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ANTONY TROMBA

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THE EULER CHARACTERISTIC OF VECTOR FIELDS

ON BANACH MANIFOLDS AND THE PROBLEM OF PLATEAU

par Antony TROMBA

In this note we outline a theory of characteristics for vector fields on Banach manifolds, and then give an application to simply connected minimal surfaces. The theory provides a framework to study the question of how the number of simply connected minimal surfaces spanning a simple closed curve $\Gamma \subset \mathbb{R}^3$ changes as the curve changes.

I. THE THEORY.

Let M be a smooth Banach manifold and K : $T^2M \rightarrow TM$ a connection map [3]. In [13] the author defines a smooth vector field X : $M \rightarrow TM$ to be Fredholm with respect to K if for each $p \in M$ the covariant derivative of X with respect to K, $\nabla X(p)$, which is a linear map of T_pM to itself is linear Fredholm [9]. By the *index of* X we mean the dim ker $\nabla X(p) - dim$ coker $\nabla X(p)$. If M is connected this index does not depend on p. If M est not connected, the index is constant on components and we shall require it to be the same for all components. A Fredholm vector field is Palais-Smale if $\nabla X(p)$ is of the form I+C, where C is a compact linear map. Palais-Smale vector fields have index zero.

Let X be a Palais-Smale vector field on M with finitely many isolated zeros in the interior of M. Then using the degree theory developed in [4] one can define the degree of X at a zero p, which we denote by (deg X)(p). The *Euler characteristic* $\chi(X)$ is defined to be

$$X(X) = \sum_{p \in zeros(X)} (deg X)(p).$$

If X has no zeros, then $\chi(X) = 0$. By using elementary transversality techniques the Euler characteristic can be defined for Palais-Smale vector fields with a compact set of zeros in the interior of M.

<u>DEFINITION</u>. - Suppose M is a smooth Banach manifold with $X : M \to TM$ a smooth vector field. A zero $m \in M$ is non-degenerate if the Frechet derivative $X_{*}(m) : T_{m} \leftrightarrow is$ an isomorphism. (At a zero the Frechet derivative agrees with the covariant derivative of X with respect to any connection on M).

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As a trivial consequence of this definition it follows that non-degenerate zeros are isolated.

Recall form [4] that the Lie subgroup $GL_{c}(E)$ of the general linear group GL(E) for a Banach space E is defined as the set of invertible linear maps on E of the form I+C, C compact. In [4] it is shown that $GL_{c}(E)$ has two components $GL_{c}^{+}(E)$ and $GL_{c}^{-}(E)$. Using these ideas we can give a particularly simple description of the Euler-characteristic of a vector field X with non-degenerate zeros. At a zero p of X, define

$$\operatorname{sgn} \nabla X(p) = \begin{cases} +1 & \text{if } \nabla X(p) \in \operatorname{GL}_{c}^{+}(T_{p}M) \\ \\ -1 & \text{if } \nabla X(p) \in \operatorname{GL}_{c}^{-}(T_{p}M). \end{cases}$$

Then

(1)
$$\chi(X) = \sum_{p \in zeros(X)} sgn \nabla X(p)$$

 $\begin{array}{l} \underline{\text{DEFINITION.}}_{\text{o}} - \text{Let } \pi_{0} : \mathcal{M} \rightarrow [0,1] \text{ be a smooth fibre bundle over the unit interval} \\ \hline with \pi_{0}^{-1}(t) = \mathcal{M}_{t} \text{ a smooth Banach manifold. Suppose there is a family of maps } \mathbb{K}_{t} \\ with each \mathbb{K}_{t} \text{ a connection for } \mathcal{M}_{t}. \text{ Two smooth Palais-Smale vector fields} \\ \hline \mathbb{X}_{0} : \mathcal{M}_{0} \rightarrow \mathbb{T}\mathcal{M}_{0} \text{ and } \mathbb{X}_{1} : \mathbb{M}_{1} \rightarrow \mathbb{T}\mathbb{M}_{1} \text{ are equivalent } (\mathbb{X}_{0} \sim \mathbb{X}_{1}) \text{ if there is a smooth vector field } \mathbb{X} : \mathcal{M} \rightarrow \mathbb{T} \text{ such that} \end{array}$

i) $X_t = X | \mathcal{M}_t : \mathcal{M}_t \to T \mathcal{M}_t$, i.e., X is a vertical family on \mathcal{M} ; ii) X_t is Palais-Smale w.r.t. K_t ; iii) the zeros of X are compact in the interior of \mathcal{M} .

<u>THEOREM 1</u>. (Euler-Hopf Theorem). – If $X_0 \sim X_1$ then $X(X_0)$ and $X(X_1)$ are both defined and equal.

Proof (A Sketch). - Using transversality theorems which go back to Thom and Abraham we can assume

(a) X_{0} and X_{1} have non-degenerate zeros ;

and (b) X is transverse to the zero section of the vertical subbundle $v(T\mathcal{M}) = \bigcup T\mathcal{M}_t$. m $\in M$

Conditions (a) and (b) imply that $X(\mathcal{M}) \cap \mathcal{M}$ is a compact one-dimensional submanifold of the interior of \mathcal{M} with boundary the union of the zeros of X_0 and the zeros of X_1 . Then $X(\mathcal{M}) \cap \mathcal{M}$ establishes a cobordism between the set $\{p_1, \ldots, p_k\}$ and $\{q_1, \ldots, q_m\}$. One then shows that if p_i and p_j (similarly q_i and q_j) bound the same component of $X(\mathcal{M}) \cap \mathcal{M}$, then sgn $\nabla X(p_i) = - \operatorname{sgn} \nabla X(p_i)$ (similarly

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 $\nabla X(q_i) = - \operatorname{sgn} \nabla X(q_j)$. If p_i and q_j bound the same component, then $\operatorname{sgn} \nabla X(p_i) = \operatorname{sgn} \nabla X(q_j)$. Using these facts along with formula (1) and pairing off the $\{p_i\}$ and the $\{q_i\}$ we see immediately that $X(X_0) = X(X_1)$.

By applying the Morse theory as developed in [14], [17], one can show that if X and Y are two vector fields on a manifold M, with $\partial M = \phi$, X ~ Y, Y a gradient-like vector field, then the Euler characteristic of M is defined and X(X) = $\chi(M)$. If $\partial M \neq \phi$ and both X and Y point outward along ∂M the same result holds.

There are conditions which insure that the zeros of a family of vector fields parametrized by some manifold will be generically isolated.

Let \mathscr{A} be a smooth Hilbert manifold, $\pi : \mathscr{M} \to \mathscr{A}$ a smooth Banach Fibre bundle over \mathscr{A} (the fibre $\pi^{-1}(a) = \mathscr{M}^a$ is a smooth Banach manifold). Let $X : \mathscr{M} \to TM$ be a smooth vector field such that $X^a = X | \mathscr{M}^a$ is a Fredholm vector field on \mathscr{M}^a with respect to a connection K_a where $\{K_a\}_{a \in \mathscr{A}}$ is a family of connections. We shall say that such an X represents a vertical family of Fredholm vector fields, with respect to the family $\{K_a\}$.

For each zero $m \in \mathcal{M}$ of X the Frechet derivative $X_{\mathbf{*}}(m)$ can be viewed as a map of $T_{m}\mathcal{M}$ into itself. It follows that if $\pi(m) = a$, then $X_{\mathbf{*}}(m) \in T_{m}\mathcal{M}^{a}$.

We shall say that a vertical family of Fredholm vector fields X is *vertically* transverse to the zero section of T \mathscr{M} if $X_{*}(m) : T_{m} \mathscr{M} \to T_{m} \mathscr{M}^{a}$ is surjective for each zero m of X. In this case, we write $X \uparrow_{V} z(T\mathscr{M})$. We can interpret this geometrically as meaning that $X(\mathscr{M})$ is transverse to the zero section of the vertical subbundle of T \mathscr{M} .

Assume now that Y is a vector field on a Banach Finsler manifold M. Therefore we have a norm $\| \|_m : T_m M \rightarrow R$ on each fibre of TM which varies continuously over M [e.g., see [13]]. We shall say that a vector field Y on a Banach Finsler manifold is *proper*, or satisfies *condition* (CV), if whenever $\| Y(p_i) \|$ converges to zero, then $\{p_i\}$ has a convergent subsequence.

Suppose $\pi : \mathcal{M} \to \mathcal{A}$ is a fibre bundle as above with $\| \| \| : v(T,\mathcal{M}) \to R$ is a Finsler on the vertical subbundle of T. \mathcal{M} . A vertical family X is proper if whenever $\|X(p_i)\|$ converges to zero and $\pi(p_i)$ converges, then $\{p_i\}$ has a convergent subsequence.

<u>THEOREM 2</u>. - Suppose X $\oint_V z(T.M)$, where X represents a proper vertical family of index zero vector fields. Then there exists an open dense set $V \subset \mathcal{A}$ with the property that for $a \in V$, $X^a : \mathcal{M}^a \to T.\mathcal{M}^a$ has only non-degenerate zeros.

II. APPLICATIONS TO THE PLATEAU PROBLEM.

Since its formulation by PLATEAU in the 19th century, little (see [2], [10]) has been known about the number of simply connected minimal surfaces spanning a simple closed curve $\Gamma \subset \mathbb{R}^3$. Existence was proved in the thirties by J. DOUGLAS [1] and T. RADO [11], and most contemporary research has been directed toward regularity results for such minimal surfaces.

Examples of Γ are known which seem to indicate that it is possible to have as many simply connected minimal surfaces spanning a curve (including infinitely many) as one would like. Nothing was known about how the number changed as the curve changed. In the paragraphs below we state theorems which partially answer these questions in terms of our topological theory. They follow from modified versions of Theorem 1 and 2 in Section 1.

Let $\operatorname{H}^{r+2}(\operatorname{S}^1, \operatorname{R}^n)$ be the Sobelev Hilbert space of H^{r+2} maps of the unit circle S^1 into R^n , with $r \ge 5$. Let $\mathscr{A} = \operatorname{Emb}(\operatorname{S}^1, \operatorname{R}^3)$ be the open submanifold of $\operatorname{H}^{r+2}(\operatorname{S}^1, \operatorname{R}^3)$ which consists of embeddings of S^1 into R^3 . Let Γ be the image of such an embedding $\alpha \in \mathscr{A}$. Set η^{α} to be the component of $\operatorname{H}^2(\operatorname{S}^1, \Gamma)$ {the C^r} Hilbert manifold of H^2 maps from S^1 to Γ } determined by the embedding α . Let \mathscr{M}^{α} be the open submanifold of η^{α} consisting of the diffeomorphisms. For every $u \in \operatorname{H}^2(\operatorname{S}^1, \Gamma) \subset \operatorname{H}^2(\operatorname{S}^1, \operatorname{R}^3)$ we can extend $u = (u_1, \ldots, u_n)$ harmonically to the disc \mathscr{D} . Define the smooth Dirichlet energy functional $\operatorname{E}_{\alpha} : \eta^{\alpha} \to \operatorname{R}$ by

(2)
$$E_{\alpha}(u) = \frac{1}{2} \sum_{i=1}^{3} \int_{\mathscr{D}} \left| \frac{\partial u_{i}}{\partial x}^{2} + \frac{\partial u_{i}}{\partial y}^{2} \right| dxdy.$$

We can write the Dirichlet functional as an integral over $S^1 = \partial \mathscr{D}$ as follows. Let $\theta \rightarrow \frac{\partial u}{\partial r}(\theta)$ represent the partial derivative with respect to the polar coordinate r of the harmonic extension of u to \mathscr{D} evaluated at r=1. This agrees with the normal derivative on S^1 of the harmonic extension. Let <, > denote the \mathbb{R}^3 inner product. Then applying Green's theorem to (2) we find that

$$E_{\alpha}(u) = \frac{1}{2} \int_{S^1} < \frac{\partial u}{\partial r}, u > d\theta$$

Denote by $\overline{\mathcal{M}}^{\alpha}$ the closure of \mathcal{M}^{α} in η^{α} .

J. DOUGLAS showed in his pioneering work [1] that the harmonic extensions of the critical points of E in $\overline{\mathcal{M}}^{\alpha}$ are the simply connected minimal surfaces spanning Γ . For a somewhat simpler proof see [16].

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<u>THEOREM 3</u>. - There exists a smooth connection K_{α} on the second tangent bundle $T^{2}n^{\alpha}$ and a smooth vector field $x^{\alpha} : n^{\alpha} \to Tn^{\alpha}$ which is Palais-Smale with respect to the connection K_{α} and whose zeros are precisely all the critical points of E_{α} . Moreover,

$$X^{\alpha}(E_{\alpha}) = dE_{\alpha}(u)(X^{\alpha}(u)) \ge 0.$$

Proof (A Sketch). - Let h, $k \in T_u \eta^{\alpha}$. Define the weak Riemannian structure \ll , \gg : $T\eta^{\alpha} \times T\eta^{\alpha} \rightarrow R$ by setting

$$\ll h, k \gg = \int_{S^1} \frac{\partial h}{\partial r}, k > d\theta.$$

By definition $\eta^{\alpha} \subset H^2(S^1, \mathbb{R}^3) = H$ is a submanifold. For each $u \in \eta^{\alpha}$

(3)
$$H = T_{u} \eta^{\alpha} \oplus (T_{u} \eta^{\alpha})^{\perp}$$

where $(T_{u}n^{\alpha})^{\perp}$ is the weak orthogonal complement of $T_{u}n^{\alpha}$ in H. In a standard way, one can use the splitting (3) to define the connection K_{α} on η^{α} .

The vector field X^{α} is the "gradient" of E_{α} with respect to \ll , \gg . It is necessary to check that this weak gradient gives a smooth vector field on n^{α} and we use regularity theorems from the theory of elliptic partial differential equations to accomplish this. The connection K_{α} and the vector field X^{α} are both defined naturally in terms of the weak Riemannian structure. By a direct computation we show that X^{α} is Palais-Smale with respect to K_{α} .

<u>DEFINITION</u>. - Let $u \in n^{\alpha}$ be a minimal surface. A branch point $p \in \mathscr{D}$ of u is a point where the map $u : \mathscr{D} \to \mathbb{R}^3$ fails to be an immersion. An embedding $\alpha \in \mathscr{A}$ is fine if all minimal surfaces spanning $\Gamma = \alpha(S^1)$ are free of branch points.

In [10] RADO showed that if α is not "too complicated", then α is fine. In particular, he showed that α is fine if there existed no point $q \in \mathbb{R}^3$ such that every hyperplane through q intersected Γ in at least four points.

<u>THEOREM 4</u>. - Let $\mathscr{I} \subset \mathscr{A}$ be the set of fine embeddings. Then \mathscr{I} is open in \mathscr{A} , and hence open in $\mathbb{H}^{r+2}(S^1, \mathbb{R}^3)$.

Conjecture. - \mathscr{I} is dense in \mathscr{A} , or perhaps the open set of curves which admit only minimal surfaces without boundary branch points is dense in \mathscr{A} .

Let G be the three dimensional non-compact Lie group of bijective holomorphic maps of the disc onto itself. The functional E_{α} and the vector field X^{α} of Theorem 3 will be equivariant with respect to the action of G. Therefore, there is no hope that the critical points of E_{α} in $\overline{\mathscr{M}}^{\alpha}$ will be isolated or non-degenerate in the

sense described earlier since the orbits of any critical point will consist of critical points. Let $u \in \overline{\mathcal{M}}^{\alpha}$ be a zero of X^{α} , and let $\mathcal{O}_{G}(u)$ denote the orbit of u under G. Then $\mathcal{O}_{G}(u)$ is an immersed three-dimensional submanifold of η^{α} consisting of critical points of E_{α} . We call $\mathcal{O}_{G}(u)$ a *critical submanifold* of η^{α} . The covariant derivative of X^{α} at u induces a homomorphism of the normal bundle of $\mathcal{O}_{G}(u)$ into itself. A critical point u, or more precisely $\mathcal{O}_{G}(u)$, is *non-degenerate* if this induced homomorphism is an isomorphism.

Applying a modified version of Theorem 2 and some regularity theorems of HILDE-BRANDT [5] and NITSCHE [7] and others we obtain

<u>THEOREM 5.</u> - For an open dense set of embeddings $\mathscr{V} \subset \mathscr{I}$ the zeros of X^{α} , $\alpha \in \mathscr{V}$, in \mathscr{M}^{α} are non-degenerate (and therefore isolated) three-dimensional submanifolds of n^{α} . Moreover, for such $\alpha \in \mathscr{V}$ there are only finitely many such critical submanifolds.

In general minimal surfaces on the same orbit are identified. Doing this we obtain

<u>THEOREM 6</u>. - If $\alpha \in \mathscr{V}$ and $\gamma \in \mathscr{V}$, $\gamma = \alpha + \rho$, is sufficiently close to α , then the minimal surfaces spanning γ are smooth functions of the parameter ρ .

<u>COROLLARY</u>. - If $\alpha \in \mathscr{V}$ and $\gamma \in \mathscr{V}$ is sufficiently close to α then the geometric number of minimal surfaces spanning γ is equal to the number spanning α .

Let $\Gamma = \alpha(S^1)$, $\alpha \in \mathscr{A}$, be a plane curve. The Riemann-Osgood mapping theorem implies that there is a unique minimal surface spanning Γ . This will be the conformal map of the disc onto the bounded component of C determined by Γ .

THEOREM 7. - If Γ is a plane curve, then the unique minimal surface which spans it is non-degenerate.

<u>COROLLARY</u>. - Any curve sufficiently close to a plane curve has a unique minimal surface spanning it.

Let γ belong to \mathscr{I} . We can define the Euler characteristic of the corresponding vector field X^{α} , and we take this to be the definition of the *algebraic number* of minimal surfaces spanning the image $\gamma(S^1)$.

We conclude with an application of a modified version of Theorem 1.

<u>THEOREM 8</u>. - Let γ_0 and γ_1 be fine embeddings. Suppose further that γ_0 is isotopic to γ_1 through a family γ_t , $0 \le t \le 1$ of fine embeddings. Then the algebraic number surfaces spanning γ_0 is equal to the number spanning γ_1 .

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Antony TROMBA The Institute for Advanced Study Princeton, N.J. 08540 and

The University of California at Santa Cruz

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