\phi}(\cdot, s) \frac{\partial w}{\partial x_{j}}=0
$$

for all $s>0$. In fact, let us set

$$
\varphi(s)=\int_{B} \tilde{\phi}(\cdot, s) \phi_{i}
$$

The definition of $\tilde{\phi}$ implies $\varphi^{\prime}(s)==-\lambda_{i} \varphi(s)$. Since $\varphi(0)=0$, the claim follows. Now, let us set

$$
\eta(s)=\int_{B} w^{m-1} \tilde{\phi}(\cdot, s)^{2}
$$

Then

$$
\eta^{\prime}(s)=-2 \int_{B} m\left(\left|\nabla\left(w^{m-1} \tilde{\phi}\right)\right|^{2}-m\left(w^{m-1} \tilde{\phi}\right)^{2}+\frac{w^{m-1}}{m-1} \tilde{\phi}^{2}\right) \mathrm{d} x
$$

Now, since $\tilde{\phi}$ satisfies the orthogonality relations (6.5), it follows that

$$
\eta^{\prime}(s) \leqslant-2 \lambda^{*} \eta(s)
$$

and hence

$$
\eta(s) \leqslant \eta(0) \mathrm{e}^{-2 \lambda^{*} s}
$$

where, we recall, $\lambda^{*}>0$ and $\eta(0) \leqslant 1$. Finally, linear parabolic regularity implies that exponential decay at this rate for $\tilde{\phi}$ also holds uniformly on compact subsets of $B$.

We summarize the above considerations in the following proposition, which provides a description of the limiting function $\phi(t, x)$ inside $\mathcal{A}$.

PROPOSITION 6.1. - We have

$$
\begin{equation*}
\phi(x, t)=\sum_{i=1}^{k} \sum_{j=1}^{k_{0}} D_{i j} \mathrm{e}^{-\lambda_{j} t} \phi_{i}\left(x-x_{j}\right)+\sum_{j=1}^{k} \sum_{i=1}^{N} C_{i j} \frac{\partial w\left(x-x_{j}\right)}{\partial x_{i}}+\theta(x, t), \tag{6.6}
\end{equation*}
$$

where $\theta(x, t)$ converges to zero as $t \rightarrow+\infty$, exponentially uniformly inside compact sets of the set $\mathcal{A}$.

## 7. Analysis near the boundary

In the last two sections we have found the validity of convergence of $\phi_{n}$ to $\phi$ essentially in the interior of the support of the limiting $w$. Here we will show estimates which provide control of $\phi_{n}$ near the boundary of the support of $w$. As a by-product we shall establish that the exponentially increasing terms in the expansion (6.6) actually vanish identically, and as a further consequence that the contribution of the region near the boundary on the integral of $G_{n}$ is basically negligible.

The next result estimates the contribution near the boundary to the integral of $G_{n}$ in terms of a boundary integral for the limiting function. We should mention that here, the key estimate, Lemma 3.1, again plays a role.

LEMMA 7.1. - There exist numbers A and $c$, depending only on $m$, with the following property: Given $\varepsilon>0$ and $0<r_{0}<R^{*}$, with $r_{0}$ sufficiently close to $R^{*}$ and any $t>0$, we have that for all $n$ sufficiently large,

$$
\begin{align*}
& \quad \int G_{n}(x, t) \mathrm{d} x \\
& \bigcap_{i=1}^{k}\left\{\left|x-x_{i}\right| \geqslant r_{1}\right\} \\
& \leqslant A\left[\mathrm{e}^{-c t}+\varepsilon+w_{*}^{\frac{3 m-3}{2}}\left(r_{0}\right) \sum_{i=1}^{k} \sup _{(s, r) \in[0, t] \times\left[r_{0}, r_{1}\right]} \int_{\left|x-x_{i}\right|=r} \phi^{2}(x, s) \mathrm{d} \sigma\right] \tag{7.1}
\end{align*}
$$

where $r_{1}=\frac{r_{0}+R^{*}}{2}$.
Proof. - Set

$$
D_{n}=\bigcap_{i=1}^{k}\left\{x /\left|x-x_{i n}\right| \geqslant r_{0}\right\}
$$

and define for $x \in D_{n}$

$$
g(x)=w_{*}^{m}\left(a r_{0}\right)-\sum_{i=1}^{k} w_{*}^{m}\left(a\left|x-x_{i n}\right|\right)
$$

where

$$
a \equiv \frac{2 R^{*}}{R^{*}+r_{0}}>1
$$

We note that the sets $\left\{x / a\left|x-x_{i n}\right| \leqslant R^{*}\right\}$ are disjoint for all $n$ sufficiently large. Let us multiply Eq. (5.1) by $\psi_{n}(x, t) g(x)$ and integrate on the region $D_{n}$. Since $g$ vanishes on the boundary of this region, recalling that $\left(G_{n}\right)_{t}=\psi_{n}\left(\phi_{n}\right)_{t}$, an integration by parts yields

$$
\begin{align*}
\frac{\partial}{\partial t} \int_{D_{n}} G_{n}(x, t) g(x) \mathrm{d} x= & B_{n}(t)+\int_{D_{n}} \frac{\psi_{n}^{2}}{2} \Delta g(x) \mathrm{d} x \\
& +\iint_{D_{n}}\left\{-\left|\nabla \psi_{n}\right|^{2}+\psi_{n}^{2}-\frac{1}{m-1} \phi_{n} \psi_{n}+\frac{z_{n} \psi_{n}}{(m-1) \eta_{n}}\right\} g(x) \mathrm{d} x \tag{7.2}
\end{align*}
$$

where

$$
B_{n}(t)=-\frac{a \partial w_{*}^{m}}{\partial r}\left(a r_{0}\right) \sum_{i=1}^{k} \int_{\left|x-x_{i n}\right|=r_{0}} \frac{\psi_{n}^{2}}{2} \mathrm{~d} \sigma
$$

Now, $\Delta w_{*}^{m}=\frac{w_{*}}{m-1}-w_{*}^{m} \geqslant 0$ for $|x| \geqslant r_{0}$ if $r_{0}$ is sufficiently close to $R^{*}$, hence we assume $\Delta g(x) \leqslant 0$ on $D_{n}$. On the other hand, $g(x)=w_{*}^{m}\left(a r_{0}\right)$ on the support of $z_{n}$, for all large $n$, since by definition of $z_{n}$ its support is contained in the union of the sets $\left\{r_{0}<\left|x-x_{i}\right|<R^{*}\right\} \cap\left\{r_{0}<\left|x-x_{j}\right|<R^{*}\right\}$ for $i, j=1, \ldots, k$ and $i \neq j$. Using these observations and (7.2) we get

$$
\begin{align*}
\frac{\partial}{\partial t} \int_{D_{n}} G_{n}(x, t) g(x) \mathrm{d} x \leqslant & B_{n}(t)+\int_{D_{n}}\left\{\psi_{n}^{2}-\frac{1}{m-1} \phi_{n} \psi_{n}\right\} g(x) \mathrm{d} x \\
& +w_{*}^{m}\left(a r_{0}\right) \int_{D_{n}} \frac{z_{n} \psi_{n}}{(m-1) \eta_{n}} \tag{7.3}
\end{align*}
$$

On the other hand, recalling the definition of $\psi_{n}$ and that $z_{n} \geqslant 0$, Lemma 3.1 implies

$$
\frac{1}{(m-1) \eta_{n}} \int z_{n} \psi_{n} \leqslant-\int \frac{\partial G_{n}}{\partial t}+\frac{1}{m^{2}-1} \int H_{n}
$$

Now, by definition of the corresponding quantities, we see that

$$
\frac{1}{m^{2}-1} H_{n}=\frac{1}{m-1} \phi_{n} \psi_{n}-\frac{2}{m-1} G_{n}
$$

hence

$$
\begin{equation*}
\frac{1}{(m-1) \eta_{n}} \int z_{n} \psi_{n} \leqslant-\int \frac{\partial G_{n}}{\partial t}+\frac{1}{m-1} \phi_{n} \psi_{n}-\frac{2}{m-1} G_{n} \tag{7.4}
\end{equation*}
$$

Then using (7.4) in relation (7.3) we obtain that

$$
\begin{align*}
\int_{D_{n}} \frac{\partial G_{n}}{\partial t} g(x) \leqslant & B_{n}(t)+\frac{1}{m-1} \int_{D_{n}} \phi_{n} \psi_{n}\left(w_{*}^{m}\left(a r_{0}\right)-g(x)\right) \\
& -w_{*}^{m}\left(a r_{0}\right) \int \frac{\partial G_{n}}{\partial t}+\int_{D_{n}}\left\{\psi_{n}^{2} g(x)-\frac{2 w_{*}^{m}\left(a r_{0}\right)}{m-1} G_{n}\right\} \tag{7.5}
\end{align*}
$$

Now, given $t^{*}>0$ we have that $v_{n} \rightarrow w$ uniformly on $\left[0, t^{*}\right] \times \mathbf{R}^{N}$. Thus, if $r_{0}$ is sufficiently close to $R^{*}$ we obtain that

$$
\psi_{n}^{2} \leqslant \frac{1}{(m-1)} G_{n}
$$

for $|x| \geqslant r_{0}$ and $0<t<t^{*}$ for large $n$. Hence

$$
\psi_{n}^{2} g(x)-\frac{2 w_{*}^{m}\left(a r_{0}\right)}{m-1} G_{n} \leqslant-\frac{\left(w_{*}^{m}\left(a r_{0}\right)+g(x)\right)}{2(m-1)} G_{n}
$$

on this region. Also, $w_{*}^{m}\left(a r_{0}\right)-g(x)=0$ on $F_{n}=\bigcap_{i=1}^{k}\left\{a\left|x-x_{i n}\right| \geqslant R^{*}\right\}$. Substituting this information into relation (7.5), we obtain the following differential inequality for all sufficiently large $n$.

$$
Y_{n}^{\prime}(t) \leqslant B_{n}(t)+W_{n}(t)-c Y_{n}(s), \quad 0<t<t^{*}
$$

where $c$ is a positive constant depending only on $m$ and

$$
\begin{aligned}
Y_{n}(t) & =\int_{D_{n}} G_{n}(x, t)\left(w_{*}^{m}\left(a r_{0}\right)+g(x)\right), \\
W_{n}(t) & =\frac{1}{m-1} \int_{D_{n} \backslash F_{n}} \phi_{n} \psi_{n}\left(w_{*}^{m}\left(a r_{0}\right)-g(x)\right) .
\end{aligned}
$$

It follows that

$$
\begin{equation*}
Y_{n}(s) \leqslant Y_{n}(0) \mathrm{e}^{-c t}+\mathrm{e}^{-c t} \int_{0}^{t} \mathrm{e}^{c s}\left(B_{n}(s)+W_{n}(s)\right) \mathrm{d} s \tag{7.6}
\end{equation*}
$$

We will estimate the right hand side of (7.6). First, we see that $B_{n}(s) \rightarrow B(s)$ and $W_{n}(s) \rightarrow W(s)$ uniformly on compact sets where

$$
B(s)=-\frac{a \partial w_{*}^{m}}{\partial r}\left(a r_{0}\right) \sum_{i=1}^{k} \int_{\left|x-x_{i}\right|=r_{0}} m^{2} w_{*}^{2(m-1)}\left(r_{0}\right) \frac{\phi^{2}}{2} \mathrm{~d} \sigma,
$$

and

$$
W(s)=\frac{m}{m-1} \sum_{i=1}^{k} \int_{r_{0} \leqslant\left|x-x_{i}\right| \leqslant \frac{r_{0}+R^{*}}{2}} \phi^{2}\left(w_{*}^{m-1}\left(\left|x-x_{i}\right|\right)\right)\left(w_{*}^{m}\left(a r_{0}\right)-g(x)\right)
$$

Now,

$$
\left(w^{m}\right)^{\prime}\left(r_{0}\right) w^{2 m-2}\left(r_{0}\right)=\frac{2}{m-1}\left(w^{\frac{m-1}{2}}\right)^{\prime}\left(r_{0}\right) w^{m}\left(r_{0}\right) w^{\frac{3 m-3}{2}}\left(r_{0}\right)
$$

and $w\left(a r_{0}\right)<w\left(r_{0}\right)$, for $r_{0}$ close enough to $R^{*}$, so that

$$
|B(s)| \leqslant C w^{m}\left(r_{0}\right) w^{\frac{3 m-3}{2}}\left(r_{0}\right) \sum_{i=1}^{k} \int_{\left|x-x_{i}\right|=r_{0}} \phi^{2} \mathrm{~d} \sigma
$$

On the other hand,

$$
|W(s)| \leqslant C w_{*}^{m-1}\left(r_{0}\right) w_{*}^{m}\left(a r_{0}\right)\left(\frac{R^{*}-r_{0}}{2}\right) \sum_{i=1}^{k} \sup _{r \in\left[r_{0}, \frac{r_{0}+R^{*}}{2}\right]} \int_{\left|x-x_{i}\right|=r} \phi^{2} \mathrm{~d} \sigma
$$

Since $\frac{\partial}{\partial r} w_{*}^{\frac{m-1}{2}}\left(R^{*}\right)>0$, we have

$$
\frac{R^{*}-r_{0}}{2} \leqslant C w_{*}^{\frac{m-1}{2}}\left(r_{0}\right)
$$

for some $C>0$ depending only on $m$, provided that $r_{0}$ is sufficiently close to $R^{*}$. From these facts and (7.6) we see that for given $\varepsilon>0$ and $t>0$,

$$
Y_{n}(t) \leqslant Y_{n}(0) \mathrm{e}^{-c t}+\varepsilon+C w_{*}^{m}\left(r_{0}\right) w_{*}^{\frac{3 m-3}{2}}\left(r_{0}\right) \sup _{[0, t]} \sum_{i=1}^{k} \sup _{r \in\left[r_{0}, \frac{r_{0}+R^{*}}{2}\right]} \int_{\left|x-x_{i}\right|=r} \phi^{2} \mathrm{~d} \sigma
$$

for all sufficiently large $n$, where we have used again that $w_{*}\left(a r_{0}\right)<w_{*}\left(r_{0}\right)$. Finally, it is easily checked that for some constant $C$ independent of $r_{0}$ close to $R^{*}$, such that $1 \leqslant \frac{w_{*}\left(r_{0}\right)}{w_{*}\left(a r_{0}\right)} \leqslant C$. Since $g(x)=w_{*}^{m}\left(a r_{0}\right)$ for $|x| \geqslant \frac{r_{0}+R^{*}}{2}$, the result of the lemma readily follows.

We prove next two important consequences of the estimate given by the above lemma: One is that no exponentially increasing terms are present in the expansion (6.6) for $\phi$, and that the integrals of $G_{n}$ near and outside the boundary of the support of $w$ become arbitrarily small as $n \rightarrow \infty$.

COROLLARY 7.1. - In the expansion (6.6), we actually have $D_{i j}=0$ for $i=$ $1, \ldots, k_{0}, j=1, \ldots, k$.

Proof. - To establish this assertion, we consider the estimate provided by Corollary 3.1. We have then that,

$$
\begin{equation*}
\int G_{n}(x, t) \mathrm{d} x \leqslant \frac{1}{m^{2}-1} \int_{0}^{t} \int H_{n}+C\left(\int_{0}^{t}\left(\int G_{n}(x, s) \mathrm{d} x\right)^{1 / 2} \mathrm{~d} s+t+1\right) \tag{7.7}
\end{equation*}
$$

for certain number $C$ independent of $t$ and $m$. Let us fix a number $r_{0}$ close to $R^{*}$ and as in the previous lemma, set $r_{1}=\frac{r_{0}+R^{*}}{2}$. We also write

$$
\mathcal{A}_{r_{1}}=\bigcup_{i=1}^{k}\left\{x /\left|x-x_{i}\right| \leqslant r_{1}\right\}
$$

Then there is a constant $D>0$ depending on $r_{0}$ such that

$$
\left|H_{n}\right| \leqslant \frac{D}{\eta_{n}^{2}}\left|v_{n}-w\right|^{3} \quad \text { on } \mathcal{A}_{r_{1}}
$$

from where it follows that

$$
\int_{0}^{t} \int_{\mathcal{A}_{r_{1}}} H_{n} \rightarrow 0 \quad \text { as } n \rightarrow \infty
$$

for each fixed $t$. We note that for any $\sigma>0$ and any $t>0$ one has

$$
s^{1 / 2} \leqslant \sigma s+\sigma^{-1}
$$

Then from relation (7.7), recalling that $\left|H_{n}\right| \leqslant C G_{n}$, we find that for some $C>0$ independent of $r_{0}$ and $\sigma$, and all sufficiently large $n$,

$$
\int_{\mathcal{A}_{r_{1}}} G_{n}(x, t) \mathrm{d} x \leqslant C\left[\left(\frac{1}{m^{2}-1}+\sigma\right) \int_{0}^{t} \int_{\mathbf{R}^{N} \backslash \mathcal{A}_{r_{1}}} G_{n}+\sigma \int_{0}^{t} \int_{\mathcal{A}_{r_{1}}} G_{n}+\sigma^{-1} t+1\right]
$$

Then, passing to the limit, recalling that $G_{n}$ converges uniformly in $\mathcal{A}_{r_{1}} \times[0, t]$ to $m w^{m-1} \phi^{2}$, we get

$$
\begin{align*}
& \int_{\mathcal{A}_{r_{1}}} m w^{m-1} \phi^{2}(x, t) \mathrm{d} x-C \sigma \int_{0}^{t} \int_{\mathcal{A}_{r_{1}}} m w^{m-1} \phi^{2}(x, s) \mathrm{d} x \mathrm{~d} s \\
& \quad \leqslant \limsup _{n \rightarrow \infty} C\left(\int_{0}^{t} \int_{\mathbf{R}^{N} \backslash \mathcal{A}_{r_{1}}} G_{n}+\sigma^{-1} t+1\right) . \tag{7.8}
\end{align*}
$$

Now, from the expression (6.6) for $\phi$, we obtain

$$
\phi(x, t)=\sum_{i=1}^{k} \sum_{j=1}^{k_{0}} D_{i j} \mathrm{e}^{-\lambda_{j} t} \phi_{i}\left(x-x_{j}\right)+\mathrm{O}(1)
$$

with $\mathrm{O}(1)$ uniformly bounded in time and space inside $\mathcal{A}_{r_{1}}$. It follows that

$$
\begin{aligned}
\int_{\mathcal{A}_{\nabla \infty}} w^{m-1} \phi^{2}(x, t) \mathrm{d} x & =\sum_{i=1}^{k} \int_{B\left(x_{i}, r_{1}\right)} w^{m-1} \phi^{2}(x, t) \mathrm{d} x \\
& =\sum_{i=1}^{k} \sum_{j=1}^{k_{0}} \int_{B\left(x_{i}, r_{1}\right)} w^{m-1} D_{i j}^{2} \mathrm{e}^{-2 \lambda_{j} t} \phi_{i}\left(x-x_{j}\right)^{2} \mathrm{~d} x+\mathrm{O}(1) \\
& =\sum_{i=1}^{k} \sum_{j=1}^{k_{0}} D_{i j}^{2} \mathrm{e}^{-2 \lambda_{j} t}+\mathrm{O}(1)
\end{aligned}
$$

Thus, if we fix now $\sigma$ sufficiently small, we get

$$
\begin{align*}
& \int_{\mathcal{A}_{r_{1}}} m w^{m-1} \phi^{2}(x, t) \mathrm{d} x-C \sigma \int_{0}^{t} \int_{\mathcal{A}_{r_{1}}} m w^{m-1} \phi^{2}(x, s) \mathrm{d} x \mathrm{~d} s \\
& \quad=\bar{C} \sum_{i=1}^{k} \sum_{j=1}^{k_{0}} D_{i j}^{2} \mathrm{e}^{2 \lambda_{j} t}+\mathrm{O}(t) \tag{7.9}
\end{align*}
$$

where $\bar{C}>0$. On the other hand, from Lemma 7.1 we can find numbers $A$ and $c$ which depend only on $m$ so that

$$
\begin{align*}
& \limsup _{n \rightarrow \infty} \int_{\mathbf{R}^{N} \backslash \mathcal{A}_{r_{1}}} G_{n}(x, s) \mathrm{d} x \\
& \leqslant A\left\{\mathrm{e}^{-c s}+w_{*}^{\frac{3 m-3}{2}}\left(r_{0}\right) \sup \left\{\int_{\left|x-x_{i}\right|=r} \phi^{2}(x, s) \mathrm{d} \sigma / s \in[0, t], r \in\left[r_{0}, r_{1}\right], 1 \leqslant i \leqslant k\right\}\right\} \tag{7.10}
\end{align*}
$$

We recall that from Remark $6.1|\phi(x)| \leqslant C w(|x|)^{\frac{3-m}{2}}$, hence

$$
\begin{align*}
& w^{\frac{3 m-3}{2}}\left(r_{0}\right) \sup \left\{\int_{\left|x-x_{i}\right|=r} \phi^{2} \mathrm{~d} \sigma / \mid s \in[0, t], r \in\left[r_{0}, r_{1}\right], 1 \leqslant i \leqslant k\right\} \\
& \quad \leqslant C w\left(r_{0}\right)^{\frac{m+3}{2}} \sum_{i=1}^{k} \sum_{j=1}^{k_{0}} D_{i j}^{2} \mathrm{e}^{2 \lambda_{j} t}+\mathrm{O}(1) \tag{7.11}
\end{align*}
$$

where $C$ is independent of $r_{0}$. Using relations (7.8), (7.9), (7.10), and (7.11) we get then that for certain constant $C$

$$
\sum_{i=1}^{k} \sum_{j=1}^{k_{0}} D_{i j}^{2} \mathrm{e}^{-2 \lambda_{j} t} \leqslant C w\left(r_{0}\right)^{\frac{m+3}{2}} \sum_{i=1}^{k} \sum_{j=1}^{k_{0}} D_{i j}^{2} \mathrm{e}^{-2 \lambda_{j} t}+\mathrm{O}(t)
$$

where $C$ is independent of $r_{0}$. Since $w\left(r_{0}\right)$ may be chosen arbitrarily small, we obtain a contradiction from this last relation for all $t$ sufficiently large if any of the $D_{i j}$ 's was not zero. Hence $D_{i j}=0$ for all $i, j$, and the proof of the lemma is complete.

Combining Lemma 7.1 and Corollary 7.1, we get the validity of the following fact.
COROLLARY 7.2. - Let $\varepsilon>0$ be given. Then there exist numbers $0<r_{0}<R^{*}$ and $s^{*}>0$ such that for each given $\bar{s} \geqslant s^{*}$ and all $n$ sufficiently large we have

$$
\sup _{s \in\left[s^{*}, \bar{s}\right]} \int_{\bigcap_{i=1}^{k}\left\{\left|x-x_{i}\right|>r_{0}\right\}} G_{n}(s, x) \mathrm{d} x<\varepsilon
$$

## 8. Conclusion: the proof of Proposition 3.1

Now we are ready to prove Proposition 3.1.
We define

$$
\bar{x}_{i n}=\eta_{n}\left(C_{i 1}, \ldots, C_{i N}\right)
$$

Then $\left|\bar{x}_{i n}\right| \leqslant C \eta_{n}$ with $C=C(m)$. Let us write

$$
\bar{w}_{n}(x)=\left(\sum_{i=1}^{k} w_{*}^{m}\left(x-x_{i}+\bar{x}_{i n}\right)\right)^{1 / m}
$$

We want to estimate the quantity

$$
I_{n}(s)=\int\left(v_{n}(x, s)^{m}-\bar{w}_{n}(x)^{m}\right)\left(v_{n}(x, s)-\bar{w}_{n}(x)\right) \mathrm{d} x .
$$

Let us consider $r \in\left[0, R^{*}\right]$, to be determined later, and set

$$
\mathcal{A}_{r}=\bigcap_{i=1}^{k}\left\{\left|x-x_{i}\right|>r\right\} .
$$

Then

$$
\begin{aligned}
I_{n}(s)= & \int_{\mathcal{A}_{\delta}}\left(v_{n}^{m}-\bar{w}_{n}^{m}\right)\left(v_{n}-\bar{w}_{n}\right) \mathrm{d} x \\
& +\int_{\mathbf{R}^{N} \backslash \mathcal{A}_{\delta}}\left(v_{n}^{m}-\bar{w}_{n}^{m}\right)\left(v_{n}-\bar{w}_{n}\right) \mathrm{d} x=I_{n}^{1}(s)+I_{n}^{2}(s) .
\end{aligned}
$$

We have

$$
I_{n}^{1}(s) \leqslant C\left[\int_{\mathcal{A}_{r}}\left(v_{n}^{m}-w_{n}^{m}\right)\left(v_{n}-w_{n}\right) \mathrm{d} x+\int_{\mathcal{A}_{r}}\left(\bar{w}_{n}^{m}-w_{n}^{m}\right)\left(\bar{w}_{n}-w_{n}\right) \mathrm{d} x\right]
$$

Now, from 3.10, we get

$$
\int_{\mathcal{A}_{r}}\left(v_{n}^{m}-w_{n}^{m}\right)\left(v_{n}-w_{n}\right) \mathrm{d} x \leqslant C \eta_{n}^{2} \int_{\mathcal{A}_{r}} G_{n}(x, s) \mathrm{d} x
$$

again with $C=C(m)$. Corollary 7.2 then implies that if $r$ is chosen close enough to $R^{*}$, depending on $m$, and $s \geqslant s^{*}$, with $s^{*}$ also depending only on $m$ then for all $n$ sufficiently large

$$
C \int_{\mathcal{A}_{r}} G_{n}(x, s) \mathrm{d} x<\frac{1}{8}
$$

Also, it follows from Lemma A.2, in the appendix, that

$$
C\left(\bar{w}_{n}^{m}-w_{n}^{m}\right)\left(\bar{w}_{n}-w_{n}\right) \leqslant K \eta_{n}^{2}
$$

with $K$ depending on $m$ and $k$ only. Therefore taking $r$ closer to $R^{*}$, if necessary, we get

$$
C \int_{\mathcal{A}_{r}}\left(\bar{w}_{n}^{m}-w_{n}^{m}\right)\left(\bar{w}_{n}-w_{n}\right) \mathrm{d} x \leqslant \frac{\eta_{n}^{2}}{8}
$$

if $n$ is large enough. Putting these two estimates together we see that if we choose $T \geqslant s^{*}$, then

$$
I_{n}^{1}(s) \leqslant \frac{\eta_{n}^{2}}{4}
$$

for all $s \in[T, 2 T]$ provided that $n$ is sufficiently large.
On the other hand, we recall that

$$
v_{n}(x, s)=w_{n}(x)+\eta_{n} \phi_{n}(x, s),
$$

which we can write, in view of Proposition 6.1 and Corollary 7.1, as

$$
v_{n}(x, s)=w_{n}(x)+\eta_{n} \sum_{j=1}^{N} C_{i j} \frac{\partial w_{*}}{\partial x_{i}}\left(x-x_{i}\right)+\eta_{n} \theta(x, s)+\left(\phi_{n}(x, s)-\phi(x, s)\right),
$$

where $\theta$ decays exponentially in compact sets of $\mathcal{A}$.
Now, since $r$ has been already fixed and liminf $\left|x_{i n}-x_{j n}\right| \geqslant 2 R^{*}$ as $n \rightarrow \infty$ for $i \neq j$, it follows that if $x \in \mathbf{R}^{N} \backslash A_{r}$ then

$$
w_{n}(x)=\sum_{i=1}^{k} w_{*}\left(x-x_{i}\right)
$$

and

$$
\bar{w}_{n}(x)=\sum_{i=1}^{k} w_{*}\left(x-x_{i n}+\bar{x}_{i n}\right)
$$

if $n$ is sufficiently large. From these observations it follows that

$$
\lim _{n \rightarrow \infty} \eta_{n}^{-2} \int_{\mathbf{R}^{N} \backslash \mathcal{A}_{r}}\left(v_{n}^{m}-\bar{w}_{n}^{m}\right)\left(v_{n}-\bar{w}_{n}\right) \mathrm{d} x=m \int_{\mathbf{R}^{N} \backslash \mathcal{A}_{r}} w^{m-1}(x) \theta^{2}(x, s) \mathrm{d} x
$$

uniformly on $s$ on compact subsets of $(0, \infty)$. Since $\theta(x, s)$ decays exponentially we have that there are positive numbers $A$ and $a$, depending only on $m$, such that

$$
I_{n}^{2}(s) \leqslant \eta_{n}^{2} A \mathrm{e}^{-a t}
$$

Consequently we have

$$
I_{n}(s) \leqslant \eta_{n}^{2}\left(\frac{1}{4}+A \mathrm{e}^{-a T}\right)
$$

for all $s \in[T, 2 T]$. Making $T$ larger if necessary (depending only on $m$ ) we obtain that the quantity between brackets is less than $1 / 2$. This concludes the proof of the proposition.

## Appendix A

Lemma A.1. - With the notation of Section 3, we have

$$
\begin{equation*}
\left(w_{n}^{m+1}-\sum_{i=1}^{k} w_{i n}^{m+1}\right) \leqslant \frac{1}{m-1}\left(w_{n}^{m} z_{n}\right) \tag{A.1}
\end{equation*}
$$

Proof. - By homogeneity, it suffices to establish the following general fact on real numbers:

For any nonnegative numbers $h_{1}, \ldots, h_{k}$ such that $\sum_{i=1}^{k} h_{i}^{m}=1$ one has

$$
\begin{equation*}
\left(1-\sum_{i=1}^{k} h_{i}^{m+1}\right) \leqslant \frac{1}{m-1}\left(\sum_{i=1}^{k} h_{i}-1\right) \tag{A.2}
\end{equation*}
$$

To prove (A.2), we set $h=\left(h_{1}, \ldots, h_{k}\right)$,

$$
F(h)=\sum_{i=1}^{k} h_{i}+(m-1) \sum_{i=1}^{k} h_{i}^{m+1} \quad \text { and } \quad P(h)=\sum_{i=1}^{k} h_{i}^{m}
$$

we see that our problem reduces to show that the minimum of the function $F$, over to the set $S=\left\{h \mid P(h)=1, h_{1} \geqslant 0, \ldots, h_{k} \geqslant 0\right\}$, is greater than $m$. If a minimum of $F$ over $S$
is attained at a point $h$ with all coordinates positive, then Lagrange multiplier rule yields the existence of a number $\lambda$ such that

$$
\frac{1}{h_{i}^{m-1}}+\left(m^{2}-1\right) h_{i}=m \lambda \quad \text { for all } i=1, \ldots, k
$$

For each $i$, this equation has at most two solutions, which we denote by $a$ and $b$. Therefore there are integers $p$ and $q$ such that $p+q=k, p a^{m}+q b^{m}=1$ and the minimum of $F$ is given by

$$
p a+q b+(m-1)\left(p a^{m+1}+q b^{m+1}\right)
$$

It is clear that if $a \leqslant b$ this quantity is greater or equal to

$$
k a+(m-1) k a^{m+1}
$$

with $k a^{m}=1$. This last number is greater or equal to $m$ if $k \geqslant 1$. So far we have proved that any minimum attained at the interior of $S$ is greater or equal to $m$. Studying the possible minima attained at the boundary of $S$ reduces to the same problem with a different value of $k$. Inequality (A.2) is thus established, and the proof of the lemma is concluded.

Our next result refers to the behavior of the function $w$ near the boundary of $B$.
Lemma A.2. - Let $w_{*}(|x|)$ be the unique radially symmetric, compactly supported solution of

$$
\Delta w^{m}+w^{m}-\frac{1}{m-1} w=0
$$

and $B\left(0, R^{*}\right)$ its support. Then there exist positive constants $A$ and $B$ such that

$$
\begin{aligned}
& A\left(R^{*}-r\right)^{\frac{2}{m-1}} \leqslant w_{*}(r) \leqslant B\left(R^{*}-r\right)^{\frac{2}{m-1}} \\
& A\left(R^{*}-r\right)^{\frac{3-m}{m-1}} \leqslant-w_{*}(r)^{\prime} \leqslant B\left(R^{*}-r\right)^{\frac{3-m}{m-1}}
\end{aligned}
$$

for all $r \in\left[0, R^{*}\right]$.
Proof. - The function $z=w_{*}^{m}$ satisfies

$$
z^{\prime \prime}+\frac{N-1}{r} z^{\prime}+z-\frac{1}{m-1} z^{1 / m}=0 .
$$

Multiplying by $z^{\prime}$ and integrating from $r$ to $R^{*}$ we get

$$
\frac{z^{\prime}(r)^{2}}{2}+\frac{z(r)^{2}}{2}-\int_{r}^{R^{*}} \frac{N-1}{s} z^{\prime}(s)^{2} \mathrm{~d} s-\frac{m}{m^{2}-1} z^{\frac{m+1}{m}}(r)=0
$$

Hence near $r=R^{*}$,

$$
z^{\prime}(r)^{2} \geqslant A z^{\frac{m+1}{m}}(r)
$$

and hence $z^{-\frac{m+1}{2 m}} z^{\prime} \leqslant-A^{1 / 2}$, so that $z^{\frac{m-1}{2 m}}(r) \geqslant A\left(R^{*}-r\right)$, whence $w(r) \geqslant A\left(R^{*}-r\right)^{\frac{2}{m-1}}$ near $r=R^{*}$. On the other hand, again near $R^{*}$,

$$
-r^{N-1} z^{\prime}(r) \leqslant C \int_{r}^{R^{*}} z^{1 / m}(s) s^{N-1} \mathrm{~d} s
$$

or, since $z$ is decreasing in $r$,

$$
-r^{N-1} z^{\prime}(r) \leqslant C\left(\left(R^{*}\right)^{N}-r^{N}\right) z^{1 / m}(r)
$$

It follows that $-z^{\frac{-1}{m}} z^{\prime}(r) \leqslant C\left(R^{*}-r\right)$. Thus $z^{\frac{m-1}{m}}(r) \leqslant C\left(R^{*}-r\right)^{2}$ and hence

$$
w(r) \leqslant C\left(R^{*}-r\right)^{\frac{2}{m-1}}
$$

near $r=R^{*}$. Similar estimates for the derivative follow from those for $w$ and the above intermediate computations. Making $A$ smaller and $B$ bigger, if necessary, the lemma is proved.

The following lemma was used in Section 6. Since its proof follows closely the proof of Lemma 4.2 of [23], we only sketch it here.

LEMMA A.3. - The only eigenfunctions of (6.1) for $\lambda=0$ are linear combinations of the functions $\frac{\partial w}{\partial_{x_{i}}}$.

Proof. - The lemma will be proved as soon as we prove that the eigenspace corresponding to $\lambda=0$ has dimension less or equal to $N-1$. So let $\psi$ satisfy

$$
\begin{equation*}
m \Delta \psi+m \psi-\frac{1}{m-1} w^{-(m-1)} \psi=0 \tag{A.3}
\end{equation*}
$$

Let $\mu_{k}, e_{k}(\sigma)$, with $\sigma \in S^{N-1}$, be the eigenvalues and eigenvectors of the LaplaceBeltrami operator on $S^{N-1}$. We recall that

$$
\mu_{0}=0<\mu_{1}=\cdots=\mu_{N}=N-1<\mu_{N+1} \leqslant \cdots
$$

We normalize $e_{k}$ so that they form a complete orthonormal basis of $L^{2}\left(S^{N-1}\right)$. Now we set

$$
\varphi_{k}(r)=\int_{S^{N-1}} \psi(r, \sigma) e_{k}(\sigma) \mathrm{d} \sigma
$$

and observe that $\varphi_{k}$ satisfies

$$
\begin{equation*}
m \varphi_{k}^{\prime \prime}+m \frac{N-1}{r} \varphi_{k}^{\prime}+m \varphi_{k}-\frac{w^{-(m-1)}}{m-1} \varphi_{k}=m \mu_{k} \varphi_{k} \quad \text { on } 0<r<R^{*} \tag{A.4}
\end{equation*}
$$

We note that for $\varphi_{0}$ we have

$$
m \varphi_{0}^{\prime \prime}+m \frac{N-1}{r} \varphi_{0}^{\prime}+m \varphi_{0}-\frac{w^{-(m-1)}}{m-1} \varphi_{0}=0 \quad \text { on } 0<r<R^{*}
$$

with $\varphi_{0}^{\prime}(0)=0$ and $\varphi_{0}\left(R^{*}\right)=0$.
Also setting $z=w^{m}$ we see that

$$
z^{\prime \prime}+\frac{N-1}{r} z^{\prime}+z-\frac{z^{1 / m}}{m-1}=0 \quad \text { on } 0<r<R^{*}
$$

According to Proposition 4.1 in [3], the corresponding linearized equation

$$
m \varphi^{\prime \prime}+m \frac{N-1}{r} \varphi^{\prime \prime}+m \varphi-\frac{z^{-\frac{m-1}{m}}}{m-1} \varphi=0
$$

has no nontrivial solutions satisfying $z^{\prime}(0)=0$ and $z\left(R^{*}\right)=0$. We observe that the results of [3] hold the same for the case $p=1$ in the notation of that paper. This implies $\varphi_{0} \equiv 0$ since $z^{-\frac{m-1}{m}}=w^{-(m-1)}$. Therefore, as in [23], the lemma will be proved as soon as we prove that $\varphi_{k} \equiv 0$ for all $k \geqslant N+1$. To do this assume for a contradiction that $\varphi_{k} \neq 0$ for some $k \geqslant N+1$. Since in this case, as in [23], we can assume that $\varphi_{k}(r)$ is positive for small values of $r$, we have that there exists $\rho_{k} \in\left(0, R^{*}\right]$ such that $\varphi_{k}(r)>0$ if $r \in\left(0, \rho_{k}\right)$ and $\varphi_{k}\left(\rho_{k}\right)=0$. Multiplying (A.4) by $r^{N-1}\left(w^{m}\right)^{\prime}$ and integrating from 0 to $\rho_{k}$, after integrating by parts twice and using boundary values, one gets

$$
\rho_{k}^{N-1} \varphi_{k}^{\prime}\left(\rho_{k}\right)\left(w^{m}\right)^{\prime}\left(\rho_{k}\right)+\left(N-1+\mu_{k}\right) \int_{0}^{\rho_{k}} r^{N-3} \varphi_{k}(r)\left(w^{m}\right)^{\prime}(r) \mathrm{d} r=0
$$

This is a contradiction since $\varphi_{k}^{\prime}\left(\rho_{k}\right) \leqslant 0$ and $\left(w^{m}\right)^{\prime}(r)<0$ for $r \in\left(0, R^{*}\right)$. The lemma is proved.

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