

## FIXPOINTS, GAMES AND THE DIFFERENCE HIERARCHY\*

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**Abstract.** Drawing on an analogy with temporal fixpoint logic, we relate the arithmetic fixpoint definable sets to the winning positions of certain games, namely games whose winning conditions lie in the difference hierarchy over  $\Sigma_2^0$ . This both provides a simple characterization of the fixpoint hierarchy, and refines existing results on the power of the game quantifier in descriptive set theory. We raise the problem of transfinite fixpoint hierarchies.

**Mathematics Subject Classification.** 03E15, 68Q45.

### 1. INTRODUCTION

For several decades, games have been an essential tool for the study of logic, both in mathematical logic and more recently in computer science. Perhaps the most developed application in computer science logic is the use of Ehrenfeucht–Fraïssé games for first-order logic, and the refinements such as pebble games which correspond to finite variable fragments. However, games are also useful in temporal logic, and in particular for the modal mu-calculus. The ability to switch one’s point of view between logics, automata and games facilitates many results. In particular, the semantics of the modal mu-calculus can be described by means of a *parity game*, that is, a game in which the winning condition concerns the parity of the highest *index* seen infinitely often in the game. This presentation is equivalent to a presentation *via* alternating Rabin automata, or *via* tableaux. In modal

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*Keywords and phrases:* Descriptive set theory, fixpoint, game quantifier, induction.

\* *The main part of this paper was first presented at CSL'99 in Madrid [3]; the final part is based on a talk given at FICS 2001 in Florence, published in RAIRO: Theoret. Informatics Appl., volume 36, No. 2 (2002).*

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mu-calculus, a key issue is the alternation of minimal and maximal fixpoints; in automata, this corresponds to the Rabin index, and in normal form parity games it corresponds to the number of indices.

Games, in the form of Gale–Stewart games, also play an important role in descriptive set theory: they provide a tool with which many of the structure theorems of the classical and effective Borel and Lusin hierarchies can be obtained. The *game quantifier*  $\mathfrak{D}$  takes a game, defined by its set of winning plays, and returns the set of winning positions; the power of this quantifier is the object of our study. Kechris and Moschovakis showed that a  $\Sigma_1^0$  game has a  $\Pi_1^1$  set of winning positions; and Robert Solovay showed that the set of winning positions of a  $\Sigma_2^0$  game is  $\Sigma_1^1$ -inductive. Thomas John studied  $\Sigma_3^0$  games, and the characterization is complex, involving higher-type recursion and certain levels of the constructible universe.

If one looks at the previous paragraph with fixpoint glasses on, one notices that  $\Pi_1^1$  is  $\Pi_1^0$ -inductive, that is, on the first level  $\Sigma_1^\mu$  of the fixpoint alternation hierarchy of arithmetic with fixpoints; and that  $\Sigma_1^1$ -inductive is the second level. It is then natural to ask whether this is coincidence, or whether there is, in arithmetic, a nice relationship between fixpoint alternation and some hierarchy of games, mediated by the game quantifier. One might initially speculate that  $\Sigma_n^0$  games have  $\Sigma_n^\mu$  winning positions, but alas this cannot be true. However, the world of Rabin automata and modal mu-calculus provides a suggestion: the complexity of the Rabin or parity condition corresponds to the complexity of the winning plays, and since the modal fixpoint alternation *is* correlated nicely to that, the next obvious thing to do is to try to find a notion of complexity in arithmetic that corresponds to the Rabin index, and then hope that the correlation still holds in the rather different world of arithmetic. The result of such an exploration is that fixpoint complexity of winning positions does indeed correspond to a natural fine hierarchy of arithmetic, in a way that matches well with the finite automata world; and although the result is pure descriptive set theory, the games used in its proof are natural analogues of games developed for the automata and temporal logic world.

## 2. PRELIMINARIES

### 2.1. NOTATIONS AND BASIC DEFINITIONS

$\omega$  is the set of non-negative integers; variables  $i, j, \dots, n$  range over  $\omega$ . The set of finite sequences of integers is denoted  $\omega^*$ ; finite sequences are identified with integers *via* standard codings; variables  $u, v$  range over  $\omega^*$ . The set of infinite sequences of integers is  ${}^\omega\omega$ ; variables  $\alpha, \beta$  range over  ${}^\omega\omega$ . For  $\alpha \in {}^\omega\omega$ ,  $\alpha(i)$  is the  $i$ 'th element of  $\alpha$ , and  $\alpha(<i)$  is the finite sequence  $\langle \alpha(0), \dots, \alpha(i-1) \rangle$ . Concatenation of finite and infinite sequences is written with concatenation of symbols or with  $\cdot$ , and extended to sets pointwise.

We consider (only) spaces that are the product of copies of  ${}^\omega\omega$  and  $\omega$ ; they are given the product topology, where  $\omega$  carries the discrete topology and  ${}^\omega\omega$  itself

carries the infinite product topology (in which the basic open sets are the sets  $u \cdot {}^\omega\omega$  for every finite sequence  $u$ ). A *pointset*  $P$  is a subset of such a space  $\mathfrak{X}$ ; we write variously  $P(i, \alpha)$  or  $(i, \alpha) \in P$  if  $\mathfrak{X}$  is, for example,  $\omega \times {}^\omega\omega$ . A pointset is *semi-recursive* or  $\Sigma_1^0$  iff it is a recursive union of basic opens, in other words given by a semi-recursive set of prefixes: in particular, a pointset  $P \subseteq {}^\omega\omega$  is  $\Sigma_1^0$  iff  $P = \bigcup_i N_{\varepsilon(i)}$ , where  $N_k$  denotes the basic neighbourhood  $u_k \cdot {}^\omega\omega$  for some recursive enumeration  $k \mapsto u_k$  of the finite sequences  $w^*$ , and  $\varepsilon$  is a recursive function  $\omega \rightarrow \omega$ , otherwise known as a recursive element of  ${}^\omega\omega$ . A *pointclass* is a set of pointsets; if  $\Lambda$  and  $\Lambda'$  are pointclasses, then  $\Lambda \wedge \Lambda'$  is the pointclass  $\{P \cap P' \mid P' \in \Lambda, P' \in \Lambda'\}$  and similarly for  $\vee$  and  $\neg$ ; if  $\Lambda$  is a pointclass on  $\omega \times \mathfrak{X}$ , then  $\exists^\omega \Lambda$  is the pointclass  $\{Q \subseteq \mathfrak{X} \mid \exists P \in \Lambda. x \in Q \Leftrightarrow \exists i. (i, x) \in P\}$ ; similarly for  $\exists^\omega$ . The *Kleene pointclasses* (the arithmetical and analytical hierarchies) are defined by  $\Pi_j^i = \neg \Sigma_j^i$ ;  $\Sigma_{j+1}^0 = \exists^\omega \Pi_j^0$ ;  $\Sigma_0^1 = \Sigma_1^0$ ;  $\Sigma_{j+1}^1 = \exists^\omega \Pi_j^1$ ;  $\Delta_j^i = \Sigma_j^i \cap \Pi_j^i$ . Pointsets in the Kleene pointclasses are definable by formulae of first- and second-order arithmetic in the usual prenex normal form.

For completeness we recall that the boldface classes are given by:  $\Sigma_1^0$  is the class of open sets, and then similarly to the lightface classes; however, we are here concerned mainly with the lightface classes.

Ordinals are ranged over by variables  $\zeta, \xi$ . By  $\omega_1$  we mean the first non-recursive ordinal, not the first uncountable ordinal.

An  $(\omega)$ -*tree* is a prefix-closed subset of  $\omega^*$ . If  $T$  is a tree,  $\alpha$  is an *infinite branch* of  $T$  iff  $\forall i. \alpha(\langle i \rangle) \in T$ . The *body*  $[T]$  of  $T$  is the set of its infinite branches.  $T$  is *recursive* (etc.) iff it is recursive (etc.) as a subset of  $\omega$  *via* the coding of sequences. The following standard fact will be useful:

**Lemma 1.** *If  $P \subseteq {}^\omega\omega$  is  $\Pi_1^0$ , then there is a  $\Pi_1^0$  tree  $T$  such that  $\alpha \in P \Leftrightarrow \alpha \in [T]$ .*

*Proof.* If  $P$  is  $\Pi_1^0$ , by definition it is  $\neg \bigcup_j N_{\varepsilon(j)} = \bigcap_j \overline{N_{\varepsilon(j)}}$  for some recursive  $\varepsilon$ . Put  $T = \{v \mid \forall j. v \cdot {}^\omega\omega \subseteq \overline{N_{\varepsilon(j)}}\}$ . If  $\alpha \in P$ , then  $\forall i. \alpha(\langle i \rangle) \in T$ ; conversely, if  $\alpha \notin P$ , then  $\alpha \in N_k$  some  $k$ , and then there is a prefix  $\alpha(\langle i \rangle) \in N_k$ . Finally,  $T$  is  $\Pi_1^0$  since the test “ $v \cdot {}^\omega\omega \subseteq \overline{N_{\varepsilon(j)}}$ ” is recursive, reducing to “ $v$  does not have  $u_{\varepsilon(j)}$  as a prefix”, where  $u_{\varepsilon(j)}$  is as above.  $\square$

## 2.2. GALE–STEWART GAMES

An infinite game of perfect information, or Gale–Stewart game, on  $\omega$ , is played between two players, Abelard and Eloise. The players take turns, starting with Eloise, to choose a number, so defining a *play* as an infinite sequence  $\alpha \in {}^\omega\omega$ . The game is defined by a *winning condition*  $P \subseteq {}^\omega\omega$ , a set of sequences; if  $\alpha \in P$  (we write also  $P(\alpha)$ ), then Eloise wins the play, otherwise Abelard. A *strategy* for Eloise is a function from partial plays where she is due to move, *i.e.* finite sequences of even length, to integers, telling Eloise her next move. A *winning strategy* for Eloise is one such that if she follows it, she is guaranteed to win the game no matter how Abelard plays. If  $u$  is a partial play in the game  $P$ , then  $P[u]$  denotes the game  $\{\alpha \mid u\alpha \in P\}$ . A *winning position* for Eloise is a partial play  $u$  of even length from which Eloise has a winning strategy for  $P[u]$ ; thus Eloise

has a winning strategy for the game, or *wins the game*, iff  $\langle \rangle$  is a winning position for her.

It is frequently convenient to relax the definition to allow games with *rules* which constrain the choices of the players, and games where the players' turns need not strictly alternate. This is harmless provided that the rules and the turn function are recursive in the partial plays.

For our purposes, it is also useful to permit finite plays where Eloise wins outright at a particular point. A game with such plays can easily be modified to a game with only infinite plays; an important point for us is that we shall always have recursive winning conditions on finite plays.

A game is *determined* if one or other player wins it. By a celebrated theorem of Martin, all games with  $\Delta_1^1$  winning conditions are determined. However, Wolfe much earlier proved determinacy for  $\Sigma_2^0$  games, and it is a generalization of this proof, far easier than Martin's theorem, that will give us our result.

It is convenient to define *cogames* in which Abelard moves first. Now we can extend the definition of Eloise winning position to partial plays  $u$  of odd length by saying that  $u$  is a winning position in the game  $P$  iff Eloise wins the cogame  $P[u]$ .

If  $P \subseteq {}^\omega\omega \times \mathfrak{X}$ , then for each  $x \in \mathfrak{X}$  the set  $\{\alpha \mid (\alpha, x) \in P\}$  defines a game (we call it  $P(\alpha, x)$ ). The *game quantifier* is defined thus:  $\mathfrak{D}\alpha.P(\alpha, x)$  is the set  $\{x \mid \text{Eloise wins the game } P(\alpha, x)\}$ . Although formally defined in terms of strategies, it is intuitively understood as an infinite string of first-order quantifiers:

$$\exists a_0. \forall a_1. \exists a_2. \forall a_3. \dots P(a_0 a_1 \dots, x).$$

Let  $\Gamma$  be a pointclass on  ${}^\omega\omega \times \mathfrak{X}$ ; then  $\mathfrak{D}\Gamma$  is the pointclass

$$\{Q \subseteq \mathfrak{X} \mid \exists P \in \Gamma. Q = \mathfrak{D}\alpha.P(\alpha, x)\}.$$

The following standard fact (see [10]) will be required:

**Lemma 2.** *If  $\Gamma$  is a determined pointclass closed under recursive substitution, then  $\neg\mathfrak{D}\Gamma = \mathfrak{D}\neg\Gamma$ .*

### 2.3. MU-ARITHMETIC

In [9] Lubarsky studies the logic given by adding fixpoint constructors to first-order arithmetic. This logic is also known as LFP in finite model theory, where it is most studied. The logic ("mu-arithmetic" for short) has as basic symbols the following: function symbols  $f, g, h$ ; predicate symbols  $P, Q, R$ ; first-order variables  $x, y, z$ ; set variables  $X, Y, Z$ ; and the symbols  $\vee, \wedge, \exists, \forall, \mu, \nu, \neg, \in$ . As with the modal mu-calculus,  $\neg$  can be pushed inwards to apply only to atomic formulae, by De Morgan duality.

The language has expressions of three kinds, individual terms, set terms, and formulae. The individual terms comprise the usual terms of first-order logic. The set terms comprise set variables and expressions  $\mu(x, X). \phi$  and  $\nu(x, X). \phi$ , where  $X$  occurs positively in  $\phi$ . Here  $\mu$  binds both an individual variable and a set variable;

henceforth we shall often write just  $\mu X. \phi$ , and assume that the individual variable is the lower-case of the set variable. We also use  $\mu$  to mean “ $\mu$  or  $\nu$  as appropriate”. The formulae are built by the usual first-order construction, together with the rule that if  $\tau$  is an individual term and  $\Xi$  is a set term, then  $\tau \in \Xi$  is a formula.

This language is interpreted over the structure  $\omega$  of first-order arithmetic. The semantics of the first-order connectives is as usual;  $\tau \in \Xi$  is interpreted naturally; and the set term  $\mu X. \phi(x, X)$  is interpreted as the least fixpoint of the functional  $X \mapsto \{ m \in \omega \mid \phi(m, X) \}$  (where  $X \subseteq \omega$ ).

Mu-arithmetic has a prenex normal form [2, 9] of the following shape:

$$\tau_n \in \mu X_n. \tau_{n-1} \in \nu X_{n-1}. \tau_{n-2} \in \mu X_{n-2}. \dots \tau_1 \in \nu X_1. \phi$$

where  $\phi$  is first-order—that is, a string of alternating fixpoint quantifiers, and a first-order body. If we refer to a formula in normal form, we shall refer to its components by this notation.

We define levels of the fixpoint alternation hierarchy similarly to the Kleene hierarchies: first-order formulae are  $\Sigma_0^\mu$  and  $\Pi_0^\mu$ , as are set variables. The  $\Sigma_{n+1}^\mu$  formulae and set terms are formed from the  $\Sigma_n^\mu \cup \Pi_n^\mu$  formulae and set terms by closing under (i) the first-order connectives and (ii) the formation of  $\mu X. \phi$  for  $\phi \in \Sigma_{n+1}^\mu$ .

A set  $X \in \omega$  is  $\Sigma_n^\mu$  if  $x \in X \Leftrightarrow \tau(x) \in \Xi(x)$  for some  $\Sigma_n^\mu$  set term  $\Xi$ . Note that this does *not* mean that  $X$  is a fixpoint, only that  $X$  is definable *via* a fixpoint.

A  $\Sigma_1^\mu$  set corresponds to a set definable by an inductive definition over an arithmetic predicate; hence by Kleene’s theorem,  $\Sigma_1^\mu$  is equal to  $\Pi_1^1$ . The higher levels of the fixpoint hierarchy have been characterized by Lubarsky [9] in terms of large admissible ordinals involving a generalized reflection principle, devised for the purpose, and whose essential content is the iteration of the idea  $\Pi_1^1 = \Pi_1^0\text{-IND} = (\Sigma_1 \text{ on } \Delta_1^1)$ ; however, there has not been a simple characterization in terms of existing notions.

#### 2.4. RABIN CONDITIONS AND PARITY GAMES

Consider a (non-deterministic) finite automaton on which Eloise and Abelard play a Gale–Stewart style game by alternately choosing next states. A *Rabin condition* is a winning condition for the game of the following form:

$$\bigvee_{1 \leq i \leq n} (\infty G_i \wedge \neg \infty R_i)$$

where  $G_i$  and  $R_i$  are subsets of states, and  $\infty X$  means that the set  $X$  is met infinitely often during the play.  $n$  is the *Rabin index*.

These *alternating Rabin automata* are important in temporal logic, as they are one characterization of modal mu-calculus. They are equivalent to alternating *parity automata*: a *parity condition* has the form “for given sets  $X_i$ ,  $1 \leq i \leq n$ , of states, the greatest  $j$  such that  $X_j$  occurs infinitely often in the play, is even”. The relationship between parity automata and modal mu-calculus is direct [6], as

the parity condition corresponds to the statement “the highest fixpoint variable regenerated infinitely often is a maximal fixpoint”.

The Rabin index, or the number of sets in a parity condition, correspond to the fixpoint alternation in modal mu-calculus, and it is this that inspires both our question and its solution. (Niwiński [11] gives a survey of all the concepts mentioned here, as part of a study of fixpoint operators on trees.)

### 3. GAMES FOR MU-ARITHMETIC

The familiar Ehrenfeucht–Fraïssé games for first-order logic are used to distinguish structures; one can also define *model-checking games* or semantic games where the object is to determine whether  $\phi(x)$  holds for a formula  $\phi$  and element  $x$  of a given structure. For first-order logic, the game may be defined thus: given a formula  $\phi$  and a structure  $\mathcal{T}$ , a position in the game is a subformula  $\psi$  of  $\phi$  and a valuation of the free variables of  $\psi$  by elements of  $\mathcal{T}$ . If  $\psi$  is a conjunction, then it is Abelard’s turn, and he chooses a conjunct; if a disjunction, then Eloise chooses a disjunct. If  $\psi = \exists x. \psi'$ , then Eloise chooses a value for  $x$  and play moves to  $\psi'$ ; and dually for  $\forall x. \psi'$ . Play terminates at atomic formulae  $P(\vec{x})$ ; Eloise wins the play if  $P(\vec{x})$  holds of the chosen values for  $\vec{x}$ , Abelard otherwise. It is a standard theorem that Eloise wins the game iff  $\phi$  is true. (If  $\phi$  itself has free variables, there is one game for each valuation of them.)

**Remark 3.** Traditionally, the valuation of variables is not explicitly encoded in the position, but read off from the history. This is a vital distinction in the finite model theory use of games, since we do not wish to assume that we can keep arbitrary amounts of information. The notion of pebble game was invented in order to encode the variable assignment in the position, and then the number of pebbles (variables) can be limited, so that we can ask “is there a winning strategy using only the bounded history information available?”. However, we are working in arithmetic, so we have all the coding apparatus we want, and may as well carry the assignment with us; it is purely a matter of convenience.

Games have been extended to LFP in the world of finite model theory, by choosing a candidate fixpoint set  $X$  when one passes through a fixpoint operator. Uwe Bosse [1] has used such games to obtain expressivity results on fragments of LFP. However, such a game is undesirable in arithmetic, since it has second-order positions. A more useful game for mu-arithmetic is defined by adapting the game for parity automata or modal mu-calculus: instead of finite plays, one now has infinite plays, and the winning condition is given by a parity condition.

Given a formula of mu-arithmetic (or indeed FOL with fixpoints in general), the model-checking game has moves as for first-order logic together with the following rules for the fixpoints: if the position is  $\tau \in \mu(x, X). \phi$ , then play moves to the position  $\phi$  with  $x$  valued at the current value of  $\tau$ . It does not matter who moves, but for definiteness say Eloise moves for  $\mu$  and Abelard for  $\nu$ . If the position is  $\tau \in X$ , where  $X$  is bound by  $\mu(x, X). \phi$ , then again play moves to  $\phi$  with  $x$  valued at the current value of  $\tau$ , and we say that we have seen  $X$ . It remains to define the

winning conditions: if play terminates, the play is won as for first-order logic; if the play is infinite, then Eloise wins iff the outermost fixpoint variable seen infinitely often is maximal. If we start with a formula in normal form, then this is exactly a parity condition. We have

**Theorem 4.** *A formula  $\phi(\vec{x})$  of mu-arithmetical holds for some valuation of  $\vec{x}$  exactly if Eloise has a winning strategy for the model-checking game for  $\phi$  with the given initial valuation.*

*Proof.* A full proof of this theorem is quite long; however it is strategically the same as the corresponding proof for modal mu-calculus and parity games. It is also the essential content of Theorem 5 of [2]. Therefore we do not give the proof again here.  $\square$

#### 4. THE POWER OF THE GAME QUANTIFIER

Suppose that a winning condition  $P(\alpha, x)$  for a Gale–Stewart game has a given descriptive complexity: what is the descriptive complexity of  $\mathfrak{G}_\alpha.P(\alpha, x)$ ? If the winning conditions are in the analytical hierarchy, then this is a question intimately related to the structure theory of the hierarchy, and a question that depends on hypotheses outside *ZFC*, in particular, the hypothesis of Projective Determinacy (that all projective games are determined). Given *PD*, the answer is quite simple for analytical games:  $\mathfrak{G}\Sigma_n^1 = \Pi_{n+1}^1$  and dually, so  $\mathfrak{G}$  is a “hermaphrodite” second-order quantifier.

If the winning conditions are below  $\Delta_1^1$ , then determinacy is not an issue, and one can expect unequivocal answers. However, the game quantifier turns out to be quite delicate. The first answer was:

**Theorem 5** (Kechris–Moschovakis).  $\mathfrak{G}\Sigma_1^0 = \Pi_1^1$

Later, Robert Solovay (unpublished, cited in [10], *q.v.* also for the previous theorem) characterized  $\Sigma_2^0$  games, based on Wolfe’s proof of the determinacy of  $\Sigma_2^0$  games.

**Theorem 6** (Solovay).  $\mathfrak{G}\Sigma_2^0 = \Sigma_1^1\text{-IND}$  (that is, sets given via an inductive definition over a  $\Sigma_1^1$  predicate).

A decade or so later, the next step was taken by Thomas John, who studied  $\Sigma_3^0$  games. Unfortunately, the characterization is complex: it involves capturing the levels of Gödel’s *L* at which winning strategies can be found, and is given in terms of higher-type recursion. This appears to be inevitable: the proof of determinacy for  $\Sigma_3^0$  proceeds *via* games in which the positions are themselves games.

There are to my knowledge no published results on  $\Sigma_4^0$  or beyond, until one reaches  $\Delta_1^1$ .

As was remarked in the introduction,  $\Pi_1^1$  is also  $\Pi_1^0\text{-IND}$ ; or in terms of the fixpoint hierarchy,  $\Sigma_1^\mu$ . Then  $\Sigma_1^1\text{-IND}$  is just  $\Sigma_2^\mu$ . We then naturally ask whether  $\Sigma_n^\mu = \mathfrak{G}X$  for some natural class  $X$ . The conjecture that immediately comes to

mind is  $\Sigma_n^\mu = \mathfrak{S}\Sigma_n^0$ ; unfortunately, the complexities of higher-type recursion are not so easily banished. In fact, the game semantics of mu-arithmetic shows that

**Theorem 7.** *For all  $n$ ,  $\Sigma_n^\mu \subseteq \mathfrak{S}\nabla_2^0$ , where  $\nabla_2^0$  denotes the Boolean closure of  $\Sigma_2^0 \cup \Pi_2^0$ .*

*Proof.* Consider a mu-arithmetic formula in normal form; wlog, consider the case of odd  $n$ . The winning condition for the associated game comprises a recursive part dealing with the finite plays, and a parity condition dealing with the infinite plays. The parity condition says that in a play  $\alpha$ , the highest  $X_i$  seen infinitely often is maximal, *i.e.*  $i$  is even. In other words, the condition is

$$\neg\infty X_n \wedge (\infty X_{n-1} \vee (\neg\infty X_{n-2} \wedge \infty X_{n-3} \vee (\dots \infty X_2 \vee \neg\infty X_1) \dots)).$$

Now, the statement “ $X_i$  is seen at position  $j$  of the play  $\alpha$ ” is a recursive predicate of  $\alpha$ ; and the statement  $\infty X_i$  is just  $\forall j. \exists k > j. “X_i$  is seen at  $k”$ , which is  $\Pi_2^0$ . Therefore the entire condition is a Boolean combination of  $\Pi_2^0$  and  $\Sigma_2^0$  statements, Q.E.D.  $\square$

One may equally well use a Rabin condition, although this is less natural.

At this point, it seems “obvious” that the argument should also run backwards. However, model-checking games are a very restricted format of games, and the statement  $\infty X_i$  is apparently a rather restricted form of  $\Pi_2^0$  statement about a play  $\alpha$ ; we wish to make a statement about arbitrary  $\nabla_2^0$  winning conditions. Thus the obvious statement requires some work to prove. The first step is to choose the appropriate fine hierarchy within  $\nabla_2^0$ . One may here choose to follow the pattern of Rabin conditions: by using disjunctive normal form, it is trivial that formulae of the shape  $\bigvee_i (\Sigma_2^0 \wedge \Pi_2^0)$  give a normal form for  $\nabla_2^0$ . However, it is easier and more elegant to follow the pattern of parity conditions, and use a hierarchy known as the *difference hierarchy* (over  $\Sigma_2^0$ ). Difference hierarchies over open sets have been studied long ago in classical descriptive set theory; more recently Victor Selivanov has, in a series of papers, made a study of an abstract fine hierarchy which subsumes, in a certain sense, difference hierarchies: applications include simpler proofs and refinements of Wagner’s hierarchies of  $\omega$ -regular languages [12]. However, we shall not need any of this more general theory; let us just define the hierarchy we need.

The difference hierarchy over  $\Sigma_2^0$  is defined thus:  $\Sigma_1^\partial = \Sigma_2^0$ ;  $\Pi_n^\partial = \neg\Sigma_n^\partial$ ;  $\Sigma_{n+1}^\partial = \Sigma_2^0 \wedge \Pi_n^\partial$ . To provide a simpler base case, let us also define  $\Sigma_0^\partial = \Sigma_1^0$  (which fits into the induction, since  $\Sigma_2^0 \wedge \Pi_1^0 = \Sigma_2^0$ ). The main result is now

**Theorem 8.**  $\mathfrak{S}\Sigma_n^\partial = \Sigma_{n+1}^\mu$  for  $n \geq 0$ .

*Proof.* First consider the easier direction, that  $\Sigma_{n+1}^\mu \subseteq \mathfrak{S}\Sigma_n^\partial$ . This is not trivial: by inspection, the parity condition of rank  $n$  is in  $\Sigma_n^\partial$ , but this is not tight enough. However, if we consider more carefully the winning condition for the game of a  $\Sigma_1^\mu$  formula  $\tau \in \mu X.\phi$ , it says simply “ $X$  is seen finitely often”. Since the only way a play can be infinite is to pass infinitely often through  $X$ , this is equivalent to saying that the play is really finite (and therefore terminates on an outright Eloise



win). Hence the winning condition is really just  $\exists i$ . “Eloise wins outright at  $\alpha(i)$ ”, and since the outright winning conditions are recursive, this is a  $\Sigma_1^0$  statement. Hence  $\Sigma_1^\mu \subseteq \mathfrak{D}\Sigma_1^0 = \mathfrak{D}\Sigma_0^\partial$ . Now an induction following the proof of Theorem 4 gives the rest. (Of course, we already know from Th. 5 that  $\Sigma_1^\mu = \mathfrak{D}\Sigma_1^0$ ; however, the above direct argument of the base case has the advantage of being easy to fit directly into the induction.)

The harder direction is showing that  $\mathfrak{D}\Sigma_n^\partial \subseteq \Sigma_{n+1}^\mu$ . For convenience we shall let Theorem 5 deal with the base case; it is an easy exercise to write down the direct proof using a simplified version of the strategy here. The inductive step is a generalization of Solovay’s result, using a generalization of Wolfe’s determinacy proof. We shall follow, more or less, the presentation of Wolfe’s proof by Moschovakis [10], extending as necessary.

The approach is to define inductively “easy winning positions”, and show that all winning positions are easy. We then inspect the inductive definition, and see that it has the required form.

Suppose we have a  $\Sigma_n^\partial$  winning condition  $P(\alpha, \vec{x})$ ; for notational convenience we omit the parameters  $\vec{x}$ . Then it has the form

$$(\exists i. Q(i, \alpha)) \wedge R(\alpha)$$

where  $Q$  is  $\Pi_1^0$  and  $R$  is  $\Pi_{n-1}^\partial$ . In Solovay’s result, the winning condition is  $\Sigma_2^0 = \Sigma_1^\partial$ , and so there is no  $R$  term; we have to show that the argument still goes through with this additional term, so allowing us to use the proof in an induction on  $n$ .

We start with a trivial but critical observation:

$$(\exists i. Q(i, \alpha)) \wedge R(\alpha) \Leftrightarrow \exists i. (Q(i, \alpha) \wedge R(\alpha)).$$

The second observation is that (by Lem. 1) since, for a given  $i$ ,  $Q(i, \alpha)$  is a  $\Pi_1^0$  predicate of  $\alpha$ , there is a  $\Pi_1^0$  tree  $T_i \subseteq \omega^*$  such that  $Q(i, \alpha) \Leftrightarrow \alpha \in [T_i]$ .

We shall build the set of winning positions by a transfinite induction; to explain the technique let us first consider the base case on its own. We can define a set of *really* easy winning positions: let

$$W^0 = \{ u \mid \exists i. \text{“Eloise wins the game } H_i^0[u] = (Q(i, \alpha) \wedge R(\alpha))[u] \text{”} \}.$$

Strictly, if  $u$  is an odd length sequence, we mean the cogame  $H_i^0[u]$ ; we will assume henceforth that “game” means “game” for even length  $u$  and “cogame” for odd length  $u$ . Now, it is clear that if  $u \in W^0$ , then Eloise wins the game  $P[u]$ .

To extend this base case into an inductive step, we first reformulate this definition using the second observation:

$$W^0 = \{ u \mid \exists i. \text{“Eloise wins the game } H_i^0[u] = (R(\alpha) \wedge \forall k. \alpha(\langle k \rangle) \in T_i)[u] \text{”} \}.$$

So the “really easy” winning positions can be thought of as the places where Eloise knows how to win  $R$  while also staying within  $T_i$ . Now the inductive step is to

look at places where Eloise knows how to win  $R$  while staying within the winning positions for easier games. That is, if  $W^\xi$  is defined for  $\xi < \zeta$ , let  $W^{<\zeta} = \bigcup_{\xi < \zeta} W^\xi$ , and define the game

$$H_i^\zeta(\alpha) = R(\alpha) \wedge \forall k. \alpha(<k) \in W^{<\zeta} \cup T_i.$$

Then we define

$$W^\zeta = \{ u \mid \exists i. \text{“Eloise wins the game } H_i^\zeta[u]\text{”} \}.$$

We show by induction that if  $u \in W^\zeta$ , then  $u$  is a winning position in the original game  $P$ . So, let  $u \in W^\zeta$ . Then for some  $i$ , Eloise wins  $H_i^\zeta[u]$ ; let Eloise play according to her winning strategy to produce a play  $\alpha$ . Then by definition,  $R(\alpha) \wedge \forall k. \alpha(<k) \in W^{<\zeta} \cup T_i$ . If play ever reached a position  $v = \alpha(<k) \in W^{<\zeta}$ , then by induction Eloise could have won  $P[v]$ , so by switching to her winning strategy there, instead of continuing with  $\alpha$ , she can win  $P[u]$ . If not, then  $R(\alpha) \wedge \forall k. \alpha(<k) \in T_i$ ; but then  $\alpha \in [T_i]$ , so  $Q(i, \alpha) \wedge R(\alpha)$ , so Eloise wins the play  $P$ .

Now,  $W^\zeta$  is an increasing chain, and so (by cardinality) closes at some  $W = W^\kappa = W^{<\kappa}$ . We now show that if  $u \notin W^\kappa$ , then Abelard wins  $P[u]$ . So, let  $u = a_0 \dots a_j \notin W^\kappa$ . By definition, for all  $i$ , Abelard wins  $H_i^\kappa[u]$ . (Note: see Rem. 9.) Let Abelard continue to play according to his winning strategy for  $H_0^\kappa[u]$ , generating a play  $\alpha = ua_{j+1} \dots$ . First suppose that  $\forall k. \alpha(<k) \in W^{<\kappa} \cup T_o$ ; then we must have  $\alpha \notin R$ , so  $\alpha \notin P$ , and so Abelard has won  $P$ . On the other hand, suppose at some  $j_0$  we have  $u_0 = \alpha(<j_0) \notin W^{<\kappa} \cup T_0$ . Then firstly  $u_0 \notin T_0$ , and since  $T_0$  is a tree, any extension of  $u_0$  is also  $\notin T_0$ . Secondly,  $W^{<\kappa} = W^\kappa$ , so  $u_0 \notin W^\kappa$ , so Abelard wins all  $H_i^\kappa[u_0]$ . So now let Abelard switch to his strategy for  $H_1^\kappa$ . Now repeat the argument: either Abelard plays and wins with  $R$ , or there is a  $u_1 \notin W^{<\kappa} \cup T_1$ . If the process of finding  $u_0, u_1, \dots$  continues for ever, then the final play  $\alpha$  is not an infinite branch of any  $T_i$ , and so  $\neg \exists i. Q(i, \alpha)$  and again Abelard has won the play.

We have now shown that  $u \in W$  iff Eloise wins the game  $P[u]$ , in other words that  $W = \mathfrak{D}\alpha.P(u \cdot \alpha)$ . All that remains is to recast the inductive definition in terms of  $\mathfrak{D}$  and mu-arithmetic:

$$W = \mu(w, W). \exists i. \mathfrak{D}\alpha. (R(w \cdot \alpha) \wedge \forall k. ((w \cdot \alpha)(<k) \in W \vee (w \cdot \alpha)(<k) \in T_i)).$$

Now,  $T_i$  is a  $\Pi_1^0$  set, and therefore  $\forall k. \dots$  is also  $\Pi_1^0$ ;  $R$  is  $\Pi_{n-1}^0$ , and so the body of the game quantified expression is also  $\Pi_{n-1}^0$ . Therefore by the induction hypothesis and duality,  $\mathfrak{D}\alpha. \dots$  is equal to some  $\Pi_n^\mu$  expression  $\phi$ , and so  $W$  is indeed  $\Sigma_{n+1}^\mu$ ; Q.E.D.  $\square$

**Remark 9.** At the point referring to this remark, we seem to be assuming the determinacy of  $H_i^\kappa$ . At first sight, this seems odd, since the set  $W^\kappa$  occurring in the definition is rather complex; however, the determinacy theorems involve the boldface classes, not the lightface, and any subset of the integers is  $\Delta_1^0$ , so the

determinacy theorems apply. In fact, as previously mentioned, this proof is mostly Wolfe's, and was devised to show determinacy. This works because at the end we have constructed a set  $W$  such that Eloise wins  $P$  iff  $\langle \rangle \in W$ , and Abelard wins  $P$  iff  $\langle \rangle \notin W$ . To show determinacy, we use  $\Sigma_2^0$  rather than  $\Sigma_2^0$ ; the only difference this makes is that  $Q$  is  $\Pi_1^0$  instead of  $\Pi_1^0$ , so the trees  $T_i$  are not necessarily  $\Pi_1^0$ . The argument goes through to produce the set  $W$ ; thus we have an inductive proof of the determinacy of  $\Sigma_n^\partial$  games, and then we look at the lightface version in order to obtain the complexity results we really want.

It is worth mentioning, as already noted in [6], that the use of fixpoint notation makes Wolfe's proof itself rather more transparent. The determinacy of (boldface)  $\nabla_2^0$  games was studied by Büchi [4] in the context of monadic second-order logic; again the use of fixpoint notation allows a transparent presentation, since the formulation of Theorem 8 works also in the boldface case.

As was mentioned above, we could as well use the Rabin style hierarchy as the difference hierarchy; indeed,  $\Sigma_{2n}^\partial$  is equal to the Rabin class  $\bigvee_{1 \leq i \leq n} (\Sigma_2^0 \wedge \Pi_2^0)$ , and the odd levels of the difference hierarchy correspond to Rabin conditions with one disjunct being simply  $\Sigma_2^0$ .

Since the above proof is also defining a winning strategy, it follows from Lubarsky's characterization that:

**Corollary 10.** *A  $\Sigma_n^\partial$  game has a winning strategy in the  $\omega^{+(n+1)}$ 'th level of Gödel's  $L$ , where  $\omega^{+n}$  is the first  $n$ -reflecting admissible [9] after  $\omega$ .*

A result that is already known, but which is much more easily seen from this approach, is:

**Corollary 11.** *The fixpoint definable sets of integers are strictly contained in  $\Delta_2^1$ .*

*Proof.* Because the game quantifier is self-dual for reasonable point classes (Lem. 2) and because if  $U(i, \alpha, x) \subseteq \omega \times {}^\omega\omega \times \mathfrak{X}$  is universal for  $\Gamma$  on  ${}^\omega\omega \times \mathfrak{X}$  then  $\exists \alpha. U(i, \alpha, x) \subseteq \omega \times \mathfrak{X}$  is universal for  $\exists \Gamma$  on  $\mathfrak{X}$ , the game quantifier preserves the strictness of reasonable hierarchies. In particular, it preserves the arithmetic and hyperarithmetic hierarchies. By the main theorem, the fixpoint definable sets are contained in  $\exists \nabla_2^0$ ; but  $\Delta_2^1$  contains  $\exists \Delta_1^1$ , a much larger set.  $\square$

The fact that fixpoint definable sets are contained in  $\Delta_2^1$  follows from the classical closure of  $\Delta_2^1$  under inductive definitions; the strictness of the containment is already established by classical ([8], V.5) results to the effect that  $\Delta_2^1$  cannot be approximated "from below", and in some sense more strongly by Lubarsky's analysis, as the ordinals  $\omega^{+n}$  are all less (and in some sense much less) than the first non- $\Delta_2^1$  ordinal. However, the game characterization is technically far simpler, and gives a more transparent meaning to "much less":  $\nabla_2^0$  is "much smaller" than  $\Delta_1^1$  in a well understood sense.

## 5. REPRISE

The characterization we have established here is interesting in both directions. The fact that  $\mathfrak{D}\Sigma_n^\partial$  is characterized by a natural and useful pointclass extends a little the point at which games become inherently difficult. Perhaps the other direction is more interesting: fixpoint alternation is notoriously incomprehensible, so characterizing it in terms of a simple hierarchy of games is helpful—and arguably more useful than the admissible-recursion-theoretic characterization. It also reinforces a slightly different view on the traditional world of automata with Rabin and parity conditions: “infinitely often” is a fundamental concept in temporal logics, but really it is a fundamental concept because it is  $\Pi_2^0$ . Indeed, within the framework of recursion theory, any  $\Pi_2^0$  statement about  $\alpha$  is of the form “infinitely often something happens at  $\alpha(i)$ ”, where in general “something” includes statements about the previous and future elements of  $\alpha$ .

## 6. THE QUESTION OF TRANSFINITE EXTENSION

One can ask whether our characterization here extends at all. A possibly interesting issue here is that there is something of a mis-match between the hierarchies: the first natural stopping point for a transfinite extension of the difference hierarchy is  $\omega_1$ , whereas any transfinite fixpoint hierarchy will have no natural stopping point before an otherwise unknown and extremely large ordinal.

Attempting to analyse the possible extension into the transfinite of Theorem 8 leads quickly into rather delicate recursion theory, and further investigation is required to address the problem. In this section, we shall just outline the direction such an investigation will take, and point out some of the difficulties.

In order to extend Theorem 8 into the transfinite, one must first formulate it. This is itself not without difficulties; however, the difference hierarchy has a classical extension.

### 6.1. THE TRANSFINITE DIFFERENCE HIERARCHY

Transfinite difference hierarchies over the open sets were studied almost a century ago by Hausdorff; in the 60s an abstract study of difference hierarchies and “alternating chains” was undertaken by Addison, although regrettably most of the results on transfinite hierarchies were in a planned paper that never appeared (to my knowledge). Hinman and Burgess also used difference hierarchies to analyse Kolmogorov’s  $R$ -sets, giving results intimately connected to our aim here. Part of the purpose of extending Theorem 8 is to find the parts of that work that have somewhat simpler formulations analogous to those in the theory of automata, where transfinite hierarchies have been studied by Büchi, Landweber, Barua, Selivanov, and others.

There are several ways to formulate the definitions. One is: given a class  $\mathcal{S}$  of sets, and a sequence  $S_0, S_1, \dots$  of sets in  $\mathcal{S}$ , the *difference kernel*  $\partial(S_0, \dots)$  is the set of  $x$  such that the least  $i$  such that  $x \notin S_i$  is odd (extending the sequence

by an empty set if necessary). For example,  $\partial(X, Y, Z) = X \wedge (\neg Y \vee Z)$ . This extends to transfinite sequences, where limit ordinals are even. Then  $\partial_\zeta(\mathcal{S})$  is the class of sets representable as a difference kernel over  $\mathcal{S}$  of length  $\zeta$ . This definition coincides at finite levels with the earlier definition, for reasonable  $\mathcal{S}$ .

The following is the analogue of the relationship between parity (Mostowski) acceptance conditions for automata, and Rabin chain conditions: Let  $S_0, \dots$  be a sequence. Define  $R_\zeta = \bigcap_{\xi \leq \zeta} S_\xi$ . Then  $\partial(S_0, \dots) = \bigcup_\zeta (R_{2\zeta} - R_{2\zeta+1})$ .

**Example.** Let  $S_0, S_1, \dots, S_\omega$  be a sequence of length  $\omega + 1$ . The difference kernel of the sequence is

$$\left( \bigcup_i (\bigcap_{j \leq i} S_{2j} - \bigcap_{j \leq i} S_{2j+1}) \right) \vee (\bigcap_{i < \omega} S_i \wedge S_\omega).$$

The following “well-known” result on the transfinite difference hierarchy over Kleene pointclasses is the motivation for extending Theorem 8:

**Fact 12.**  $\partial_{<\omega_1}(\Sigma_n^0) = \Delta_{n+1}^0$

and in particular,  $\Sigma_{<\omega_1}^2 = \Delta_3^0$ . So if Theorem 8 extended neatly into the transfinite, we would have a characterization of  $\mathfrak{D}\Delta_3^0$  in terms of transfinite fixpoint iteration, as close to  $\mathfrak{D}\Sigma_3^0$  as we could hope.

## 6.2. TRANSFINITE FIXPOINT ALTERNATION

It is well known that the arithmetical hierarchy can be extended to form the transfinite arithmetical hierarchy, by letting  $\Sigma_\zeta^0$  comprise recursive unions of sets each in  $\bigcup_{\xi < \zeta} \Pi_\xi^0$ , and as a syntactic manipulation this has the advantage that the syntax of formulae remains recursive. One could naively do the same with  $L\mu$ : for example, to go one step beyond the finite, we allow would recursive unions (or intersections) of fixpoint formulae: let  $R: \omega \rightarrow L\mu$  be a recursive enumeration of formulae of  $L\mu$ , and say that for any recursive  $f: \omega \rightarrow \omega$ ,  $\bigvee_{i < \omega} R(f(i))$  is a formula. An enumeration of these formulae is then given *via* an enumeration of the  $f$ . If we now close under positive first-order operators and least fixpoint, we have an apparently plausible definition of  $\Sigma_\omega^\mu$ , which is clearly more expressive than  $L\mu$ .

There are standard reasons why this approach is too naive, which we describe shortly; however, it is interesting to run with it and see another problem emerge.

Consider such a formula  $\tau \in \mu(x, X) \cdot \bigwedge_i \phi_i$ , where, say, each  $\phi_i = R(f(i))$  is  $\Pi_i^\mu$ , of the form  $\tau_i^0 \in \nu Z_i^0 \cdot \tau_i^1 \in \mu Z_i^1 \dots$ . The satisfaction game for this formula has the usual rules, with the extension that at the infinite conjunction, Abelard chooses some  $i$  and play moves to a position with  $\phi_i$  as the formula. By extension of the usual arguments, the formula is true if Eloise can win the game where on every play the outermost (least  $j$ ) variable seen infinitely often is a maximal fixpoint variable; that is, is a  $Z_i^{j_0}$  for some even  $j_0$ . In particular,  $X$  must be seen finitely often,

and therefore play must get stuck in one conjunct, and thus there is some particular  $i_0$  and outermost even  $j_0$  for which  $Z_{i_0}^{j_0}$  appears infinitely often. Hence the winning condition boils down to “ $X$  fin. often”  $\wedge$  “least  $j$  seen inf. often is even”. Considering  $X$  as  $Z^{-1}$ , this is an infinite parity condition.

Now take  $S_{j+1}$  to be the set of game plays in which  $Z^j$  occurs finitely often, and  $S_0$  to be plays where  $X$  occurs finitely often; the infinite parity condition is the difference kernel of the  $\omega$ -sequence  $S_0, S_1, \dots$

This is somewhat disturbing, because now consider a formula

$$\sigma \in \nu(y, Y). \tau \in \mu(x, X). \bigwedge_i \phi_i,$$

with  $\phi_i$  as before, which is in what we would naturally call  $\Pi_{\omega+1}^\mu$ . The satisfaction game for this formula is just as before, except that now  $Y$  may occur infinitely often on a winning run; taking  $S_{-1}$  to be plays where  $Y$  occurs finitely often, this is *also* the difference kernel of an  $\omega$ -sequence  $S_{-1}, S_0, \dots$ . Hence there is no obvious difference between the complexity of the winning conditions for the satisfaction games for these two formulae.

The standard reason why the above candidate for transfinite fixpoint alternation is not natural is the following: the restriction to recursive unions of  $L\mu$  formulae is unreasonable, because already in  $L\mu$  we can define far more complex sets, and (unlike the case of the hyperarithmetical hierarchy) we can define well-orderings much longer than  $\omega_1$ . Thus the more natural extension to level  $\omega$  would be to allow the function  $f$  to be  $L\mu$  definable rather than just recursive. This now has a dramatic effect on the satisfaction game, for at the infinite con-/disjunction, play moves to a new position which is not just a recursive function of the previous position, but any  $L\mu$  definable function of the previous position. Hence the rules of the game are no longer just recursive, and the winning conditions (into which the rules are incorporated) are *prima facie* themselves now arbitrary  $L\mu$ , so the strategies are *prima facie* vastly more complex.

This rather curious situation invites continued investigation, which will depend heavily on recursion theory from the 1970s and 1980s. In [8], Hinman studied the finite levels of an effective version of the so-called hierarchy of  $R$ -sets ( $R$  being Kolmogorov’s operator). He showed, indeed, that each level is equal to the sets inductively definable over the previous level, which implies that the levels coincide with the levels of the fixpoint hierarchy, and therefore that the associated ordinals (which he called  $\nu_n$ ) are the same as Lubarsky’s  $n$ -reflecting admissibles. On the other hand, Burgess [5] studied the classical  $R$ -hierarchy, and establishes a relation between the difference hierarchy over  $\Sigma_2^0$  and the classical hierarchy. However, I am not aware of such results on the transfinite part of the effective  $R$ -hierarchy. It is also possible that finer hierarchies such as the Wadge hierarchy and Selivanov’s fine hierarchies [12] play a part in the solution, but this is not yet clear.

*Acknowledgements.* From 1997 to 2002 I was supported by an Advanced Fellowship (AF/97/0322) from the United Kingdom Engineering and Physical Sciences Research

Council; also BRICS, the Danish National Research Foundation Centre for Basic Research In Computer Science, supported a year's visit to Aarhus during which most of this work was done.

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Communicated by A. Labella.