# The near field refractor 

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#### Abstract

We present an abstract method in the setting of compact metric spaces which is applied to solve a number of problems in geometric optics. In particular, we solve the one source near field refraction problem. That is, we construct surfaces separating two homogeneous media with different refractive indices that refract radiation emanating from the origin into a target domain contained in an $n-1$ dimensional hypersurface. The input and output energy are prescribed. This implies the existence of lenses focusing radiation in a prescribed manner.


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## 1. Introduction

We present in this paper an abstract method, having general interest, that can be applied to prove existence of solutions to a number of problems in geometric optics relative to refraction. The method is formulated in the abstract setting of compact metric spaces and it is based on the ideas of concave and convex mappings and the existence of families of functions that play the role of building blocks satisfying certain properties. The application to show existence of solutions to various problems then consists in selecting the appropriate maps and the appropriate class of building blocks related to the specific problem.

A main application of this method considered in the paper is to solve the one source near field refractor problem, that is, to show existence of surfaces that refract radiation when the output and input intensities are prescribed. More precisely, we have a domain $\Omega$ in the unit sphere $S^{n-1}$ and a domain $D$ contained in an $n-1$ dimensional surface in $\mathbb{R}^{n} ; D$ is referred as the target domain or screen to be illuminated. We also have two homogeneous and isotropic media I and II with refractive indices $n_{1}$ and $n_{2}$, respectively, and suppose that from a point $O$ surrounded by medium I, light emanates with intensity $f(x)$ for $x \in \Omega$, and $D$ is surrounded by media II. We are also given in $D$ a Radon measure $\mu$ and the energy conservation equation $\int_{\Omega} f(x) d x=\mu(D)$. We prove the existence of an optical surface $\mathcal{R}$ parameterized by $\mathcal{R}=\{\rho(x) x: x \in \bar{\Omega}\}$, interface between media I and II, such that all rays refracted by $\mathcal{R}$ into medium II illuminate the object $D$, and the prescribed illumination intensity distribution at $D$ is $\mu$. Of course, some

[^0]conditions on the relative position of $D$ and the set of directions in $\Omega$ are needed to illuminate $D$. This implies that one can design a lens refracting light beams so that the screen $D$ is illuminated in a prescribed way. The lens is bounded by two optical surfaces, the "outer" surface is $\mathcal{R}$ and the "inner" one is a sphere with center at the point from where the radiation emanates.

To implement the application of our abstract result to this case, we determine that the building blocks to construct the surface solution are Descartes ovals. Descartes ovals refract all light rays emanating from a point $O$ into a fixed point $P$; see Figs. 1 and 2. The solution of the near field refraction problem depends in a essential way of a novel and very delicate study of the eccentricity of the ovals and its approximation properties, Section 4. This geometry is much more complicated that the one needed for the solution to the far field problem solved in [5] using mass transport. In particular, existence of solutions for the far field refractor problem can be obtained directly with this abstract method, Section 7.

Geometric optics problems - far and near field - received recently attention because of both its applications and their mathematical interest and difficulty. To put our results in perspective, we enumerate some related results. The problem of the far field reflector has been considered by several authors, both mathematicians and engineers. For example, existence and uniqueness up to dilations of solutions for the far field reflector problem were proved by Caffarelli and Oliker in [3] and Wang in [9], and for nonisotropic media by Caffarelli and Huang [2]. $C^{1}$ regularity of solutions for the far field reflector was established in [1]. The near field reflector problem was considered by Kochengin and Oliker in [7], and in recent work by Karakhanyan and Wang [8]. The far field refractor problem was for the first time considered by the authors, and existence and uniqueness up to dilations of solutions were established in [5]. Refraction problems are in general more involved than reflection problems because of physical constraints. A difference between near and far field problems is that the latter can be cast in the frame of optimal transportation. Instead, near field problems are in general not optimal transportation problems which makes their mathematical treatment more difficult. In particular, the presence of $\rho$ in the matrix $\mathcal{A}$ and on the right hand side of the pde (A.12), indicates the problem is not an optimal transport problem. We mention that some results for the near field refractor problem have been announced in [4].

The plan of the paper is the following. Section 2 contains the main results in the paper where we develop the abstract method. Section 3 describes the Snell law and the physical constraints of refraction. Section 4 contains our study of Cartesian ovals and estimates that are essential in the application to the near field problem. In Section 5 we describe the assumptions on the domains $\Omega$ and $D$ and solve the near field problem when $\kappa<1$. Similar existence results when $\kappa>1$ are proved in Section 6. In Section 7 we show further applications of our method: the far field refractor problem and the second boundary value problem for the Monge-Ampère equation.

Finally, the pde governing the near field refractor problem is a fully nonlinear equation of Monge-Ampère type whose derivation is quite complicated and it is included in Appendix A.

## 2. Continuous mappings and measure equations

Let $X, Y$ be compact metric spaces, and $\omega$ a Radon measure on $X$. Let $Y^{X}$ denote the class of all set-valued maps $\Phi$ from $X$ to $Y$ such that $\Phi(x)$ is single-valued for a.e. $x$ with respect to the measure $\omega$. We say that the map $\Phi \in Y^{X}$ is continuous at $x_{0} \in X$ if given $x_{k} \rightarrow x_{0}$ and $y_{k} \in \Phi\left(x_{k}\right)$, there exists a subsequence $y_{k_{j}}$ and $y_{0} \in \Phi\left(x_{0}\right)$ such that $y_{k_{j}} \rightarrow y_{0}$, as $j \rightarrow \infty$. Let $C(X, Y)$ denote the class of all $\Phi \in Y^{X}$ such that $\Phi$ is continuous in $X$; and let $C_{s}(X, Y)$ denote the class of $\Phi \in C(X, Y)$ such that $\Phi(X)=Y$.

Lemma 2.1. Given $\Phi \in C_{s}(X, Y)$, the set function defined by

$$
M_{\Phi}(E)=\omega\left(\Phi^{-1}(E)\right)
$$

is a Radon measure on $Y$.
Proof. The set $\mathcal{C}=\left\{E \subset Y: \Phi^{-1}(E)\right.$ is $\omega$-measurable $\}$ is a $\sigma$-algebra containing all Borel sets in $Y\left(\Phi^{-1}(E)=\right.$ $\{x \in X: \Phi(x) \cap E \neq \emptyset\})$. Indeed, $\Phi^{-1}(\emptyset)=\emptyset, \Phi^{-1}(Y)=X, \Phi^{-1}\left(\bigcup_{i=1}^{\infty} E_{i}\right)=\bigcup_{i=1}^{\infty} \Phi^{-1}\left(E_{i}\right), \Phi^{-1}\left(E^{c}\right)=$ $\left(\Phi^{-1}(E)\right)^{c} \cup\left(\Phi^{-1}(E) \cap \Phi^{-1}\left(E^{c}\right)\right)$, and $\omega\left(\left(\Phi^{-1}(E) \cap \Phi^{-1}\left(E^{c}\right)\right)\right)=0$. If $K$ is compact in $Y$, then $\Phi^{-1}(K)$ is compact in $X$. In fact, let $\left\{x_{k}\right\} \subset \Phi^{-1}(K)$, and $y_{k} \in \Phi\left(x_{k}\right) \cap K$. Since $X$ is compact and $\Phi$ is continuous, there exist subsequences $\left\{x_{k_{j}}\right\}$ and $\left\{y_{k_{j}}\right\}$ such that $x_{k_{j}} \rightarrow x_{0}$ and $y_{k_{j}} \rightarrow y_{0}$ with $y_{0} \in \Phi\left(x_{0}\right)$, that is, $x_{0} \in \Phi^{-1}(K)$. To show the
$\sigma$-additivity, let $\left\{E_{j}\right\}$ be a disjoint sequence of sets in $\mathcal{C}$. Then $M_{\Phi}\left(\bigcup_{j=1}^{\infty} E_{j}\right)=\omega\left(\Phi^{-1}\left(E_{1}\right)\right)+\sum_{k=2}^{\infty} \omega\left(\Phi^{-1}\left(E_{k}\right) \backslash\right.$ $\left.\bigcup_{i=1}^{k-1} \Phi^{-1}\left(E_{i}\right)\right)=\sum_{k=1}^{\infty} M_{\Phi}\left(E_{k}\right)$.

Let $C(X)$ denote the set of continuous functions in $X$ with the topology of uniform convergence.
Definition 2.2. If $\mathcal{F} \subset C(X)$ and $\mathcal{T}: \mathcal{F} \rightarrow C_{s}(X, Y)$, we say that $\mathcal{T}$ is continuous at $\phi \in \mathcal{F}$, if whenever $\phi_{j} \in \mathcal{F}$, $\phi_{j} \rightarrow \phi$ uniformly in $X, x_{0} \in X$, and $y_{j} \in \mathcal{T}\left(\phi_{j}\right)\left(x_{0}\right)$, then there exists a subsequence $y_{j \ell}$ such that $y_{j \ell} \rightarrow y_{0}$ with $y_{0} \in \mathcal{T}(\phi)\left(x_{0}\right)$.

Lemma 2.3. If $\mathcal{F} \subset C(X), \mathcal{T}: \mathcal{F} \rightarrow C_{s}(X, Y)$ is continuous at $\phi \in \mathcal{F}$, and $\phi_{j} \rightarrow \phi$ in $C(X)$ with $\phi_{j} \in \mathcal{F}$, then $M_{\mathcal{T}\left(\phi_{j}\right)} \rightarrow M_{\mathcal{T}(\phi)}$ weakly.

Proof. It is enough to show that

$$
\begin{equation*}
\limsup _{j \rightarrow \infty} M_{\mathcal{T}\left(\phi_{j}\right)}(K) \leqslant M_{\mathcal{T}(\phi)}(K), \quad \text { for all } K \subset Y \text { compact }, \tag{2.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\liminf _{j \rightarrow \infty} M_{\mathcal{T}\left(\phi_{j}\right)}(G) \geqslant M_{\mathcal{T}(\phi)}(G), \quad \text { for all } G \subset Y \text { open } . \tag{2.2}
\end{equation*}
$$

To prove (2.1), we show that $\lim \sup _{j \rightarrow \infty} \mathcal{T}\left(\phi_{j}\right)^{-1}(K) \subset \mathcal{T}(\phi)^{-1}(K)$. Let $x_{0} \in \mathcal{T}\left(\phi_{j}\right)^{-1}(K)$. So there is $y_{j} \in$ $\mathcal{T}\left(\phi_{j}\right)\left(x_{0}\right) \cap K$, and since $\mathcal{T}$ is continuous at $\phi$, there exists a subsequence $y_{j_{\ell}}$ such that $y_{j_{\ell}} \rightarrow y_{0}$ with $y_{0} \in \mathcal{T}(\phi)\left(x_{0}\right)$. Since $y_{0} \in K$, we have $x_{0} \in \mathcal{T}(\phi)^{-1}(K)$. Hence

$$
\begin{aligned}
\limsup _{j \rightarrow \infty} M_{\mathcal{T}\left(\phi_{j}\right)}(K) & =\underset{j \rightarrow \infty}{\limsup } \omega\left(\mathcal{T}\left(\phi_{j}\right)^{-1}(K)\right) \leqslant \omega\left(\limsup _{j \rightarrow \infty} \mathcal{T}\left(\phi_{j}\right)^{-1}(K)\right) \\
& \leqslant \omega\left(\mathcal{T}(\phi)^{-1}(K)\right)=M_{\mathcal{T}(\phi)}(K)
\end{aligned}
$$

To prove (2.2), we show that $\mathcal{T}(\phi)^{-1}(G) \backslash E_{0} \subset \liminf _{j \rightarrow \infty} \mathcal{T}\left(\phi_{j}\right)^{-1}(G)$, with $\omega\left(E_{0}\right)=0$. Indeed,

$$
\begin{aligned}
\limsup _{j \rightarrow \infty}\left(\mathcal{T}\left(\phi_{j}\right)^{-1}(G)\right)^{c} & \subset \limsup _{j \rightarrow \infty}\left[\left(\mathcal{T}\left(\phi_{j}\right)^{-1}(G)\right)^{c} \cup\left(\mathcal{T}\left(\phi_{j}\right)^{-1}(G) \cap \mathcal{T}\left(\phi_{j}\right)^{-1}\left(G^{c}\right)\right)\right] \\
& =\underset{j \rightarrow \infty}{\limsup \mathcal{T}\left(\phi_{j}\right)^{-1}\left(G^{c}\right)} \\
& \subset \mathcal{T}(\phi)^{-1}\left(G^{c}\right) \quad \text { since } G^{c} \text { is compact because } Y \text { is compact } \\
& =\left(\mathcal{T}(\phi)^{-1}(G)\right)^{c} \cup\left[\mathcal{T}(\phi)^{-1}(G) \cap \mathcal{T}(\phi)^{-1}\left(G^{c}\right)\right]:=\left(\mathcal{T}(\phi)^{-1}(G)\right)^{c} \cup E_{0},
\end{aligned}
$$

with $\omega\left(E_{0}\right)=0$, since $\mathcal{T}(\phi)$ is single-valued except on a set of $\omega$-measure zero. Therefore

$$
\begin{aligned}
\liminf _{j \rightarrow \infty} M_{\mathcal{T}\left(\phi_{j}\right)}(G) & =\liminf _{j \rightarrow \infty} \omega\left(\mathcal{T}\left(\phi_{j}\right)^{-1}(G)\right) \\
& \geqslant \omega\left(\liminf _{j \rightarrow \infty} \mathcal{T}\left(\phi_{j}\right)^{-1}(G)\right) \geqslant \omega\left(\mathcal{T}(\phi)^{-1}(G)\right)=M_{\mathcal{T}(\phi)}(G) .
\end{aligned}
$$

### 2.1. Concave case

Let

$$
C^{+}(X)=\{f: f \text { is continuous and positive in } X\} .
$$

In this subsection, we consider classes $\mathcal{F} \subset C^{+}(X)$ satisfying the following condition:
(A1) if $f_{1}, f_{2} \in \mathcal{F}$, then $f_{1} \wedge f_{2}=\min \left\{f_{1}, f_{2}\right\} \in \mathcal{F}$.

We say that the class $\mathcal{F} \subset C^{+}(X)$ is $\mathcal{T}$-concave if $\mathcal{F}$ satisfies (A1) and there exists a map $\mathcal{T}: \mathcal{F} \rightarrow C_{s}(X, Y)$ that is continuous at each $\phi \in \mathcal{F}$ and the following condition holds:
(A2) if $\phi_{1}\left(x_{0}\right) \leqslant \phi_{2}\left(x_{0}\right)$, then $\mathcal{T}\left(\phi_{1}\right)\left(x_{0}\right) \subset \mathcal{T}\left(\phi_{1} \wedge \phi_{2}\right)\left(x_{0}\right)$.
We also introduce the following condition on the class $\mathcal{F}$ :
(A3) For each $y_{0} \in Y$ there exists an interval ( $\alpha_{y_{0}}, \beta_{y_{0}}$ ) and a family of functions $\left\{h_{t, y_{0}}(x)\right\}_{\alpha_{y_{0}}<t<\beta_{y_{0}}} \subset \mathcal{F}$ satisfying
(a) $y_{0} \in \mathcal{T}\left(h_{t, y_{0}}\right)(x)$ for all $x \in X$,
(b) $h_{t, y_{0}} \leqslant h_{s, y_{0}}$ for $t \leqslant s$,
(c) $h_{t, y_{0}} \rightarrow 0$ uniformly as $t \rightarrow \alpha_{y_{0}}$,
(d) $h_{t, y_{0}}$ is continuous in $C(X)$ with respect to $t$, i.e., $\max _{x \in X}\left|h_{t^{\prime}, y_{0}}(x)-h_{t, y_{0}}(x)\right| \rightarrow 0$ as $t^{\prime} \rightarrow t$, for $\alpha_{y_{0}}<$ $t<\beta_{y_{0}}$.

Remark 2.4. Notice that (A3)(a) implies that $M_{\mathcal{T}\left(h_{t, y_{0}}\right)}=\omega(X) \delta_{y_{0}}$ for $\alpha_{y_{0}}<t<\beta_{y_{0}}$. Because if $E \subset Y$ is a Borel set with $y_{0} \in E$, then from (A3)(a), $X \subset \mathcal{T}\left(h_{t, y_{0}}\right)^{-1}\left(y_{0}\right) \subset \mathcal{T}\left(h_{t, y_{0}}\right)^{-1}(E) \subset X$ and so $M_{\mathcal{T}\left(h_{t, y_{0}}\right)}(E)=\omega(X)$. If $y_{0} \notin E$, then $y_{0} \in Y \backslash E$ and so $M_{\mathcal{T}\left(h_{t, y_{0}}\right)}(Y \backslash E)=\omega(X)$ and then $M_{\mathcal{T}\left(h_{t, y_{0}}\right)}(E)=0$.

The following is the main theorem in this section. We solve a measure equation when the given measure in $Y$ is discrete.

Theorem 2.5. Let $X, Y$ be compact metric spaces and $\omega$ is a Radon measure in $X$. Let $p_{1}, \ldots, p_{N}$ be distinct points in $Y$, and $g_{1}, \ldots, g_{N}$ be positive numbers with $N \geqslant 2$.

Let $\mathcal{F} \subset C^{+}(X)$ and $\mathcal{T}: \mathcal{F} \rightarrow C_{s}(X, Y)$ be such that $\mathcal{F}$ is $\mathcal{T}$-concave and (A3) holds.
Assume that

$$
\begin{equation*}
\omega(X)=\sum_{i=1}^{N} g_{i}, \tag{2.3}
\end{equation*}
$$

and there exists $\rho_{0}=\min _{1 \leqslant i \leqslant N} h_{b_{i}^{0}, p_{i}}$ such that $\mathcal{M}_{\mathcal{T}\left(\rho_{0}\right)}\left(p_{i}\right) \leqslant g_{i}$ for $2 \leqslant i \leqslant N$. Then there exist $b_{i} \in\left(\alpha_{p_{i}}, \beta_{p_{i}}\right)$, $2 \leqslant i \leqslant N$, such that the function, with $b_{1}=b_{1}^{0}$,

$$
\rho(x)=\min _{1 \leqslant i \leqslant N} h_{b_{i}, p_{i}}(x)
$$

satisfies

$$
M_{\mathcal{T}(\rho)}=\sum_{i=1}^{N} g_{i} \delta_{p_{i}} .
$$

Proof. Let $b_{1}=b_{1}^{0}$ and define the set

$$
W=\left\{\left(b_{2}, \ldots, b_{N}\right): \alpha_{p_{i}}<b_{i} \leqslant b_{i}^{0} ; M_{\mathcal{T}(\rho)}\left(p_{i}\right) \leqslant g_{i}, i=2, \ldots, N\right\} .
$$

By the assumptions, $\left(b_{2}^{0}, \ldots, b_{N}^{0}\right) \in W$.
Step 1: There exist constants $L, \epsilon_{0}>0$ such that for all $\left(b_{2}, \ldots, b_{N}\right) \in W$ we have $b_{i} \geqslant \alpha_{p_{i}}+\epsilon_{0}$ if $\alpha_{p_{i}}>-\infty$, and $b_{i} \geqslant-L$ if $\alpha_{p_{i}}=-\infty$, for $2 \leqslant i \leqslant N$.

To prove this, we first show that the measure $M_{\mathcal{T}(\rho)}$ is supported on $\left\{p_{1}, \ldots, p_{N}\right\}$. This follows if we show that the set $E=\mathcal{T}(\rho)^{-1}\left(Y \backslash\left\{p_{1}, \ldots, p_{N}\right\}\right) \subset N_{0}$, where $N_{0}:=\{x \in X: \mathcal{T}(\rho)(x)$ is not a singleton $\}$ has $\omega$-measure zero. If $z_{0} \in E$, then $\mathcal{T}(\rho)\left(z_{0}\right) \cap\left(Y \backslash\left\{p_{1}, \ldots, p_{N}\right\}\right) \neq \emptyset$. Therefore there is $p \in \mathcal{T}(\rho)\left(z_{0}\right)$ with $p \neq p_{i}$ for $1 \leqslant i \leqslant N$. On the other hand, $\rho\left(z_{0}\right)=h_{b_{k}, p_{k}}\left(z_{0}\right)$ for some $1 \leqslant k \leqslant N$. From (A2) we then have $\mathcal{T}\left(h_{b_{k}, p_{k}}\right)\left(z_{0}\right) \subset \mathcal{T}(\rho)\left(z_{0}\right)$, but $p_{k} \in \mathcal{T}\left(h_{b_{k}, p_{k}}\right)\left(z_{0}\right)$ by (A3)(a), and so $\mathcal{T}(\rho)$ is not single-valued at $z_{0}$.

Consequently, from (2.3) we get $M_{\mathcal{T}(\rho)}\left(p_{1}\right) \geqslant g_{1}>0$, and so $\omega\left(\mathcal{T}(\rho)^{-1}\left(p_{1}\right)\right)>0$. Pick $x_{0} \in \mathcal{T}(\rho)^{-1}\left(p_{1}\right) \backslash N_{0}$. We claim that $h_{b_{1}, p_{1}}\left(x_{0}\right) \leqslant h_{b_{i}, p_{i}}\left(x_{0}\right)$ for $i \geqslant 2$. Otherwise, there is some $i \geqslant 2$ such that $h_{b_{i}, p_{i}}\left(x_{0}\right)<h_{b_{1}, p_{1}}\left(x_{0}\right)$.

Pick $j \geqslant 2$ such that $h_{b_{j}, p_{j}}\left(x_{0}\right)=\min _{2 \leqslant i \leqslant N} h_{b_{i}, p_{i}}\left(x_{0}\right)$. Then $\rho\left(x_{0}\right)=h_{b_{j}, p_{j}}\left(x_{0}\right)$. Hence from (A2), $\mathcal{T}\left(h_{b_{j}, p_{j}}\right)\left(x_{0}\right) \subset$ $\mathcal{T}\left(\rho \wedge h_{b_{j}, p_{j}}\right)\left(x_{0}\right)=\mathcal{T}(\rho)\left(x_{0}\right)=p_{1}$. But from (A3)(a), $p_{j} \in \mathcal{T}\left(h_{b_{j}, p_{j}}\right)\left(x_{0}\right)$, a contradiction and the claim is proved. Since $h_{b_{1}, p_{1}}\left(x_{0}\right) \geqslant C>0$, we then get $h_{b_{i}, p_{i}}\left(x_{0}\right) \geqslant C>0$ for all $i \geqslant 2$. From (A3)(c), $h_{b_{i}, p_{i}}\left(x_{0}\right) \rightarrow 0$ as $b_{i} \rightarrow \alpha_{p_{i}}$, and therefore Step 1 is proved.

Step 2: $W$ is compact.
It is enough to show that $M_{\mathcal{T}(\rho)}\left(p_{i}\right)$ is continuous in $b^{\prime}=\left(b_{2}, \ldots, b_{N}\right)$ for each $1 \leqslant i \leqslant N$. Let $b_{m}^{\prime}=$ $\left(b_{2}^{m}, \ldots, b_{N}^{m}\right) \in W$ converging to $b_{*}^{\prime}=\left(b_{2}^{*}, \ldots, b_{N}^{*}\right)$. Then by (A3)(d), $\rho_{m}=\left(\min _{i \neq 1} h_{b_{i}^{m}, p_{i}}\right) \wedge h_{b_{1}, p_{1}} \rightarrow \rho^{*}=$ $\left(\min _{i \neq 1} h_{b_{i}^{*}, p_{i}}\right) \wedge h_{b_{1}, p_{1}}$ uniformly as $m \rightarrow \infty$. Therefore, as in the proof of Lemma 2.3, we obtain $\limsup _{m \rightarrow \infty} M_{\mathcal{T}\left(\rho_{m}\right)}\left(p_{i}\right) \leqslant M_{\mathcal{T}\left(\rho^{*}\right)}\left(p_{i}\right)$ for $i=1, \ldots, N$, and $\liminf _{m \rightarrow \infty} M_{\mathcal{T}\left(\rho_{m}\right)}(G) \geqslant M_{\mathcal{T}\left(\rho^{*}\right)}(G)$ for each $G$ open. Now choose $G$ open such that $p_{i} \in G$ and $p_{j} \notin G$ for $j \neq i$. Then $M_{\mathcal{T}\left(\rho_{m}\right)}(G)=\omega\left(\mathcal{T}\left(\rho_{m}\right)^{-1}\left(p_{i}\right)\right)+$ $\omega\left(\mathcal{T}\left(\rho_{m}\right)^{-1}\left(G \backslash\left\{p_{i}\right\}\right)\right)$, but $\omega\left(\mathcal{T}\left(\rho_{m}\right)^{-1}\left(G \backslash\left\{p_{i}\right\}\right)\right) \leqslant \omega\left(\mathcal{T}\left(\rho_{m}\right)^{-1}\left(Y \backslash\left\{p_{1}, \ldots, p_{N}\right\}\right)\right)=0$. We then obtain $\liminf _{m \rightarrow \infty} M_{\mathcal{T}\left(\rho_{m}\right)}\left(p_{i}\right) \geqslant M_{\mathcal{T}\left(\rho^{*}\right)}\left(p_{i}\right)$ and the continuity follows.

Step 3: Existence of solutions.
The function $z=b_{2}+\cdots+b_{N}$ attains its minimum on $W$ at some point $\left(a_{2}, \ldots, a_{N}\right)$. We claim that $\rho(x)=$ $\left(\min _{2 \leqslant i \leqslant N} h_{a_{i}, p_{i}}\right) \wedge h_{b_{1}, p_{1}}$ is the desired solution. Otherwise, assume for example that $M_{\mathcal{T}(\rho)}\left(p_{2}\right)<g_{2}$. Let $\bar{a}=$ $\left(a_{2}-\epsilon, a_{3}, \ldots, a_{N}\right)$ and $\bar{\rho}(x)=\left(\min _{2 \leqslant i \leqslant N} h_{\bar{a}_{i}, p_{i}}\right) \wedge h_{b_{1}, p_{1}}$. By continuity $M_{\mathcal{T}(\bar{\rho})}\left(p_{2}\right)<g_{2}$ for all $\epsilon$ sufficiently small.

For $i \geqslant 3$, we claim that $\mathcal{T}(\bar{\rho})^{-1}\left(p_{i}\right) \subset \mathcal{T}(\rho)^{-1}\left(p_{i}\right)$ except on a set of $\omega$-measure zero. Indeed, if $x_{0} \in \mathcal{T}(\bar{\rho})^{-1}\left(p_{i}\right)$ and $\mathcal{T}(\bar{\rho})\left(x_{0}\right)$ is a single point, then $p_{i}=\mathcal{T}(\bar{\rho})\left(x_{0}\right)$. Notice that $\bar{\rho}\left(x_{0}\right)=h_{a_{i}, p_{i}}\left(x_{0}\right)$. Otherwise, there exists $j \neq i$, $1 \leqslant j \leqslant N$, such that $\bar{\rho}\left(x_{0}\right)=h_{\bar{a}_{j}, p_{j}}\left(x_{0}\right)<h_{a_{i}, p_{i}}\left(x_{0}\right)$ (we set $\left.\bar{a}_{1}=b_{1}\right)$. Then from (A2), $\mathcal{T}\left(h_{\bar{a}_{j}, p_{j}}\right)\left(x_{0}\right) \subset \mathcal{T}(\bar{\rho})\left(x_{0}\right)$, and by (A3)(a) $p_{j} \in \mathcal{T}\left(h_{\bar{a}_{j}, p_{j}}\right)\left(x_{0}\right)$ and so $p_{j}=p_{i}$, a contradiction. From (A3) (b), $h_{\bar{a}_{2}, p_{2}} \leqslant h_{a_{2}, p_{2}}$ so $\bar{\rho}(x) \leqslant \rho(x)$, and therefore $\bar{\rho}\left(x_{0}\right)=h_{a_{i}, p_{i}}\left(x_{0}\right)=\rho\left(x_{0}\right)$. Hence, and once again from (A2), $\mathcal{T}\left(h_{a_{i}, p_{i}}\right)\left(x_{0}\right) \subset \mathcal{T}\left(\rho \wedge h_{a_{i}, p_{i}}\right)\left(x_{0}\right)=$ $\mathcal{T}(\rho)\left(x_{0}\right)$. Thus, $p_{i} \in \mathcal{T}(\rho)\left(x_{0}\right)$ from (A3)(a), so $x_{0} \in \mathcal{T}(\rho)^{-1}\left(p_{i}\right)$, and the claim is proved. We then obtain $M_{\mathcal{T}(\bar{\rho})}\left(p_{i}\right) \leqslant M_{\mathcal{T}(\rho)}\left(p_{i}\right) \leqslant g_{i}$ for $i \geqslant 3$, that is, $\bar{a} \in W$, a contradiction.

Remark 2.6. The existence of the function $\rho_{0}$ in Theorem 2.5 follows if one assumes that $b_{1}^{0}>\alpha_{p_{1}}$ is given and it is sufficiently close to $\alpha_{p_{1}}$. In fact, in this case we pick $\alpha_{p_{i}}<\tau_{i}<\beta_{p_{i}}$ for $2 \leqslant i \leqslant N$. Since $\mathcal{F} \subset C^{+}(X)$, we have $h_{\tau_{i}, p_{i}}(x) \geqslant C_{i}>0$ for $i \geqslant 2$ and $x \in X$. Then from (A3)(c), we can choose $b_{1}^{0}$ sufficiently close to $\alpha_{p_{1}}$ such that $h_{\tau_{i}, p_{i}}(x) \geqslant \min _{2 \leqslant i \leqslant N} C_{i} \geqslant h_{b_{1}^{0}, p_{1}}(x)$. If $b_{i}^{0}:=\tau_{i}$ for $2 \leqslant i \leqslant N$, we then select $\rho_{0}(x)=\min _{1 \leqslant i \leqslant N} h_{b_{i}^{0}, p_{i}}(x)=$ $h_{b_{1}^{0}, p_{1}}(x)$ and so from Remark $2.4 M_{\mathcal{T}\left(\rho_{0}\right)}=\omega(X) \delta_{p_{1}}$. Consequently, $M_{\mathcal{T}\left(\rho_{0}\right)}\left(p_{i}\right)=0$ for $2 \leqslant i \leqslant N$.

Theorem 2.7. Let $\rho, \rho^{*}$ be two solutions as in Theorem 2.5 , with $b=\left(b_{1}, \ldots, b_{N}\right)$, and $b^{*}=\left(b_{1}^{*}, \ldots, b_{N}^{*}\right)$. Assume that $X$ is connected and $\omega(E)>0$ for each open set $E \subset X$. Assume in addition that condition (A3)(b) is replaced by $h_{t, y_{0}}<h_{s, y_{0}}$ for $t<s$.
(a) If $b_{1}^{*} \leqslant b_{1}$, then $b_{i}^{*} \leqslant b_{i}$ for all $1 \leqslant i \leqslant N$. In particular, if $b_{1}^{*}=b_{1}$, then $b_{i}^{*}=b_{i}$ for all $1 \leqslant i \leqslant N$.
(b) If $\rho\left(x_{0}\right)=\rho^{*}\left(x_{0}\right)$ at some $x_{0} \in X$, then $\rho=\rho^{*}$.

Proof. (a) Let $J=\left\{j: b_{j}<b_{j}^{*}\right\}$ and $I=\left\{i: b_{i}^{*} \leqslant b_{i}\right\}$. Suppose by contradiction that $J \neq \emptyset$. We have $I \neq \emptyset$ since $1 \in I$. For each $j \in J$ we have $h_{b_{j}, p_{j}}(x)<h_{b_{j}^{*}, p_{j}}(x)$ for all $x \in X$, since $b_{j}<b_{j}^{*}$. And also $h_{b_{i}^{*}, p_{i}}(x) \leqslant h_{b_{i}, p_{i}}(x)$ for all $i \in I$ and all $x \in X$.

Let $Q=\left\{x \in X: \mathcal{T}\left(\rho^{*}\right)(x)\right.$ is not a singleton $\}$. From (A2) and (A3)(a), we notice that if $x \in \mathcal{T}\left(\rho^{*}\right)^{-1}\left(p_{i}\right) \backslash Q$, for some $1 \leqslant i \leqslant N$, then $\rho^{*}(x)=h_{b_{i}^{*}, p_{i}}(x)$.

We next prove that bdy $\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right) \subset Q$, where $\mathcal{P}_{J}=\left\{p_{j}: j \in J\right\}$. Indeed, let $z_{0} \in$ bdy $\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right)$ and $N_{z_{0}}$ be an open neighborhood of $z_{0}$. Then $N_{z_{0}} \cap\left(\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right)\right)^{c}$ is a nonempty open set, since $\left(\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right)\right)$ is compact. Thus, $N_{z_{0}} \cap\left(\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right)\right)^{c} \backslash Q$ has a positive measure and therefore is nonempty. We then obtain $\left\{z_{k}\right\}$ such that $z_{k} \rightarrow z_{0}$ and $z_{k} \in\left(\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right)\right)^{c} \backslash Q$. So there exists $\left\{p_{i_{k}}\right\}$ with $p_{i_{k}}=\mathcal{T}\left(\rho^{*}\right)\left(z_{k}\right)$ and $i_{k} \in I$. We may assume that $p_{i_{k}}=p_{i}$, for some $i \in I$. Therefore, $\rho^{*}\left(z_{k}\right)=h_{b_{b}^{*}, p_{i}}\left(z_{k}\right)$. By taking limit, $\rho^{*}\left(z_{0}\right)=h_{b_{i}^{*}, p_{i}}\left(z_{0}\right)$. From (A2) and (A3)(a), this yields $p_{i} \in \mathcal{T}\left(\rho^{*}\right)\left(z_{0}\right)$. Since $\mathcal{T}\left(\rho^{*}\right)\left(z_{0}\right) \cap \mathcal{P}_{J} \neq \emptyset$, we obtain $z_{0} \in Q$.

As a consequence, $\omega\left(\left(\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right)\right)^{\circ}\right)=\sum_{j \in J} g_{j}>0$.

Given $x_{0} \in \overline{\left(\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right)\right)^{\circ}}$, for any open neighborhood $N_{x_{0}}$ of $x_{0}$, we have that $N_{x_{0}} \cap\left(\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right)\right)^{\circ}$ is a nonempty open set. Therefore, as in the previous argument, there exists $x_{k} \in\left(\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right)\right)^{\circ} \backslash Q$ for $k \geqslant 1$ such that $x_{k} \rightarrow x_{0}$. Hence, one may assume that there exists some $p_{j}$ with $j \in J$ such that $p_{j}=\mathcal{T}\left(\rho^{*}\right)\left(x_{k}\right)$. So $h_{b_{j}^{*}, p_{j}}\left(x_{k}\right)=$ $\rho^{*}\left(x_{k}\right)$ and then $h_{b_{j}^{*}, p_{j}}\left(x_{0}\right)=\rho^{*}\left(x_{0}\right)$ by taking limit. Therefore, $h_{b_{j}^{*}, p_{j}}\left(x_{0}\right) \leqslant h_{b_{i}^{*}, p_{i}}\left(x_{0}\right)$ for all $1 \leqslant i \leqslant N$. Thus, we obtain for $j \in J$ that

$$
h_{b_{j}, p_{j}}\left(x_{0}\right)<h_{b_{j}^{*}, p_{j}}\left(x_{0}\right) \leqslant h_{b_{i}^{*}, p_{i}}\left(x_{0}\right) \leqslant h_{b_{i}, p_{i}}\left(x_{0}\right) \quad \text { for all } i \in I .
$$

Hence by continuity, there exists $N_{x_{0}}$ a neighborhood of $x_{0}$ such that

$$
h_{b_{j}, p_{j}}(y)<h_{b_{i}, p_{i}}(y) \quad \text { for all } i \in I, j \in J, \text { and } y \in N_{x_{0}} .
$$

By definition of $\rho$ this implies that $\rho(y)=\min _{j \in J} h_{b_{j}, p_{j}}(y)$ for all $y \in N_{x_{0}}$. Therefore for each $y \in N_{x_{0}}$ there exists $j_{0} \in J$, depending on $y$, such that $\rho(y)=h_{b_{j_{0}}, p_{j_{0}}}(y)$. Hence, once again by (A2) and (A3)(a), $p_{j_{0}} \in \mathcal{T}\left(h_{b_{j_{0}}}, p_{j_{0}}\right)(y) \subset$ $\mathcal{T}(\rho)(y)$. That is, $y \in \mathcal{T}(\rho)^{-1}\left(p_{j_{0}}\right)$, and therefore

$$
N_{x_{0}} \subset \mathcal{T}(\rho)^{-1}\left(\mathcal{P}_{J}\right)
$$

We then have that every point $x \in \overline{\left(\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right)\right)^{\circ}}$ has a neighborhood contained in $\mathcal{T}(\rho)^{-1}\left(\mathcal{P}_{J}\right)$, that is,

$$
\overline{\left(\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right)\right)^{\circ}} \subset\left(\mathcal{T}(\rho)^{-1}\left(\mathcal{P}_{J}\right)\right)^{\circ} \neq X .
$$

This is a contradiction with the fact that

$$
\omega\left(\mathcal{T}(\rho)^{-1}\left(\mathcal{P}_{J}\right)\right)=\sum_{j \in J} g_{j}=\omega\left(\overline{\left(\left(\mathcal{T}\left(\rho^{*}\right)^{-1}\left(\mathcal{P}_{J}\right)\right)^{\circ}\right.}\right) .
$$

(b) If $b_{1}=b_{1}^{*}$, then $b_{j}=b_{j}^{*}$ for all $j>1$ by part (a), and we are done. We claim that if $b_{1}>b_{1}^{*}$, then $b_{j}>b_{j}^{*}$ for all $j>1$. Indeed, if $b_{j}=b_{j}^{*}$ for some $j \neq 1$, then $b_{k}=b_{k}^{*}$ for all $k \neq j$ by part (a), a contradiction. Therefore $\rho^{*}\left(x_{0}\right)=\min h_{b_{i}^{*}, p_{i}}\left(x_{0}\right)<\min h_{b_{i}, p_{i}}\left(x_{0}\right)=\rho\left(x_{0}\right)$, a contradiction.

Theorem 2.8. Let $\left\{\mu_{l}\right\}$ be a sequence of discrete Radon measures in $Y$ such that $\mu_{l} \rightarrow \mu$ weakly and $\mu_{l}(Y)=\omega(X)$ for $l \geqslant 1$. Let $\rho_{l}$ be a solution obtained in Theorem 2.5 corresponding to $\mu_{l}$. Assume that there exists $R_{0}>0$ such that $R_{0} \in \operatorname{Range}\left(\rho_{l}\right)$ for $l \geqslant 1$. Suppose that
(i) For each $R_{1}>0$ with $R_{1} \in$ Range ( $h_{t, y}$ ), there exists $C_{R_{1}}>0$ such that $C_{R_{1}}^{-1} \leqslant h_{t, y} \leqslant C_{R_{1}}$.
(ii) For any $C_{1}>C_{0}>0$, the family $\left\{f \in \mathcal{F}: C_{0} \leqslant f \leqslant C_{1}\right.$ in $\left.X\right\}$ is compact in $C(X)$.

Then there exists $\rho \in \mathcal{F}$ satisfying $\mathcal{M}_{\mathcal{T}(\rho)}=\mu$.
Proof. By (ii) and Lemma 2.3, it suffices to show $\left\{\rho_{l}\right\}$ is bounded from below and above. Assume $\rho_{l}\left(x_{l}\right)=R_{0}$ for some $x_{l} \in X$. Then there exists $h_{b_{l}, y_{l}}$ such that $\rho_{l} \leqslant h_{b_{l}, y_{l}}$ and $R_{0}=\rho_{l}\left(x_{l}\right)=h_{b_{l}, y_{l}}\left(x_{l}\right)$. By (i), $C_{R_{0}}^{-1} \leqslant h_{b_{l}, y_{l}} \leqslant C_{R_{0}}$ for some $C_{R_{0}}$. Therefore, $\rho_{l} \leqslant C_{R_{0}}$. To get a lower bound, given $x_{1} \in X$, there exists $h_{b_{l}^{\prime}, y_{l}^{\prime}}$ such that $\rho_{l} \leqslant h_{b_{l}^{\prime}, y_{l}^{\prime}}$ and $\rho_{l}\left(x_{1}\right)=h_{b_{l}^{\prime}, y_{l}^{\prime}}\left(x_{1}\right)$. Hence, $R_{0} \leqslant h_{b_{l}^{\prime}, y_{l}^{\prime}}\left(x_{l}\right)$. Since $h_{t, y_{l}^{\prime}}$ is continuous and decreasing to zero ((A3)(b) and (c)), there exists $b_{l}^{\prime \prime} \leqslant b_{l}^{\prime}$ with $R_{0}=h_{b_{l}^{\prime \prime}, y_{l}^{\prime}}\left(x_{l}\right)$. It follows from (A3)(b) that $\rho_{l}\left(x_{1}\right) \geqslant h_{b_{l}^{\prime \prime}, y_{l}^{\prime}}\left(x_{1}\right) \geqslant C_{R_{0}}^{-1}$. Hence $\rho_{l} \geqslant C_{R_{0}}^{-1}$.

### 2.2. Convex case

We assume here that $\mathcal{F} \subset C^{+}(X)$ and condition (A1) above is replaced by
(A1') if $f_{1}, f_{2} \in \mathcal{F}$, then $f_{1} \vee f_{2}=\max \left\{f_{1}, f_{2}\right\} \in \mathcal{F}$.

We say that the class $\mathcal{F} \subset C^{+}(X)$ is $\mathcal{T}$-convex if $\mathcal{F}$ satisfies ( $\mathrm{A1}^{\prime}$ ) and there exists a map $\mathcal{T}: \mathcal{F} \rightarrow C_{s}(X, Y)$ that is continuous at each $\phi \in \mathcal{F}$ and the following condition holds:
$\left(\mathrm{A} 2^{\prime}\right)$ if $\phi_{1}\left(x_{0}\right) \geqslant \phi_{2}\left(x_{0}\right)$, then $\mathcal{T}\left(\phi_{1}\right)\left(x_{0}\right) \subset \mathcal{T}\left(\phi_{1} \vee \phi_{2}\right)\left(x_{0}\right)$.
Here we substitute condition (A3) by
(A3') for each $y_{0} \in Y$ there exists an interval ( $\alpha_{y_{0}}, \beta_{y_{0}}$ ) and a family of functions $\left\{h_{t, y_{0}}(x)\right\}_{\alpha_{y_{0}}<t<\beta_{y_{0}}} \subset \mathcal{F}$ satisfying
(a) $y_{0} \in \mathcal{T}\left(h_{t, y_{0}}\right)(x)$ for all $x \in X$,
(b) $h_{t, y_{0}} \geqslant h_{s, y_{0}}$ for $t \leqslant s$,
(c) $h_{t, y_{0}} \rightarrow 0$ uniformly as $t \rightarrow \beta_{y_{0}}$,
(d) $h_{t, y_{0}}$ is continuous in $C(X)$ with respect to $t$, i.e., $\max _{x \in X}\left|h_{t^{\prime}, y_{0}}(x)-h_{t, y_{0}}(x)\right| \rightarrow 0$ as $t^{\prime} \rightarrow t$, for $\alpha_{y_{0}}<$ $t<\beta_{y_{0}}$.

Under these assumptions we prove the following theorem.
Theorem 2.9. Let $X, Y$ be compact metric spaces and $\omega$ is a Radon measure in $X$. Let $p_{1}, \ldots, p_{N}$ be distinct points in $Y$, and $g_{1}, \ldots, g_{N}$ be positive numbers with $N \geqslant 2$.

Let $\mathcal{F} \subset C^{+}(X)$ and $\mathcal{T}: \mathcal{F} \rightarrow C_{s}(X, Y)$ be such that $\mathcal{F}$ is $\mathcal{T}$-convex and ( $\mathrm{A}^{\prime}$ ) holds.
Assume that

$$
\begin{equation*}
\omega(X)=\sum_{i=1}^{N} g_{i} . \tag{2.4}
\end{equation*}
$$

Suppose that there exists $\left(b_{1}^{0}, \ldots, b_{N}^{0}\right)$ with $h_{b_{1}^{0}, p_{1}}(x) \leqslant \min _{2 \leqslant i \leqslant N} h_{b_{i}^{0}, p_{i}}(x)$ on $X$. Then there exist $b_{i} \in\left(\alpha_{p_{i}}, \beta_{p_{i}}\right)$, $2 \leqslant i \leqslant N$, such that the function, with $b_{1}=b_{1}^{0}$,

$$
\rho(x)=\max _{1 \leqslant i \leqslant N} h_{b_{i}, p_{i}}(x)
$$

satisfies

$$
M_{\mathcal{T}(\rho)}=\sum_{i=1}^{N} g_{i} \delta_{p_{i}}
$$

Proof. Let $b_{1}=b_{1}^{0}$ and $\eta=\min _{X} h_{b_{1}, p_{1}}>0$. From ( $\mathrm{A}^{\prime}$ )(c), there exists $\tau>0$ such that

$$
\max _{X} h_{h_{p_{i}}-\tau, p_{i}} \leqslant \eta
$$

for all $2 \leqslant i \leqslant N$. Therefore, if $\rho_{\tau}=h_{b_{1}, p_{1}} \vee\left(\max _{2 \leqslant i \leqslant N} h_{\beta_{p_{i}}-\tau, p_{i}}\right)=h_{b_{1}, p_{1}}$, then $M_{\mathcal{T}\left(\rho_{\tau}\right)}=\omega(X) \delta_{p_{1}}$, and so $M_{\mathcal{T}\left(\rho_{\tau}\right)}\left(p_{i}\right)=0$ for $2 \leqslant i \leqslant N$.

Consider the set

$$
W\left(b_{1}\right)=\left\{\left(b_{2}, \ldots, b_{N}\right): \alpha_{p_{i}}<b_{i} \leqslant \beta_{p_{i}}-\tau ; M_{\mathcal{T}(\rho)}\left(p_{i}\right) \leqslant g_{i}, i=2, \ldots, N\right\},
$$

$W\left(b_{1}\right) \neq \emptyset$, because $\left(\beta_{p_{2}}-\tau, \ldots, \beta_{p_{N}}-\tau\right) \in W\left(b_{1}\right)$.
We claim that $b_{i} \geqslant b_{i}^{0}$, for $2 \leqslant i \leqslant N$, for all $\left(b_{2}, \ldots, b_{N}\right) \in W\left(b_{1}\right)$.
To prove the claim, we first show $M_{\mathcal{T}(\rho)}\left(Y \backslash\left\{p_{1}, \ldots, p_{N}\right\}\right)=0 ; \rho=\max _{1 \leqslant i \leqslant N} h_{b_{i}, p_{i}}$. Indeed, for $z_{0} \in E=$ $\mathcal{T}(\rho)^{-1}\left(Y \backslash\left\{p_{1}, \ldots, p_{N}\right\}\right)$, there is $p \in \mathcal{T}(\rho)\left(z_{0}\right)$ with $p \neq p_{i}$ for $1 \leqslant i \leqslant N$. On the other hand, $\rho\left(z_{0}\right)=h_{b_{k}, p_{k}}\left(z_{0}\right)$ for some $k$. From ( $\mathrm{A}^{\prime}$ ) and $\left(\mathrm{A3}^{\prime}\right)\left(\right.$ a) we then have $p_{k} \in \mathcal{T}\left(h_{b_{k}, p_{k}}\right)\left(z_{0}\right) \subset \mathcal{T}(\rho)\left(z_{0}\right)$. So $\mathcal{T}(\rho)$ is not single-valued at $z_{0}$ and so $\omega(E)=0$. Consequently, from (2.4) we get $M_{\mathcal{T}(\rho)}\left(p_{1}\right) \geqslant g_{1}>0$.

Now suppose by contradiction that $b_{i}<b_{i}^{0}$ for some $2 \leqslant i \leqslant N$. Since $b_{1}=b_{1}^{0}$, it follows from the assumption and (A3')(b) that $h_{b_{1}, p_{1}} \leqslant h_{b_{i}^{0}, p_{i}} \leqslant h_{b_{i}, p_{i}}$ in $X$. This implies that for each $x_{0} \in X$, there is $j \neq 1$ such that
$\rho\left(x_{0}\right)=h_{b_{j}, p_{j}}\left(x_{0}\right)$. By $\left(\mathrm{A} 2^{\prime}\right), p_{j} \in \mathcal{T}\left(h_{b_{j}, p_{j}}\right)\left(x_{0}\right) \subset \mathcal{T}(\rho)\left(x_{0}\right)$. Thus, $X=\mathcal{T}(\rho)^{-1}\left(\left\{p_{2}, \ldots, p_{N}\right\}\right)$ and $M_{\mathcal{T}(\rho)}\left(p_{1}\right)=$ $\omega\left(\mathcal{T}(\rho)^{-1}\left(p_{1}\right)\right)=0$, a contradiction and the claim is proved.

As in the proof of Theorem 2.5, one can show that $M_{\mathcal{T}(\rho)}\left(p_{i}\right)$ is continuous in $b^{\prime}=\left(b_{2}, \ldots, b_{N}\right)$ for each $1 \leqslant i \leqslant N$. Therefore, $W\left(b_{1}\right)$ is compact.

Finally, to get the existence of solutions, the function $z=b_{2}+\cdots+b_{N}$ attain its minimum on $W\left(b_{1}\right)$ at some point $\left(a_{2}, \ldots, a_{N}\right)$. We claim that $\rho(x)=\left(\max _{2 \leqslant i \leqslant N} h_{a_{i}, p_{i}}\right) \vee h_{b_{1}, p_{1}}$ is the desired solution. Otherwise, we may assume, for example, that $M_{\mathcal{T}(\rho)}\left(p_{2}\right)<g_{2}$. Let $\bar{a}=\left(a_{2}-\epsilon, a_{3}, \ldots, a_{N}\right)$ and $\bar{\rho}(x)=\left(\max _{2 \leqslant i \leqslant N} h_{\bar{a}_{i}, p_{i}}\right) \vee h_{b_{1}, p_{1}}$. By continuity $M_{\mathcal{T}(\bar{\rho})}\left(p_{2}\right)<g_{2}$ for all $\epsilon$ sufficiently small.

On the other hand, for $i \geqslant 3$, we claim that $\mathcal{T}(\bar{\rho})^{-1}\left(p_{i}\right) \subset \mathcal{T}(\rho)^{-1}\left(p_{i}\right)$ except on a set of $\omega$-measure zero. Indeed, if $x_{0} \in \mathcal{T}(\bar{\rho})^{-1}\left(p_{i}\right)$ and $\mathcal{T}(\bar{\rho})\left(x_{0}\right)$ is a single point, then $p_{i}=\mathcal{T}(\bar{\rho})\left(x_{0}\right)$. Notice that $\bar{\rho}\left(x_{0}\right)=h_{a_{i}, p_{i}}\left(x_{0}\right)$. Otherwise, if $\bar{\rho}\left(x_{0}\right)=h_{\bar{a}_{j}, p_{j}}\left(x_{0}\right)>h_{a_{i}, p_{i}}\left(x_{0}\right)$ for some $j \neq i$ (we set $\bar{a}_{1}=b_{1}$ ), then by ( $\mathrm{A}^{\prime}$ ) and ( $\left.\mathrm{A3}^{\prime}\right)\left(\right.$ a) $p_{j} \in \mathcal{T}\left(h_{\bar{a}_{j}, p_{j}}\right)\left(x_{0}\right) \subset$ $\mathcal{T}(\bar{\rho})\left(x_{0}\right)$ and so $p_{j}=p_{i}$, a contradiction. Set $\bar{a}_{2}=a_{2}-\epsilon$. From ( $\left.\mathrm{A}^{\prime}\right)(\mathrm{b}), h_{\bar{a}_{2}, p_{2}} \geqslant h_{a_{2}, p_{2}}$ and hence $h_{a_{i}, p_{i}}\left(x_{0}\right)=$ $\rho\left(x_{0}\right)$. Hence, and once again from (A2'), $\mathcal{T}\left(h_{a_{i}, p_{i}}\right)\left(x_{0}\right) \subset \mathcal{T}\left(\rho \vee h_{a_{i}, p_{i}}\right)\left(x_{0}\right)=\mathcal{T}(\rho)\left(x_{0}\right)$. Thus, $p_{i} \in \mathcal{T}(\rho)\left(x_{0}\right)$ from ( $\left.\mathrm{A}^{\prime}\right)\left(\right.$ a) ; so $x_{0} \in \mathcal{T}(\rho)^{-1}\left(p_{i}\right)$, and the claim is proved. We then obtain $M_{\mathcal{T}(\bar{\rho})}\left(p_{i}\right) \leqslant M_{\mathcal{T}(\rho)}\left(p_{i}\right) \leqslant g_{i}$ for $i \geqslant 3$, that is, $\bar{a} \in W$, a contradiction.

Similar to Theorem 2.7 we have the following.
Theorem 2.10. Let $\rho, \rho^{*}$ be two solutions as in Theorem 2.9 , with $b=\left(b_{1}, \ldots, b_{N}\right)$, and $b^{*}=\left(b_{1}^{*}, \ldots, b_{N}^{*}\right)$. Assume that $X$ is connected and $\omega(E)>0$ for each open set $E \subset X$. Assume in addition that condition $\left(\mathrm{A}^{\prime}\right)(\mathrm{b})$ is replaced by $h_{s, y_{0}}<h_{t, y_{0}}$ for $t<s$.
(a) If $b_{1}^{*} \leqslant b_{1}$, then $b_{i}^{*} \leqslant b_{i}$ for all $1 \leqslant i \leqslant N$. In particular, if $b_{1}^{*}=b_{1}$, then $b_{i}^{*}=b_{i}$ for all $1 \leqslant i \leqslant N$.
(b) If $\rho\left(x_{0}\right)=\rho^{*}\left(x_{0}\right)$ at some $x_{0} \in X$, then $\rho=\rho^{*}$.

Theorem 2.11. Let $\left\{\mu_{l}\right\}$ be a sequence of discrete Radon measures in $Y$ such that $\mu_{l} \rightarrow \mu$ weakly and $\mu_{l}(Y)=\omega(X)$ for $l \geqslant 1$. Let $\rho_{l}$ be a solution obtained in Theorem 2.9 corresponding to $\mu_{l}$. Assume that there exists $R_{0}>0$ such that $R_{0} \in \operatorname{Range}\left(\rho_{l}\right)$ for $l \geqslant 1$ and $R_{0}<\lim _{t \rightarrow \alpha_{y}^{+}} h_{t, y}(x)$ for $x \in X, y \in Y$. Suppose that
(i) For each $R_{1}>0$ with $R_{1} \in \operatorname{Range}\left(h_{t, y}\right)$, there exists $C_{R_{1}}>0$ such that $C_{R_{1}}^{-1} \leqslant h_{t, y} \leqslant C_{R_{1}}$.
(ii) For any $C_{1}>C_{0}>0$, the family $\left\{f \in \mathcal{F}: C_{0} \leqslant f \leqslant C_{1}\right.$ in $\left.X\right\}$ is compact in $C(X)$.

Then there exists $\rho \in \mathcal{F}$ satisfying $\mathcal{M}_{\mathcal{T}(\rho)}=\mu$.
Proof. By (ii) and Lemma 2.3, it suffices to show $\left\{\rho_{l}\right\}$ is bounded from below and above. Assume $\rho_{l}\left(x_{l}\right)=R_{0}$ for some $x_{l} \in X$. Then there exists $h_{b_{l}, y_{l}}$ such that $\rho_{l} \geqslant h_{b_{l}, y_{l}}$ and $R_{0}=\rho_{l}\left(x_{l}\right)=h_{b_{l}, y_{l}}\left(x_{l}\right)$. By (i), $C_{R_{0}}^{-1} \leqslant h_{b_{l}, y_{l}} \leqslant C_{R_{0}}$ for some $C_{R_{0}}$. Therefore, $\rho_{l} \geqslant C_{R_{0}}^{-1}$. To get an upper bound, given $x_{1} \in X$, there exists $h_{b_{l}^{\prime}, y_{l}^{\prime}}$ such that $\rho_{l} \geqslant h_{b_{l}^{\prime}, y_{l}^{\prime}}$ and $\rho_{l}\left(x_{1}\right)=h_{b_{l}^{\prime}, y_{l}^{\prime}}^{\prime}\left(x_{1}\right)$. Hence, $R_{0} \geqslant h_{b_{l}^{\prime}, y_{l}^{\prime}}\left(x_{l}\right)$. Since $R_{0}<\lim _{t \rightarrow \alpha_{y_{l}^{\prime}}^{+}} h_{t, y_{l}^{\prime}}\left(x_{l}\right)$, there exists $b_{l}^{\prime \prime} \leqslant b_{l}^{\prime}$ with $R_{0}=h_{b_{l}^{\prime \prime}, y_{l}^{\prime}}\left(x_{l}\right)$. It follows from ( $\mathrm{A}^{\prime}$ )(b) that $\rho_{l}\left(x_{1}\right) \leqslant h_{b_{l}^{\prime \prime}, y_{l}^{\prime}}\left(x_{1}\right) \leqslant C_{R_{0}}$. Hence $\rho_{l} \leqslant C_{R_{0}}$.

### 2.3. Convex case infinity

We assume here that the class $\mathcal{F} \subset C(X)$ is $\mathcal{T}$-convex, i.e., $\mathcal{F}$ satisfies ( $\mathrm{Al}^{\prime}$ ) and there exists a map $\mathcal{T}: \mathcal{F} \rightarrow$ $C_{s}(X, Y)$ that is continuous at each $\phi \in \mathcal{F}$ and (A2') holds. We also consider the following condition.
(A3") For each $y_{0} \in Y$ there exists an interval $\left(\alpha_{y_{0}}, \beta_{y_{0}}\right)$ and a family of functions $\left\{h_{t, y_{0}}(x)\right\}_{\alpha_{y_{0}}<t<\beta_{y_{0}}} \subset \mathcal{F}$ satisfying
(a) $y_{0} \in \mathcal{T}\left(h_{t, y_{0}}\right)(x)$ for all $x \in X$,
(b) $h_{t, y_{0}} \leqslant h_{s, y_{0}}$ for $t \leqslant s$,
(c) $h_{t, y_{0}} \rightarrow+\infty$ uniformly as $t \rightarrow \beta_{y_{0}}$,
(d) $h_{t, y_{0}}$ is continuous in $C(X)$ with respect to $t$, i.e., $\max _{x \in X}\left|h_{t^{\prime}, y_{0}}(x)-h_{t, y_{0}}(x)\right| \rightarrow 0$ as $t^{\prime} \rightarrow t$, for $\alpha_{y_{0}}<$ $t<\beta_{y_{0}}$.

Under these assumptions we prove the following theorem.
Theorem 2.12. Let $X, Y$ be compact metric spaces and $\omega$ be a Radon measure in $X$. Let $p_{1}, \ldots, p_{N}$ be distinct points in $Y$, and $g_{1}, \ldots, g_{N}$ be positive numbers with $N \geqslant 2$.

Let $\mathcal{F} \subset C(X)$ and $\mathcal{T}: \mathcal{F} \rightarrow C_{s}(X, Y)$ be such that $\mathcal{F}$ is $\mathcal{T}$-convex and $\left(\mathrm{A}^{\prime \prime}\right)$ holds.
Assume that

$$
\begin{equation*}
\omega(X)=\sum_{i=1}^{N} g_{i}, \tag{2.5}
\end{equation*}
$$

and there exists $\rho_{0}=\max _{1 \leqslant i \leqslant N} h_{b_{i}^{0}, p_{i}}$ such that $\mathcal{M}_{\mathcal{T}\left(\rho_{0}\right)}\left(p_{i}\right) \leqslant g_{i}$ for $2 \leqslant i \leqslant N$. Then there exist $b_{i} \in\left(\alpha_{p_{i}}, \beta_{p_{i}}\right)$, $2 \leqslant i \leqslant N$, such that the function, with $b_{1}=b_{1}^{0}$,

$$
\rho(x)=\max _{1 \leqslant i \leqslant N} h_{b_{i}, p_{i}}(x)
$$

satisfies

$$
M_{\mathcal{T}(\rho)}=\sum_{i=1}^{N} g_{i} \delta_{p_{i}}
$$

Proof. We convert this case to the concave case considered in Subsection 2.2, and use Theorem 2.5 to prove the theorem. Consider the family $\mathcal{F}^{*}=\left\{e^{-f}: f \in \mathcal{F}\right\} \subset C^{+}(X)$ and the mapping $\mathcal{T}^{*}: \mathcal{F}^{*} \rightarrow C_{s}(X, Y)$ given by $\mathcal{T}^{*}\left(e^{-f}\right)=\mathcal{T}(f)$. It is easy to verify that (A1) and (A2) hold and hence $\mathcal{F}^{*}$ is $\mathcal{T}^{*}$-concave. To verify (A3), for $y_{0} \in Y$, consider the interval $\left(-\beta_{y_{0}},-\alpha_{y_{0}}\right)$ and $h_{t, y_{0}}^{*}(x)=e^{-h_{-t, y_{0}}(x)}$. Obviously, $\left\{h_{t, y_{0}}^{*}(x)\right\}_{-\beta_{y_{0}}<t<-\alpha_{y_{0}}} \subset \mathcal{F}^{*}$ and satisfies (A3)(a)-(d). Set $\rho_{0}^{*}=e^{-\rho_{0}}=\min _{1 \leqslant i \leqslant N} h_{-b_{i}^{0}, p_{i}}^{*}$. By definition of $\mathcal{T}^{*}, \mathcal{T}^{*}\left(\rho_{0}^{*}\right)=\mathcal{T}\left(\rho_{0}\right)$, and consequently $\mathcal{M}_{\mathcal{T}^{*}\left(\rho_{0}^{*}\right)}\left(p_{i}\right)=\mathcal{M}_{\mathcal{T}\left(\rho_{0}\right)}\left(p_{i}\right) \leqslant g_{i}$. By Theorem 2.5, there exists $\rho^{*}(x)=\min _{1 \leqslant i \leqslant N} h_{-b_{i}, p_{i}}^{*}$ satisfying the equation $\mathcal{M}_{\mathcal{T}^{*}(\rho)}=\sum_{i=1}^{N} g_{i} \delta_{p_{i}}$. Since $\rho^{*}=e^{-\rho}, \mathcal{M}_{\mathcal{T}(\rho)}=\sum_{i=1}^{N} g_{i} \delta_{p_{i}}$.

## 3. Snell's law of refraction

Suppose $\Gamma$ is a surface in $\mathbb{R}^{n}$ that separates two media I and II that are homogeneous and isotropic. Let $v_{1}$ and $v_{2}$ be the velocities of propagation of light in the media I and II respectively. The index of refraction of medium I is $n_{1}=c / v_{1}$, where $c$ is the velocity of propagation of light in the vacuum, and similarly $n_{2}=c / v_{2}$. If a ray of light ${ }^{3}$ having direction $x \in S^{n-1}$ and traveling through medium I hits $\Gamma$ at the point $P$, and $v$ is the unit normal to $\Gamma$ at $P$ going towards medium II, then this ray is refracted in the direction $m \in S^{n-1}$ through medium II according with the Snell law in vector form: the vectors $x, v$ and $m$ are all coplanar, and the vector $n_{2} m-n_{1} x$ is parallel to the normal vector $\nu$, that is, setting $\kappa=n_{2} / n_{1}$, we have

$$
\begin{equation*}
x-\kappa m=\lambda v, \tag{3.1}
\end{equation*}
$$

for some $\lambda \in \mathbb{R}$. Making the vector product of this equation with the normal $v$ we obtain the well known form of the Snell law: $n_{1} \sin \theta_{1}=n_{2} \sin \theta_{2}$, where $\theta_{1}$ is the angle between $x$ and $\nu$ (the angle of incidence), $\theta_{2}$ the angle between $m$ and $\nu$ (the angle of refraction).

When $\kappa<1$, or equivalently $v_{1}<v_{2}$, waves propagate in medium II faster than in medium I, or equivalently, medium I is denser than medium II. In this case the refracted rays tend to bent away from the normal, that is the case for example, when medium I is glass and medium II is air. In case $\kappa>1$, waves propagate in medium I faster than in medium II, and the refracted rays tend to bent towards the normal.

We summarize the physical constraints of refraction in the following lemma whose proof is in [5].

[^1]Lemma 3.1. Let $n_{1}$ and $n_{2}$ be the indices of refraction of two media I and II, respectively, and $\kappa=n_{2} / n_{1}$. Then a light ray in medium I with direction $x \in S^{n-1}$ is refracted by some surface into a light ray with direction $m \in S^{n-1}$ in medium II if and only if $m \cdot x \geqslant \kappa$, when $\kappa<1$; and if and only if $m \cdot x \geqslant 1 / \kappa$, when $\kappa>1$.

## 4. Cartesian ovals

To resolve our problem it is important to solve first the following simpler problem: given a point $O$ inside medium I and a point $P$ inside medium II, find an interface surface $\mathcal{S}$ between media I and II that refracts all rays emanating from the point $O$ into the point $P$. Suppose $O$ is the origin, and let $X(t)$ be a curve on $\mathcal{S}$. By the Snell law of refraction the tangent vector $X^{\prime}(t)$ satisfies

$$
X^{\prime}(t) \cdot\left(\frac{X(t)}{|X(t)|}-\kappa \frac{P-X(t)}{|P-X(t)|}\right)=0 .
$$

That is,

$$
|X(t)|^{\prime}+\kappa|P-X(t)|^{\prime}=0
$$

Therefore $\mathcal{S}$ is the Cartesian oval

$$
\begin{equation*}
|X|+\kappa|X-P|=b . \tag{4.1}
\end{equation*}
$$

Since $f(X)=|X|+\kappa|X-P|$ is a convex function, the oval is a convex set.
In our treatment of the problem, we need to analyze the polar equation and find the refracting piece for the oval. Write $X=\rho(x) x$ with $x \in S^{n-1}$. Then writing $\kappa|\rho(x) x-P|=b-\rho(x)$, squaring this quantity and solving the quadratic equation yields

$$
\begin{equation*}
\rho(x)=\frac{\left(b-\kappa^{2} x \cdot P\right) \pm \sqrt{\left(b-\kappa^{2} x \cdot P\right)^{2}-\left(1-\kappa^{2}\right)\left(b^{2}-\kappa^{2}|P|^{2}\right)}}{1-\kappa^{2}} . \tag{4.2}
\end{equation*}
$$

Set

$$
\begin{equation*}
\Delta(t)=\left(b-\kappa^{2} t\right)^{2}-\left(1-\kappa^{2}\right)\left(b^{2}-\kappa^{2}|P|^{2}\right) \tag{4.3}
\end{equation*}
$$

### 4.1. Case $0<\kappa<1$

We have

$$
\begin{equation*}
\Delta(x \cdot P)>\kappa^{2}(x \cdot P-b)^{2}, \quad \text { if }|x \cdot P|<|P| \tag{4.4}
\end{equation*}
$$

If $b \geqslant|P|$, then $O$ and $P$ are inside or on the oval, and so the oval cannot refract rays to $P$. If the oval is nonempty, then $\kappa|P| \leqslant b$. In case $\kappa|P|=b$, the oval reduces to the point $O$. The only interesting case is then $\kappa|P|<b<|P|$. From the equation of the oval we get that $\rho(x) \leqslant b$. So we now should decide which values $\pm$ to take in the definition of $\rho(x)$. Let $\rho_{+}$and $\rho_{-}$be the corresponding $\rho^{\prime}$ s. We claim that $\rho_{+}(x)>b$ and $\rho_{-}(x) \leqslant b$. Indeed,

$$
\begin{aligned}
\rho_{+}(x) & =\frac{\left(b-\kappa^{2} x \cdot P\right)+\sqrt{\Delta(x \cdot P)}}{1-\kappa^{2}} \geqslant \frac{\left(b-\kappa^{2} x \cdot P\right)+\kappa|b-x \cdot P|}{1-\kappa^{2}} \\
& =b+\frac{\kappa^{2}(b-x \cdot P)+\kappa|b-x \cdot P|}{1-\kappa^{2}} \geqslant b .
\end{aligned}
$$

The equality $\rho_{+}(x)=b$ holds only if $|x \cdot P|=|P|$ and $b=x \cdot P$. So $\rho_{+}(x)>b$ if $\kappa|P|<b<|P|$. Similarly,

$$
\begin{aligned}
\rho_{-}(x) & =\frac{\left(b-\kappa^{2} x \cdot P\right)-\sqrt{\Delta(x \cdot P)}}{1-\kappa^{2}} \leqslant \frac{\left(b-\kappa^{2} x \cdot P\right)-\kappa|b-x \cdot P|}{1-\kappa^{2}} \\
& =b+\frac{\kappa^{2}(b-x \cdot P)-\kappa|b-x \cdot P|}{1-\kappa^{2}} \leqslant b .
\end{aligned}
$$



Fig. 1. Cartesian ovals $\kappa<1$, e.g., glass to air.

So the claim is proved. Therefore the polar equation of the oval is then given by

$$
\begin{equation*}
h(x, P, b)=\rho_{-}(x)=\frac{\left(b-\kappa^{2} x \cdot P\right)-\sqrt{\Delta(x \cdot P)}}{1-\kappa^{2}} . \tag{4.5}
\end{equation*}
$$

To find the refracting part of the oval, from the physical constraint for refraction (Lemma 3.1), we must have $x \cdot\left(\frac{P-h(x, P, b) x}{|P-h(x, P, b) x|}\right) \geqslant \kappa$, and by (4.1) it is reduced to

$$
\begin{equation*}
x \cdot P \geqslant b \tag{4.6}
\end{equation*}
$$

The estimates of $h(x, P, b)$ are contained in the following lemma.
Lemma 4.1. Let $0<\kappa<1, h(x, P, b)$ given by (4.5), and assume that $\kappa|P|<b<|P|$. Then we have

$$
\begin{equation*}
\min _{x \in S^{n-1}} h(x, P, b)=\frac{b-\kappa|P|}{1+\kappa}, \quad \text { and } \quad \max _{x \in S^{n-1}} h(x, P, b)=\frac{b-\kappa|P|}{1-\kappa} . \tag{4.7}
\end{equation*}
$$

We also have

$$
\begin{equation*}
\min _{x \in S^{n-1}}|P-h(x, P, b) x|=\frac{|P|-b}{1-\kappa}=\min _{x \cdot P \geqslant b}|P-h(x, P, b) x|=\left|P-h\left(\frac{P}{|P|}, P, b\right) \frac{P}{|P|}\right|, \tag{4.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\max _{x \cdot P \geqslant b}|P-h(x, P, b) x|=\frac{\sqrt{|P|^{2}-b^{2}}}{\sqrt{1-\kappa^{2}}} . \tag{4.9}
\end{equation*}
$$

Proof. We write

$$
\begin{equation*}
h(x, P, b)=\frac{b^{2}-\kappa^{2}|P|^{2}}{\left(b-\kappa^{2} x \cdot P\right)+\sqrt{\Delta(x \cdot P)}} \tag{4.10}
\end{equation*}
$$

and let $g(t)=\left(b-\kappa^{2} t\right)+\sqrt{\Delta(t)}$. We have $g$ is decreasing for $-|P| \leqslant t \leqslant|P|$, and so $g(-|P|) \geqslant g(x \cdot P) \geqslant g(|P|)$. Hence $\frac{b^{2}-\kappa^{2}|P|^{2}}{g(-|P|)} \leqslant h(x, P, b) \leqslant \frac{b^{2}-\kappa^{2}|P|^{2}}{g(|P|)}$ and calculating $g(-|P|)$ and $g(|P|)$ the estimates in (4.7) follow.

To prove (4.8), since $\kappa|P-h(x, P, b) x|=b-h(x, P, b)$, the first equality follows from the right identity in (4.7). To show the second identity in (4.8), notice that since the oval is convex and symmetric with respect to the line joining 0 and $P$ we have that $\min _{x \in S^{n-1}}|P-h(x, P, b) x|$ is attained at $x=P /|P|$. In particular, this gives the explicit value of the distance from $P$ to the oval.

To prove (4.9) we have $\max _{x \cdot P \geqslant b}|P-h(x, P, b) x|=\frac{1}{\kappa}\left(b-\min _{x \cdot P \geqslant b} h(x, P, b)\right.$ ), and we claim that $\min _{x \cdot P \geqslant b} h(x, P, b)=h(z, P, b)$, for all $z \cdot P=b$. In fact, this follows from (4.10) since $g(x \cdot P) \leqslant g(b)$, obtaining $h(x, P, b) \geqslant b-\frac{\sqrt{\Delta(b)}}{1-\kappa^{2}}=b-\frac{\kappa}{\sqrt{1-\kappa^{2}}} \sqrt{|P|^{2}-b^{2}}$.

Remark 4.2. If $|P| \rightarrow \infty$, then the oval converges to an ellipsoid which is the surface having the uniform refraction property in the far field case, see [5]. In fact, if $m=P /|P|$ and $b=\kappa|P|+C$ with $C$ positive constant we have

$$
\begin{aligned}
h(x, P, b) & =\frac{b^{2}-\kappa^{2}|P|^{2}}{b-\kappa^{2} x \cdot P+\sqrt{\Delta(x \cdot P)}} \\
& =\frac{C(2 \kappa|P|+C)}{\left(\kappa|P|-\kappa^{2} x \cdot m|P|+C\right)+\sqrt{\left(\kappa|P|-\kappa^{2} x \cdot m|P|+C\right)^{2}-\left(1-\kappa^{2}\right) C(2 \kappa|P|+C)}} \\
& \rightarrow \frac{2 \kappa C}{\left(\kappa-\kappa^{2} x \cdot m\right)+\sqrt{\left(\kappa-\kappa^{2} x \cdot m\right)^{2}}}=\frac{C}{1-\kappa x \cdot m}
\end{aligned}
$$

as $|P| \rightarrow \infty$.

### 4.2. Case $\kappa>1$

In this case we must have $|P| \leqslant b$, and in case $b=|P|$ the oval reduces to the point $P$. Also $b<\kappa|P|$, since otherwise the points $0, P$ are inside the oval or 0 is on the oval, and therefore there cannot be refraction if $b \geqslant \kappa|P|$. So to have refraction we must have $|P|<b<\kappa|P|$ and so the point $P$ is inside the oval and 0 is outside the oval.

Rewriting $\rho$ in (4.2) we get that

$$
\rho_{ \pm}(x)=\frac{\left(\kappa^{2} x \cdot P-b\right) \pm \sqrt{\left(\kappa^{2} x \cdot P-b\right)^{2}-\left(\kappa^{2}-1\right)\left(\kappa^{2}|P|^{2}-b^{2}\right)}}{\kappa^{2}-1} .
$$

Now $\Delta(x \cdot P) \geqslant 0$ amounts $x \cdot P \geqslant \frac{b+\sqrt{\left(\kappa^{2}-1\right)\left(\kappa^{2}|P|^{2}-b^{2}\right)}}{\kappa^{2}}$, by Noticing that $\rho_{ \pm}(x)<0$ if $\kappa^{2} x \cdot P-b<0$. We have that $\rho_{-}(x) \leqslant \rho_{+}(x) \leqslant \frac{\left(\kappa^{2}|P|-b\right)+\sqrt{\Delta(|P|)}}{\kappa^{2}-1}=\frac{\kappa|P|+b}{\kappa+1}<b$. To have refraction, by the physical constraint we need to have $x \cdot \frac{P-x \rho_{ \pm}(x)}{\left|P-x \rho_{ \pm}(x)\right|} \geqslant 1 / \kappa$, which is equivalent to $\kappa^{2} x \cdot P-b \geqslant\left(\kappa^{2}-1\right) \rho_{ \pm}(x)$. Therefore, the physical constraint is satisfied only by $\rho_{-}$.

For $|P|<b<\kappa|P|$, the refracting piece of the oval is then given by

$$
\begin{equation*}
\mathcal{O}(P, b)=\left\{h(x, P, b) x: x \cdot P \geqslant \frac{b+\sqrt{\left(\kappa^{2}-1\right)\left(\kappa^{2}|P|^{2}-b^{2}\right)}}{\kappa^{2}}\right\} \tag{4.11}
\end{equation*}
$$

with

$$
\begin{equation*}
h(x, P, b)=\rho_{-}(x)=\frac{\left(\kappa^{2} x \cdot P-b\right)-\sqrt{\left(\kappa^{2} x \cdot P-b\right)^{2}-\left(\kappa^{2}-1\right)\left(\kappa^{2}|P|^{2}-b^{2}\right)}}{\kappa^{2}-1} . \tag{4.12}
\end{equation*}
$$

Let us define

$$
\begin{equation*}
I(P, b):=\frac{b+\sqrt{\left(\kappa^{2}-1\right)\left(\kappa^{2}|P|^{2}-b^{2}\right)}}{\kappa^{2}|P|}, \tag{4.13}
\end{equation*}
$$

and let

$$
\begin{equation*}
\Gamma(P, b)=\left\{x \in S^{n-1}: x \cdot P \geqslant I(P, b)|P|\right\}, \tag{4.14}
\end{equation*}
$$

that is, $\Gamma(P, b)$ denotes the set of directions in $\mathcal{O}(P, b)$.
We notice that $I(P, b)$ is decreasing as a function of $b$ and tends to one when $b \rightarrow|P|^{+}$, and tends to $1 / \kappa$ when $b \rightarrow(\kappa|P|)^{-}$.

If $|P| \rightarrow \infty$, then the oval $\mathcal{O}(P, b)$ converges to the semi-hyperboloid appearing in the far field refraction problem when $\kappa>1$, see [5]. Indeed, let $m=\frac{P}{|P|} \in S^{n-1}$ and $b=\kappa|P|-a$ with $a>0$ a constant. Then we have

$$
\frac{b+\sqrt{\left(\kappa^{2}-1\right)\left(\kappa^{2}|P|^{2}-b^{2}\right)}}{\kappa^{2}|P|}=\frac{\kappa|P|-a+\sqrt{\left(\kappa^{2}-1\right)\left(\kappa^{2}|P|^{2}-(\kappa|P|-a)^{2}\right)}}{\kappa^{2}|P|} \rightarrow \frac{1}{\kappa}
$$

as $|P| \rightarrow \infty$. On the other hand, if $x \cdot m>1 / \kappa$, we get

$$
\begin{aligned}
h(x, P, b) & =\frac{a(2 \kappa|P|-a)}{\left(\kappa^{2}|P| x \cdot m-\kappa|P|+a\right)+\sqrt{\left(\kappa^{2}|P| x \cdot m-\kappa|P|+a\right)^{2}-\left(\kappa^{2}-1\right) a(2 \kappa|P|-a)}} \\
& \rightarrow \frac{a 2 \kappa}{\kappa^{2} x \cdot m-\kappa+\sqrt{\left(\kappa^{2} x \cdot m-\kappa\right)^{2}}}=\frac{a}{\kappa x \cdot m-1},
\end{aligned}
$$

as $|P| \rightarrow \infty$.


Fig. 2. Cartesian ovals $\kappa>1$, e.g., air to glass.
The following lemma gives estimates for the size of $h(x, P, b)$.
Lemma 4.3. Let $\kappa>1, h(x, P, b)$ is given by (4.12), assume $|P|<b<\kappa|P|$, and $\Gamma(P, b)$ given by (4.14). We have
(a) $\min _{x \in \Gamma(P, b)} h(x, P, b)=\frac{\kappa|P|-b}{\kappa-1}$;
(b) $\max _{x \in \Gamma(P, b)} h(x, P, b)=\frac{\sqrt{\kappa^{2}|P|^{2}-b^{2}}}{\sqrt{\kappa^{2}-1}} \leqslant \sqrt{2|P|} \sqrt{\frac{\kappa|P|-b}{\kappa-1}}$;
(c) $\quad \frac{b-|P|}{\kappa} \leqslant|P-h(x, P, b) x| \leqslant \frac{b-|P|}{\kappa-1}, \quad$ for $x \in \Gamma(P, b)$;
(d) The following inequalities hold:

$$
\frac{\sqrt{\kappa|P|-b}}{\sqrt{|P|}} \frac{\kappa^{2}+\kappa-2}{2 \kappa \sqrt{2 \kappa\left(\kappa^{2}-1\right)}} \leqslant I(P, b)-\frac{1}{\kappa} \leqslant \frac{\sqrt{\kappa|P|-b}}{\sqrt{|P|}} \frac{2 \sqrt{\kappa-1}}{\kappa},
$$

where $I(P, b)$ is given by (4.13).
Proof. (a) The minimum of $h(x, P, b)$ is attained when $x=P /|P|$. So

$$
\min _{x \in \Gamma(P, b)} h(x, P, b)=h(P /|P|, P, b)=\frac{\kappa^{2}|P|^{2}-b^{2}}{\left(\kappa^{2}|P|-b\right)+\sqrt{\Delta(|P|)}}=\frac{\kappa|P|-b}{\kappa-1} .
$$

(b) The maximum of $h(x, P, b)$ on $\Gamma(P, b)$ is attained when

$$
x \cdot P=\frac{b+\sqrt{\left(\kappa^{2}-1\right)\left(\kappa^{2}|P|^{2}-b^{2}\right)}}{\kappa^{2}},
$$

that is, when $\Delta(x \cdot P)=0$ and the formula follows.
(c) We have

$$
\begin{aligned}
\min _{x \in \Gamma(P, b)}|P-h(x, P, b) x| & =\min _{x \in \Gamma(P, b)}\left(\frac{b-h(x, P, b)}{\kappa}\right)=\frac{b-\max _{x \in \Gamma(P, b)} h(x, P, b)}{\kappa} \\
& =\frac{b \sqrt{\kappa^{2}-1}-\sqrt{\kappa^{2}|P|^{2}-b^{2}}}{\kappa \sqrt{\kappa^{2}-1}} \geqslant \frac{b \sqrt{\kappa^{2}-1}-|P| \sqrt{\kappa^{2}-1}}{\kappa \sqrt{\kappa^{2}-1}} .
\end{aligned}
$$

Furthermore, set $\rho(x)=h(x, P, b)$ and then $|P|+(\kappa-1)|P-\rho(x) x| \leqslant \rho(x)+\kappa|P-\rho(x) x|=b$. It yields $|P-\rho(x) x| \leqslant \frac{b-|P|}{\kappa-1}$.
(d) It follows writing

$$
I(P, b)-\frac{1}{\kappa}=\frac{\sqrt{\kappa|P|-b}}{\kappa^{2}|P|} \cdot \frac{\left(\kappa^{2}-2\right) \kappa|P|+\kappa^{2} b}{\sqrt{\left(\kappa^{2}-1\right)(\kappa|P|+b)}+\sqrt{\kappa|P|-b}}
$$

and noticing that $\left(\kappa^{2}+\kappa-2\right) \kappa|P|<\left(\kappa^{2}-2\right) \kappa|P|+\kappa^{2} b<2\left(\kappa^{2}-1\right) \kappa|P|$, since $|P|<b<\kappa|P|$.

Remark 4.4. If $b \rightarrow(\kappa|P|)^{-}$, then, by Lemma 4.3(a), $\mathcal{O}(P, b)$ approaches zero.
Remark 4.5. If $b \rightarrow|P|^{+}$, then $\mathcal{O}(P, b)$ shrinks to $P$. Because $|P|+(\kappa-1)|P-X| \leqslant|X|+\kappa|P-X|=b$ for $X \in \mathcal{O}(P, b)$ and so $|P-X| \leqslant \frac{b-|P|}{\kappa-1}$.

## 5. Near field refractor problem for $\kappa<1$

### 5.1. Formulation of problem

Let $\Omega \subset S^{n-1}$ be a domain with $|\partial \Omega|=0$ (measure in the sphere). Let $D \subset \mathbb{R}^{n}$ be a "target" domain that we want to illuminate and suppose it is contained in an $n-1$ dimensional hypersurface, and assume $\bar{D}$ is compact, and $0 \notin \bar{D}$. Points in the sphere will be denoted with lower case letters and points in $\mathbb{R}^{n}$ by capitals.

We make the following assumptions on $\Omega$ and $D$ :
(H1) There exists $\tau$ with $0<\tau<1-\kappa$ such that $x \cdot P \geqslant(\kappa+\tau)|P|$ for all $x \in \bar{\Omega}$ and all $P \in \bar{D}$.
(H2) Let $0<r_{0} \leqslant \frac{\tau}{1+\kappa} \operatorname{dist}(0, \bar{D})$ and consider the cone in $\mathbb{R}^{n}$

$$
Q_{r_{0}}=\left\{t x: x \in \bar{\Omega}, 0<t \leqslant r_{0}\right\}
$$

For each $m \in S^{n-1}$ and for each $X \in Q_{r_{0}}$ we assume that $\bar{D} \cap\{X+t m: t \geqslant 0\}$ contains at most one point. That is, for each $X \in Q_{r_{0}}$ each ray emanating from $X$ intersects $\bar{D}$ at most in one point.

Given $P \in \mathbb{R}^{n}$ and $\kappa|P|<b<|P|$, keeping in mind (4.5) and (4.6), a refracting oval is the set

$$
\mathcal{O}(P, b)=\left\{h(x, P, b) x: x \in S^{n-1}, x \cdot P \geqslant b\right\}
$$

where

$$
h(x, P, b)=\frac{\left(b-\kappa^{2} x \cdot P\right)-\sqrt{\left(b-\kappa^{2} x \cdot P\right)^{2}-\left(1-\kappa^{2}\right)\left(b^{2}-\kappa^{2}|P|^{2}\right)}}{1-\kappa^{2}} .
$$

Definition 5.1. Let $\mathcal{S}=\{x \rho(x): x \in \bar{\Omega}\} \subset Q_{r_{0}}$ be a surface. We say that $\mathcal{S}$ is a near field refractor if for any point $y \rho(y) \in \mathcal{S}$ there exist $P \in \bar{D}$ and $b>0$ such that the refracting oval $\mathcal{O}(P, b)$ supports $\mathcal{S}$ at $y \rho(y)$, i.e. $\rho(x) \leqslant$ $h(x, P, b)$ for all $x \in \bar{\Omega}$ with equality at $x=y$.

The near field refractor mapping associated with $\mathcal{S}$ is defined by

$$
\begin{equation*}
\mathcal{R}_{\mathcal{S}}(x)=\{P \in \bar{D}: \text { there exists a supporting oval } \mathcal{O}(P, b) \text { to } \mathcal{S} \text { at } \rho(x) x\} . \tag{5.1}
\end{equation*}
$$

The definition implies that if $\mathcal{O}(P, b)$ is a supporting oval, then the opening of $\mathcal{O}(P, b)$ is wider than $\bar{\Omega}$, i.e., $x \cdot P \geqslant b$ for all $x \in \bar{\Omega}$.

Remark 5.2. If $\mathcal{S}$ is a near field refractor, then $\mathcal{R}_{\mathcal{S}}(\bar{\Omega})=\bar{D}$. Indeed, let $P \in \bar{D}$ and $b_{0}=(\kappa+\tau)|P|$. Then from the left identity in (4.7) and the assumption on $r_{0}$ in (H2) we get that $r_{0} \leqslant \frac{b_{0}-\kappa|P|}{1+\kappa} \leqslant h\left(x, P, b_{0}\right)$ for $x \in \bar{\Omega}$. Also from (H1), we have $x \cdot P \geqslant b_{0}$. Hence $\mathcal{S} \subset Q_{r_{0}}$ enclosed by $\mathcal{O}\left(P, b_{0}\right)$. Let

$$
b_{1}=\inf \{b: \rho(x) \leqslant h(x, P, b), x \cdot P \geqslant b \forall x \in \bar{\Omega}\} .
$$

Thus, the oval $\mathcal{O}\left(P, b_{1}\right)$ supports $\mathcal{S}$ at some $y \in \bar{\Omega}$.
We point out that if $\mathcal{S}=\mathcal{O}(P, b)$, then $\bar{D} \backslash\{P\} \subset \mathcal{R}_{\mathcal{S}}(\partial \Omega)$.
Lemma 5.3. If $\mathcal{S}$ is a near field refractor with defining function $\rho(x)$, then $\rho$ is Lipschitz continuous in $\bar{\Omega}$ with a Lipschitz constant depending only on $\kappa$ ad $\tau$ in the assumptions $(\mathrm{H} 1)$ and (H2) and $\max _{\bar{D}}|P|$.

Proof. Indeed, given $x_{0} \in \bar{\Omega}, \mathcal{S}$ has a supporting oval $h(x, P, b)$ at $\rho\left(x_{0}\right) x_{0}$ with $P \in \bar{D}$. Then

$$
\begin{aligned}
\rho(x)-\rho\left(x_{0}\right) & \leqslant h(x, P, b)-h\left(x_{0}, P, b\right) \\
& =\frac{1}{1-\kappa^{2}}\left(\left(b-\kappa^{2} x \cdot P\right)-\left(b-\kappa^{2} x_{0} \cdot P\right)+\sqrt{\Delta\left(x_{0} \cdot P\right)}-\sqrt{\Delta(x \cdot P)}\right) \\
& =\frac{1}{1-\kappa^{2}}(I+I I),
\end{aligned}
$$

where $\Delta$ is given by (4.3). We have $|I| \leqslant C(\kappa)|P| \cdot\left|x-x_{0}\right|$ and

$$
I I=\frac{\Delta\left(x_{0} \cdot P\right)-\Delta(x \cdot P)}{\sqrt{\Delta\left(x_{0} \cdot P\right)}+\sqrt{\Delta(x \cdot P)}} .
$$

We estimate $\Delta\left(x_{0} \cdot P\right)$ from below. Obviously, the function $\Delta(t)$ has a minimum at $t=b / \kappa^{2}$, is increasing in $\left(b / \kappa^{2},+\infty\right)$ and decreasing in $\left(-\infty, b / \kappa^{2}\right)$. Since $\kappa<1$, we have $b / \kappa<b / \kappa^{2}$, and so $\Delta$ decreases in the interval $[b, b / \kappa]$. Since $|P| \in(b, b / \kappa)$ and $b \leqslant x \cdot P \leqslant|P|$,

$$
\min _{[b,|P|]} \Delta(t)=\Delta(|P|)=\kappa^{2}(|P|-b)^{2}
$$

and therefore

$$
\begin{equation*}
\Delta(x \cdot P) \geqslant \kappa^{2}(|P|-b)^{2}, \quad \text { for } x \cdot P \geqslant b \tag{5.2}
\end{equation*}
$$

From (4.9)

$$
|P|-b \geqslant \frac{1-\kappa^{2}}{2|P|}|P-h(x, P, b) x|^{2}, \quad \text { for all } x \cdot P \geqslant b,
$$

which combined with (5.2) yields

$$
\begin{equation*}
\sqrt{\Delta(x \cdot P)} \geqslant \kappa \frac{1-\kappa^{2}}{2|P|}|P-h(x, P, b) x|^{2}, \quad \text { for all } x \cdot P \geqslant b . \tag{5.3}
\end{equation*}
$$

Since $\rho\left(x_{0}\right)=h\left(x_{0}, P, b\right)$, and $\mathcal{S} \subset Q_{r_{0}}$, we get that $h\left(x_{0}, P, b\right) \leqslant r_{0}$. From (H2), $|P| \geqslant r_{0} \frac{1+\kappa}{\tau}$. Therefore we obtain the estimate

$$
\begin{align*}
\sqrt{\Delta\left(x_{0} \cdot P\right)} & \geqslant \kappa \frac{1-\kappa^{2}}{2|P|}\left|P-h\left(x_{0}, P, b\right) x_{0}\right|^{2} \geqslant \kappa \frac{1-\kappa^{2}}{2|P|}\left(|P|-r_{0}\right)^{2} \\
& \geqslant \frac{\kappa(1-\kappa)(1+\kappa-\tau)^{2}}{2(1+\kappa)}|P| . \tag{5.4}
\end{align*}
$$

Clearly, $\left|\Delta\left(x_{0} \cdot P\right)-\Delta(x \cdot P)\right| \leqslant C(\kappa)|P|^{2}\left|x-x_{0}\right|$ which completes the proof of the lemma.

### 5.2. Application of the setup from Section 2 to the solution of the near field refractor problem

We apply the setup in that section with the spaces $X=\bar{\Omega}$, and $Y=\bar{D}$. The Radon measure $\omega$ in $\bar{\Omega}$ there is now given by $\omega=f d x$ with $f \in L^{1}(\bar{\Omega})$ nonnegative. If $\mathcal{S}$ is a near field refractor in the sense of Definition 5.1, then it is proved in Lemma 5.4 below that the map $\Phi=\mathcal{R}_{\mathcal{S}} \in C_{s}(\bar{\Omega}, \bar{D})$. From Lemma 2.1 we therefore obtain that the set function

$$
\begin{equation*}
\mathcal{M}_{\mathcal{S}, f}(F):=\int_{\mathcal{R}_{\mathcal{S}}^{-1}(F)} f d x \tag{5.5}
\end{equation*}
$$

is a Radon measure defined on $\bar{D}$. We call this measure the near field refractor measure associated with $f$ and the refractor $\mathcal{S}$.

Let $\mathcal{S}_{\rho}$ denote the near field refractor with defining radial function $\rho$ given by Definition 5.1. We let $\mathcal{F}$ be the family of functions in $C^{+}(\bar{\Omega})$ given by
$\mathcal{F}=\left\{\rho(x): \mathcal{S}_{\rho}\right.$ is a near field refractor $\}$.
On $\mathcal{F}$ we define the mapping $\mathcal{T}$ by

$$
\mathcal{T}(\rho)=\mathcal{R}_{\mathcal{S}_{\rho}} .
$$

To continue with the application of the results from Section 2 , we need to show also that $\mathcal{T}$ is continuous at each $\rho \in \mathcal{F}$ in the sense of Definition 2.2. This is proved in Lemma 5.5 below.

Lemma 5.4. For each near field refractor $\mathcal{S}$, we have $\mathcal{R}_{\mathcal{S}} \in C_{s}(\bar{\Omega}, \bar{D})$.
Proof. By Remark 5.2, $\mathcal{R}_{\mathcal{S}}$ is surjective. Now show that $\mathcal{R}_{\mathcal{S}}(x)$ is single-valued for a.e. $x$ with respect to $\omega$. If $\mathcal{R}_{\mathcal{S}}(x)$ contains more than one point, then $\mathcal{S}$ parameterized by $\rho$ has two distinct supporting ovals $\mathcal{O}\left(P_{1}, b_{1}\right)$ and $\mathcal{O}\left(P_{2}, b_{2}\right)$ at $\rho(x) x$ with $P_{1} \neq P_{2}$. We claim that $\rho(x) x$ is a singular point of $\mathcal{S}$. Otherwise, if $\mathcal{S}$ has tangent hyperplane $\Pi$ at $\rho(x) x$, then $\Pi$ must coincide both with the tangent hyperplane of $\mathcal{O}\left(P_{1}, b_{1}\right)$ and that of $\mathcal{O}\left(P_{2}, b_{2}\right)$ at $\rho(x) x$. From the Snell law we get that $\frac{P_{1}-\rho(x) x}{\left|P_{1}-\rho(x) x\right|}=\frac{P_{2}-\rho(x) x}{\left|P_{2}-\rho(x) x\right|}:=m$, and so the ray through $X=\rho(x) x$ with direction $m$ contains $P_{1}, P_{2}$ and therefore $P_{1}=P_{2}$ from assumption (H2), a contradiction. Since the graph of $\mathcal{S}$ is Lipschitz and $|\partial \Omega|=0$, the set of singular points of $\mathcal{S}$ has measure zero and therefore $\mathcal{R}_{\mathcal{S}}(x)$ is single-valued for a.e. $x \in \bar{\Omega}$.

To prove that $\mathcal{R}_{\mathcal{S}}$ is continuous, let $x_{i} \rightarrow x_{0}$ and $P_{i} \in \mathcal{R}_{\mathcal{S}}\left(x_{i}\right)$. Let $\mathcal{O}\left(P_{i}, b_{i}\right)$ be a supporting oval to $\mathcal{S}$ at $\rho\left(x_{i}\right) x_{i}$. Then

$$
\begin{equation*}
\rho(x)+\kappa\left|P_{i}-\rho(x) x\right| \leqslant b_{i} \quad \text { for } x \in \bar{\Omega}, \tag{5.6}
\end{equation*}
$$

with equality at $x=x_{i}$ and $x \cdot P_{i} \geqslant b_{i}$ for all $x \in \bar{\Omega}$. Assume that $a_{1} \leqslant \rho(x) \leqslant r_{0}$ on $\bar{\Omega}$ for some constant $a_{1}>0$. From (4.7) and (H2) we get $a_{1}(1-\kappa)+\kappa\left|P_{i}\right| \leqslant b_{i} \leqslant \kappa\left|P_{i}\right|+r_{0}(1+\kappa) \leqslant(\kappa+\tau)\left|P_{i}\right|$. Therefore selecting a subsequence we can assume that $P_{i} \rightarrow P_{0} \in \bar{D}$ and $b_{i} \rightarrow b_{0}$, as $i \rightarrow \infty$. By taking limit in (5.6), one obtains that the oval $\mathcal{O}\left(P_{0}, b_{0}\right)$ supports $\mathcal{S}$ at $\rho\left(x_{0}\right) x_{0}, x \cdot P_{0} \geqslant b_{0}$, and $P_{0} \in \mathcal{R}_{\mathcal{S}}\left(x_{0}\right)$.

Lemma 5.5. The refractor mapping $\mathcal{T}(\rho)=\mathcal{R}_{\mathcal{S}_{\rho}}$ is continuous at each $\rho \in \mathcal{F}$.
Proof. Suppose $\rho_{j} \rightarrow \rho$ uniformly as $j \rightarrow \infty$. Let $x_{0} \in \bar{\Omega}$ and $P_{j} \in \mathcal{R}_{\mathcal{S}_{\rho_{j}}}\left(x_{0}\right)$. Then there exists $b_{j}$ such that $\rho_{j}(x) \leqslant$ $h\left(x, P_{j}, b_{j}\right)$ for all $x \in \bar{\Omega}$ with equality at $x=x_{0}$ and with $x \cdot P_{j} \geqslant b_{j}$. As in the proof of Lemma 5.4, $\kappa\left|P_{j}\right|+$ $a(1-\kappa) \leqslant b_{j} \leqslant(\kappa+\tau)\left|P_{j}\right|$ for some $a>0$, so there exists a subsequence $P_{j_{k}} \rightarrow P_{0}$ and $P_{0} \in \mathcal{R}_{\mathcal{S}_{\rho}}\left(x_{0}\right)$.

We therefore can apply Lemma 2.3 to obtain that the definition of refractor measure given in (5.5) is stable by uniform limits, i.e., if $\rho_{j} \rightarrow \rho$ uniformly, then $\mathcal{M}_{\mathcal{S}_{\rho_{j}}, f} \rightarrow \mathcal{M}_{\mathcal{S}_{\rho}, f}$ weakly.

To be able to apply Theorem 2.5 , we next need to verify that the family $\mathcal{F}$ and the map $\mathcal{T}$ satisfy conditions (A1)-(A3) from Subsection 2.1. Indeed, (A1) follows immediately from the definition of refractor. Condition (A2) immediately follows from the definition of refractor.

It remains to verify (A3). For that we use the estimates for ovals proved in Section 4. Indeed, with the notation in condition (A3) we will take

$$
h_{t, y_{0}}(x)=h(x, P, b)
$$

with the understanding that $t=b$, and $y_{0}=P$, and $h(x, P, b)$ is the oval defined by (4.5). In other words, we will show that the family

$$
\left\{h(\cdot, P, b): \kappa|P|<b<\kappa|P|+(1-\kappa) r_{0}\right\} \subset \mathcal{F},
$$

and verifies (A3), with $r_{0}$ from (H2). Indeed, to show the inclusion, if $b<\kappa|P|+(1-\kappa) r_{0}$, then from (H2) and (H1) we have $b<\kappa|P|+\frac{1-\kappa}{1+\kappa} \tau|P| \leqslant(\kappa+\tau)|P| \leqslant x \cdot P$ for all $x \in \Omega$. So the oval $h(x, P, b) x$ refracts in $\Omega$ and in particular $P \in \mathcal{T}(h(\cdot, P, b))(x)$ for all $x \in \bar{\Omega}$, that is, (A3)(a) holds. Condition (A3)(b) is trivial. Condition (A3)(c)
follows from the second identity in (4.7). To verify (A3)(d), we notice that since $\Delta(x \cdot P)$ has a lower bound given in (5.4), we obtain that $\left|h\left(x, P, b^{\prime}\right)-h(x, P, b)\right| \leqslant C\left|b^{\prime}-b\right|$, with $C$ depending only on the constants in (H1) and (H2).

The notion of weak solution is introduced through conservation of energy.
Definition 5.6. A near field refractor $\mathcal{S}$ is a weak solution of the near field refractor problem for the case $\kappa<1$ with emitting illumination intensity $f(x)$ on $\bar{\Omega}$ and prescribed refracted illumination intensity $\mu$ on $\bar{D}$ if for any Borel set $F \subset \bar{D}$

$$
\begin{equation*}
\mathcal{M}_{\mathcal{S}, f}(F)=\int_{\mathcal{R}_{\mathcal{S}}^{-1}(F)} f d x=\mu(F) \tag{5.7}
\end{equation*}
$$

We are now ready to apply Theorem 2.5 to solve the near field refractor problem when the measure $\mu$ is a linear combination of deltas.

### 5.2.1. Existence for sum of Dirac measures

Theorem 5.7. Suppose (H1) and (H2) hold. Let $P_{1}, \ldots, P_{N}$ be distinct points in $\bar{D}, g_{1}, \ldots, g_{N}$ are positive numbers, and $f \in L^{1}(\Omega)$ with $f>0$ a.e. in $\Omega$ such that

$$
\begin{equation*}
\int_{\bar{\Omega}} f(x) d x=\sum_{i=1}^{N} g_{i} . \tag{5.8}
\end{equation*}
$$

Then, for each $b_{1}$ with $\kappa\left|P_{1}\right|<b_{1}<\kappa\left|P_{1}\right|+r_{0} \frac{(1-\kappa)^{2}}{1+\kappa}$, there exists a unique $\left(b_{2}, \ldots, b_{N}\right)$ such that the poly-oval $\mathcal{S}=\{\rho(x) x: x \in \bar{\Omega}\}$ with

$$
\begin{equation*}
\rho(x)=\min _{1 \leqslant i \leqslant N} h\left(x, P_{i}, b_{i}\right) \tag{5.9}
\end{equation*}
$$

is a weak solution to the near field refractor problem. Moreover, $\mathcal{M}_{\mathcal{S}, f}\left(\left\{P_{i}\right\}\right)=g_{i}$ for $1 \leqslant i \leqslant N$.
Proof. To prove the theorem, we apply Theorem 2.5. So we only need to verify that there exists $\rho_{0}(x)=$ $\min _{1 \leqslant i \leqslant N} h\left(x, P_{i}, b_{i}^{0}\right)$ satisfying $\mathcal{M}_{\mathcal{S}_{\rho_{0}}, f}\left(P_{i}\right) \leqslant g_{i}$ for $2 \leqslant i \leqslant N$.

Rewrite $b_{1}=\kappa\left|P_{1}\right|+\left(r_{0}-\sigma\right) \frac{(1-\kappa)^{2}}{1+\kappa}$ for some $\sigma>0$. Let $b_{1}^{0}=b_{1}$, and $b_{i}^{0}=\kappa\left|P_{i}\right|+\left(r_{0}-\sigma\right)(1-\kappa)$ for $2 \leqslant i \leqslant N$. Then $\rho_{0}(x)=h\left(x, P_{1}, b_{1}^{0}\right)$, because $h\left(x, P_{1}, b_{1}^{0}\right) \leqslant \frac{b_{1}^{0}-\kappa\left|P_{1}\right|}{1-\kappa} \leqslant \frac{\left(r_{0}-\sigma\right)(1-\kappa)}{1+\kappa}=\frac{b_{i}^{0}-\kappa\left|P_{i}\right|}{1+\kappa} \leqslant h\left(x, P_{i}, b_{i}^{0}\right)$ for $2 \leqslant i \leqslant N$, from (H2) and (4.7). Hence $\mathcal{M}_{\mathcal{S}_{0}, f}\left(\left\{P_{i}\right\}\right)=0$ for $i \neq 1$. The uniqueness follows from Theorem 2.7.

### 5.2.2. Existence in the general case

Theorem 5.8. Assume conditions $(\mathrm{H} 1)$ and $(\mathrm{H} 2)$. Let $\mu$ be a Radon measure on $\bar{D}, f \in L^{1}(\Omega)$ with $f>0$ a.e., and satisfying the energy conservation condition

$$
\int_{\Omega} f(x) d x=\mu(\bar{D})
$$

Then given $X_{0} \in Q_{r_{0}}$ with $0<\left|X_{0}\right|<\left(\frac{1-\kappa}{1+\kappa}\right)^{3} r_{0}$, there exists a weak solution of the near field refractor problem passing through $X_{0}$.

Proof. We assume first that $\mu=\sum_{i=1}^{N} g_{i} \delta_{P_{i}}$, with $g_{i}>0$ and $P_{i}$ distinct points in $\bar{D}$. From Theorem 5.7, given $b_{1} \in\left(\kappa\left|P_{1}\right|, \kappa\left|P_{1}\right|+r_{0} \frac{(1-\kappa)^{2}}{1+\kappa}\right)$ there exists a unique $\left(b_{2}, \ldots, b_{N}\right)$ such that $\mathcal{S}$, defined by the radial function $\rho\left(x, b_{1}\right)=$ $\min _{i} h\left(x, P_{i}, b_{i}\right)$, is a weak solution to the near field refractor problem. By the comparison Theorem 2.7, the function $\rho\left(x, b_{1}\right)$ is increasing in $b_{1}$ and continuous for $\left(x, b_{1}\right) \in \bar{\Omega} \times\left(\kappa\left|P_{1}\right|, \kappa\left|P_{1}\right|+r_{0} \frac{(1-\kappa)^{2}}{1+\kappa}\right)$. Let $t_{1}=\kappa\left|P_{1}\right|+\left(r_{0}-\sigma\right) \frac{(1-\kappa)^{2}}{1+\kappa}$ for $0<\sigma<r_{0}$. We shall first prove that

$$
\begin{equation*}
\rho\left(x, t_{1}\right) \geqslant\left(\frac{1-\kappa}{1+\kappa}\right)^{3}\left(r_{0}-\sigma\right), \quad \forall x \in \bar{\Omega} . \tag{5.10}
\end{equation*}
$$

We have $\rho\left(x, t_{1}\right)=\min _{1 \leqslant i \leqslant N} h\left(x, P_{i}, b_{i}\right)$ with $b_{1}=t_{1}$ and some $b_{2}, \ldots, b_{N}$. From (4.7)

$$
\begin{equation*}
\frac{b_{i}-\kappa\left|P_{i}\right|}{1-\kappa} \geqslant h\left(x, P_{i}, b_{i}\right) \geqslant \rho\left(x, t_{1}\right), \quad i=1, \ldots, N ; \forall x \in \bar{\Omega} . \tag{5.11}
\end{equation*}
$$

Also there exists $x_{1} \in \bar{\Omega}$ such that $\rho\left(x_{1}, t_{1}\right)=h\left(x_{1}, P_{1}, t_{1}\right)$ and then again by (4.7), $\rho\left(x_{1}, t_{1}\right) \geqslant\left(\frac{1-\kappa}{1+\kappa}\right)^{2}\left(r_{0}-\sigma\right)$. Hence from (5.11) we get

$$
\begin{equation*}
\frac{b_{i}-\kappa\left|P_{i}\right|}{1-\kappa} \geqslant\left(\frac{1-\kappa}{1+\kappa}\right)^{2}\left(r_{0}-\sigma\right), \quad i=1, \ldots, N . \tag{5.12}
\end{equation*}
$$

Once again by (4.7), $h\left(x, P_{i}, b_{i}\right) \geqslant \frac{b_{i}-\kappa\left|P_{i}\right|}{1+\kappa}$, which combined with (5.12) yields

$$
h\left(x, P_{i}, b_{i}\right) \geqslant\left(\frac{1-\kappa}{1+\kappa}\right)^{3}\left(r_{0}-\sigma\right), \quad i=1, \ldots, N
$$

and hence (5.10) follows. On the other hand, $\rho\left(x, b_{1}\right) \leqslant h\left(x, P_{1}, b_{1}\right) \leqslant \frac{b_{1}-\kappa\left|P_{1}\right|}{1-\kappa}$ by (4.7) for all $\left(x, b_{1}\right) \in \bar{\Omega} \times$ $\left(\kappa\left|P_{1}\right|, \kappa\left|P_{1}\right|+r_{0} \frac{(1-\kappa)^{2}}{1+\kappa}\right)$ and hence given $\delta>0$, we get $\rho\left(x, b_{1}\right)<\delta$ for all $x \in \bar{\Omega}$ as long as $b_{1}$ is sufficiently close to $\kappa\left|P_{1}\right|$. Suppose now that $X_{0} \in Q_{r_{0}}$ with $0<\left|X_{0}\right|<\left(\frac{1-\kappa}{1+\kappa}\right)^{3} r_{0}$ and with $x_{0}=\frac{X_{0}}{\left|X_{0}\right|} \in \bar{\Omega}$. Hence from (5.10) and the continuity of $\rho\left(x_{0}, \cdot\right)$, we obtain that there exists $b_{1} \in\left(\kappa\left|P_{1}\right|, \kappa\left|P_{1}\right|+r_{0} \frac{(1-\kappa)^{2}}{1+\kappa}\right)$ such that $\rho\left(x_{0}, b_{1}\right)=\left|X_{0}\right|$.

For the general case of a Radon measure $\mu$ in $\bar{D}$, we choose a sequence of measures $\mu_{\ell}$ such that each one is a finite combination of Dirac measures and $\mu_{\ell} \rightarrow \mu$ weakly with $\mu_{\ell}(\bar{D})=\mu(\bar{D})$. From the above, let $\mathcal{S}_{\ell}$ be the near field refractor corresponding to the measure $\mu_{\ell}$ and parameterized by $\rho_{\ell}(x) x$ and passing through the point $X_{0}$. Thus, $x_{0}=\frac{X_{0}}{\left|X_{0}\right|} \in \bar{\Omega}$ and $\rho_{\ell}\left(x_{0}\right)=\left|X_{0}\right|$. i.e., $\left|X_{0}\right| \in \operatorname{Range} \rho_{\ell}$ for all $\ell$. We also notice that if $R_{0} \in \operatorname{Range}(h(\cdot, P, b))$, then by Lemma 4.1

$$
\frac{1-\kappa}{1+\kappa} R_{0} \leqslant h(x, P, b) \leqslant \frac{1+\kappa}{1-\kappa} R_{0} .
$$

From Lemma 5.3 and the proof of Lemma 5.5 , the family $\left\{\rho \in \mathcal{F}: C_{0} \leqslant \rho \leqslant C_{1}\right\}$ is compact. Then applying Theorem 2.8 we obtain the existence of the desired solution.

## 6. Near field refractor problem, existence of solutions for $\kappa>1$

### 6.1. Formulation of problem

Let $\Omega \subset S^{n-1}$ be a domain with $|\partial \Omega|=0$ (measure in the sphere), and let $D \subset \mathbb{R}^{n}$ be a compact hypersurface with $0 \notin \bar{D}$.

We assume:
(H3) $\inf _{x \in \bar{\Omega}, P \in \bar{D}} x \cdot \frac{P}{|P|} \geqslant \frac{1}{\kappa}+\tau$ for some $0<\tau<1-\frac{1}{\kappa}$.
(H4) Let $0<r_{0}<\frac{\kappa^{2} \tau^{2}}{4(\kappa-1)^{2}} \inf _{P \in D}|P|$ and consider the cone in $\mathbb{R}^{n}$

$$
Q_{r_{0}}=\left\{t x: x \in \bar{\Omega}, 0<t \leqslant r_{0}\right\} .
$$

For each $m \in S^{n-1}$ and for each $X \in Q_{r_{0}}$ we assume that $\bar{D} \cap\{X+t m: t \geqslant 0\}$ contains at most one point. That is, for each $X \in Q_{r_{0}}$ each ray emanating from $X$ intersects $\bar{D}$ at most in one point.

Similarly with the case $\kappa<1$, but now keeping in mind (4.11) and (4.12), we define the notion of refractor when $\kappa>1$.

Definition 6.1. Let $\mathcal{S}=\{x \rho(x): x \in \bar{\Omega}\} \subset Q_{r_{0}}$ be a surface. We say that $\mathcal{S}$ is a near field refractor if for any point $y \rho(y) \in \mathcal{S}$ there exist $P \in \bar{D}$ and $b>0$ such that the refracting oval $\mathcal{O}(P, b)$ supports $\mathcal{S}$ at $y \rho(y)$, i.e. $\rho(x) \geqslant$ $h(x, P, b)$ for all $x \in \bar{\Omega}$ with equality at $x=y$, and

$$
\begin{equation*}
\bar{\Omega} \subset\left\{x \in S^{n-1}: x \cdot \frac{P}{|P|} \geqslant I(P, b)\right\} \tag{6.1}
\end{equation*}
$$

where $I(P, b)$ is defined in (4.13). The near field refractor map of $\mathcal{S}$ is defined by
$\mathcal{R}_{\mathcal{S}}(x)=\{P \in \bar{D}$ : there exists a supporting oval $\mathcal{O}(P, b)$ to $\mathcal{S}$ at $\rho(x) x\}$.
Remark 6.2. If $\mathcal{S}=\{\rho(x) x: x \in \bar{\Omega}\}$ is a refractor, then for any $x, x_{0} \in \bar{\Omega}$ we have

$$
\rho(x) \leqslant \sqrt{2 \sup _{P \in D}|P|} \sqrt{\rho\left(x_{0}\right)}
$$

Indeed, if $h\left(z, P_{x}, b_{x}\right)$ is a supporting oval at $\rho(x) x$, then from Lemma 4.3 we have $\rho\left(x_{0}\right) \geqslant h\left(x_{0}, P_{x}, b_{x}\right) \geqslant$ $\frac{\kappa\left|P_{x}\right|-b_{x}}{\kappa-1} \geqslant \frac{h\left(x, P_{x}, b_{x}\right)^{2}}{2\left|P_{x}\right|}=\frac{\rho(x))^{2}}{2\left|P_{x}\right|}$.

Remark 6.3. $\mathcal{R}_{\mathcal{S}}(\bar{\Omega})=\bar{D}$ for any refractor $\mathcal{S}=\{\rho(x) x: x \in \bar{\Omega}\}$. To prove the remark, we first notice that if $P \in \bar{D}$ and $h\left(x_{0}, P, b\right) \leqslant r_{0}$ for some $x_{0} \in \bar{\Omega}$, then $I(P, b) \leqslant \frac{1}{\kappa}+\tau$. Indeed, we have from Lemma 4.3(d) that $I(P, b)-\frac{1}{\kappa} \leqslant$ $\frac{2 \sqrt{\kappa-1}}{\kappa} \frac{\sqrt{\kappa|P|-b}}{\sqrt{|P|}} \leqslant \frac{2(\kappa-1)}{\kappa} \frac{\sqrt{r_{0}}}{\sqrt{|P|}} \leqslant \tau$ from the choice of $r_{0}$ in condition (H4). Given $P \in \bar{D}$, let $\mathcal{O}\left(P, b_{1}\right)$ be the oval with

$$
b_{1}=\inf \{b \in(|P|, \kappa|P|): h(x, P, b) \leqslant \rho(x) \text { in } \bar{\Omega}\} .
$$

Obviously, $h\left(x, P, b_{1}\right)$ touches $\mathcal{S}$ at some $x_{1} \in \bar{\Omega}$.
Lemma 6.4. If $\mathcal{S}$ is a near field refractor with defining function $\rho(x)$, then $\rho$ is Lipschitz in $\bar{\Omega}$ with a Lipschitz constant depending only on the constants in the assumptions $(\mathrm{H} 3)$ and $(\mathrm{H} 4)$.

Proof. As in the proof of Lemma 5.3, the Lipschitz continuity and constant of $h(x, P, b)$ is reduced to the Lipschitz continuity and lower bound of $\Delta$, where

$$
\begin{aligned}
& \Delta(t)=\left(\kappa^{2} t-b\right)^{2}-\left(\kappa^{2}-1\right)\left(\kappa^{2}|P|^{2}-b^{2}\right) \\
& h(x, P, b)=\frac{\left(\kappa^{2} x \cdot P-b\right)-\sqrt{\Delta(x \cdot P)}}{\kappa^{2}-1} \text { for } x \in \bar{\Omega}
\end{aligned}
$$

By (H3) $x \cdot \frac{P}{|P|} \geqslant \frac{1}{\kappa}+\tau$ for $x \in \bar{\Omega}$. From Lemma 4.3(a) and (d) we have

$$
\begin{aligned}
I(P, b)-\frac{1}{\kappa} & =\frac{b+\sqrt{\left(\kappa^{2}-1\right)\left(\kappa^{2}|P|^{2}-b^{2}\right)}}{\kappa^{2}|P|}-\frac{1}{\kappa} \\
& \leqslant \frac{2 \sqrt{\kappa-1}}{\kappa} \frac{\sqrt{\kappa|P|-b}}{\sqrt{|P|}} \\
& \leqslant \frac{2(\kappa-1)}{\kappa} \frac{\sqrt{r_{0}}}{\sqrt{|P|}} \text { if } h\left(x_{0}, P, b\right) \leqslant r_{0} \\
& \leqslant \tau-\sigma,
\end{aligned}
$$

where $\sigma=\tau-\frac{2(\kappa-1)}{\kappa} \frac{\sqrt{r_{0}}}{\sqrt{\inf P \in D|P|}}>0$ by (H4). Thus, if $h\left(x_{0}, P, b\right) \leqslant r_{0}$, for $x \in \bar{\Omega}$ we have $x \cdot \frac{P}{|P|} \geqslant I(P, b)+\sigma$ and furthermore

$$
\begin{align*}
\Delta(x \cdot P) & \geqslant\left[\kappa^{2}|P|(I(P, b)+\sigma)-b\right]^{2}-\left(\kappa^{2}-1\right)\left(\kappa^{2}|P|^{2}-b^{2}\right) \\
& \geqslant\left[\kappa^{2}|P| I(P, b)-b\right]^{2}+\left(\kappa^{2}|P| \sigma\right)^{2}-\left(\kappa^{2}-1\right)\left(\kappa^{2}|P|^{2}-b^{2}\right) \\
& \geqslant\left(\kappa^{2} \inf _{P \in D}|P| \sigma\right)^{2} . \tag{6.2}
\end{align*}
$$

Therefore, the uniform Lipschitz continuity for ovals and refractors contained in $Q_{r_{0}}$ on $\bar{\Omega}$ follows.

### 6.2. Application of the setup from Subsection 2.2 to the solution of the near field refractor problem with $\kappa>1$

We apply the setup in that subsection with the spaces $X=\bar{\Omega}$, and $Y=\bar{D}$. The Radon measure $\omega$ in $\bar{\Omega}$ there is given by $\omega=f d x$ with $f \in L^{1}(\bar{\Omega})$ nonnegative. If $\mathcal{S}$ is a near field refractor in the sense of Definition 6.1, then it is proved in Lemma 6.5 below that the map $\mathcal{R}_{\mathcal{S}} \in C_{s}(\bar{\Omega}, \bar{D})$. From Lemma 2.1 we therefore obtain that the set function

$$
\begin{equation*}
\mathcal{M}_{\mathcal{S}, f}(F):=\int_{\mathcal{R}_{\mathcal{S}}^{-1}(F)} f d x \tag{6.3}
\end{equation*}
$$

is a Radon measure on $\bar{D}$. We call this measure the near field refractor measure associated with $f$ and the refractor $\mathcal{S}$.
We next introduce the family $\mathcal{F}$. Let $\mathcal{S}_{\rho}$ denote the near field refractor with defining radial function $\rho$ given by Definition 6.1. We let $\mathcal{F}$ be the family of functions in $C^{+}(\bar{\Omega})$ given by

$$
\mathcal{F}=\left\{\rho(x): \mathcal{S}_{\rho} \text { is a near field refractor }\right\} .
$$

On $\mathcal{F}$ we introduce the mapping $\mathcal{T}$ by

$$
\mathcal{T}(\rho)=\mathcal{R}_{\mathcal{S}_{\rho}} .
$$

To continue with the application of the results from Subsection 2.2, we show in the next two lemmas that $\mathcal{R}_{\mathcal{S}} \in$ $C_{s}(\bar{\Omega}, \bar{D})$ and $\mathcal{T}$ is continuous at each $\rho \in \mathcal{F}$ in the sense of Definition 2.2.

Lemma 6.5. For any near field refractor $\mathcal{S}$, we have $\mathcal{R}_{\mathcal{S}} \in C_{\mathcal{S}}(\bar{\Omega}, \bar{D})$.
Proof. As in the proof of Lemma 5.4, using (H4), one can show that $\mathcal{R}_{\mathcal{S}}(x)$ is single-valued for a.e. $x$ with respect to $\omega$.

To prove that $\mathcal{R}_{\mathcal{S}}$ is continuous, let $x_{i} \rightarrow x_{0}$ and $P_{i} \in \mathcal{R}_{\mathcal{S}}\left(x_{i}\right)$. Let $\mathcal{O}\left(P_{i}, b_{i}\right)$ be a supporting oval to $\mathcal{S}$ at $\rho\left(x_{i}\right) x_{i}$. We have $a \leqslant \rho\left(x_{i}\right)=h\left(x_{i}, P_{i}, b_{i}\right) \leqslant r_{0}$ and from Lemma 4.3(b) we get $a \leqslant \sqrt{2\left|P_{i}\right|} \sqrt{\frac{\kappa\left|P_{i}\right|-b_{i}}{\kappa-1}}$, and so $b_{i} \leqslant \kappa\left|P_{i}\right|-$ $\frac{a^{2}(\kappa-1)}{2 \sup p_{D}|P|}$. On the other hand, by Lemma 4.3(c) we have $\left|P_{i}-\rho\left(x_{i}\right) x_{i}\right| \leqslant \frac{b_{i}-\left|P_{i}\right|}{\kappa-1}$. Since $\left|P_{i}-\rho\left(x_{i}\right) x_{i}\right| \geqslant\left|P_{i}\right|-r_{0}$, we obtain $b_{i} \geqslant\left|P_{i}\right|+(\kappa-1)\left(\inf _{D}|P|-r_{0}\right)$. Therefore selecting a subsequence we can assume that $P_{i} \rightarrow P_{0}$ and $b_{i} \rightarrow b_{0}$, as $i \rightarrow \infty$. Taking limits one obtains that the oval $\mathcal{O}\left(P_{0}, b_{0}\right)$ supports $\mathcal{S}$ at $\rho\left(x_{0}\right) x_{0}, x \cdot \frac{P_{0}}{\left|P_{0}\right|} \geqslant I\left(P_{0}, b_{0}\right)$, and $P_{0} \in \mathcal{R}_{\mathcal{S}}\left(x_{0}\right)$. This completes the proof.

By Lemma 6.4 and modifying the proof of Lemma 6.5, we also obtain the following analogue of Lemma 5.5 when $\kappa>1$.

Lemma 6.6. The refractor mapping $\mathcal{T}(\rho)=\mathcal{R}_{\mathcal{S}_{\rho}}$ is continuous at each $\rho \in \mathcal{F}$. Moreover, for $0<C_{0}<C_{1}$, $\left\{\rho \in \mathcal{F}: C_{0} \leqslant \rho(x) \leqslant C_{1}\right\}$ is compact in $C(\bar{\Omega})$.

To be able to apply Theorem 2.9 , we next need to verify that the family $\mathcal{F}$ and the map $\mathcal{T}$ satisfy conditions $\left(\mathrm{A} 1^{\prime}\right)-\left(\mathrm{A} 3^{\prime}\right)$ from Subsection 2.2. Indeed, $\left(\mathrm{A}^{\prime}\right)$ and ( $\mathrm{A} 2^{\prime}$ ) follow immediately from the Definition 6.1 of refractor, Lemma 6.5, and Lemma 6.6.

It remains to verify $\left(\mathrm{A} 3^{\prime}\right)$. For that we use the estimates for ovals proved in Subsection 4.2. Indeed, with the notation in condition ( $\mathrm{A} 3^{\prime}$ ) we will take

$$
h_{t, y_{0}}(x)=h(x, P, b)
$$

with the understanding that $t=b$, and $y_{0}=P$, and $h(x, P, b)$ is the oval defined by (4.11) and (4.12). By Lemma 4.3 and Remark 6.3, we have that the family

$$
\left\{h(\cdot, P, b): \kappa|P|-\frac{(\kappa-1) r_{0}^{2}}{2 \sup _{D}|P|}<b<\kappa|P|\right\} \subset \mathcal{F},
$$

with $r_{0}$ from (H4). Obviously, $P \in \mathcal{T}(h(\cdot, P, b))(x)$ for all $x \in \bar{\Omega}$, that is, (A3 $\left.{ }^{\prime}\right)($ a) holds. Condition (A3')(b) is trivial. Condition (A3')(c) follows Lemma 4.3 parts (a) and (b). To verify (A3')(d), we notice that from the lower bound (6.2), we obtain that $\left|h\left(x, P, b^{\prime}\right)-h(x, P, b)\right| \leqslant C\left|b^{\prime}-b\right|$, with $C$ depending only on the constants in (H3) and (H4).

The notion of weak solution is again introduced through conservation of energy.
Definition 6.7. A near field refractor $\mathcal{S}$ is a weak solution of the near field refractor problem for the case $\kappa>1$ with emitting illumination intensity $f(x)$ on $\bar{\Omega}$ and prescribed refracted illumination intensity $\mu$ on $\bar{D}$ if for any Borel set $F \subset \bar{D}$

$$
\begin{equation*}
\mathcal{M}_{\mathcal{S}, f}(F)=\int_{\mathcal{R}_{\mathcal{S}}^{-1}(F)} f d x=\mu(F) \tag{6.4}
\end{equation*}
$$

### 6.2.1. Existence of solutions for sum of Dirac measures

This follows from Theorem 2.9.
Theorem 6.8. Suppose $(\mathrm{H} 3)$ and $(\mathrm{H} 4)$ hold. Let $P_{1}, \ldots, P_{N}$ be distinct points in $\bar{D}, g_{1}, \ldots, g_{N}$ are positive numbers, and $f \in L^{1}(\Omega)$ with $f>0$ a.e. in $\Omega$ such that

$$
\begin{equation*}
\int_{\bar{\Omega}} f(x) d x=\sum_{i=1}^{N} g_{i} . \tag{6.5}
\end{equation*}
$$

Then for each $b_{1}$ such that $\kappa\left|P_{1}\right|-\sigma<b_{1}<\kappa\left|P_{1}\right|$, with $\sigma=\frac{(\kappa-1) r_{0}^{4}}{8\left(\sup _{D}|P|\right)^{3}}$, there exist a unique $\left(b_{2}, \ldots, b_{N}\right)$ such that the poly-oval $\mathcal{S}=\{\rho(x) x: x \in \bar{\Omega}\}$ with

$$
\begin{equation*}
\rho(x)=\max _{1 \leqslant i \leqslant N} h\left(x, P_{i}, b_{i}\right) \tag{6.6}
\end{equation*}
$$

is a weak solution to the near field refractor problem. Moreover, $\mathcal{M}_{\mathcal{S}, f}\left(\left\{P_{i}\right\}\right)=g_{i}$ for $1 \leqslant i \leqslant N$.
Proof. By Theorem 2.9, it suffices to show that there exists $\left(b_{1}^{0}, \ldots, b_{N}^{0}\right)$ such that

$$
h\left(x, P_{1}, b_{1}^{0}\right) \leqslant \min _{2 \leqslant i \leqslant N} h\left(x, P_{i}, b_{i}^{0}\right) \quad \text { for all } x \in \bar{\Omega} .
$$

Rewrite $b_{1}^{0}=b_{1}=\kappa\left|P_{1}\right|-\epsilon^{2} \sigma$ with $0<\epsilon<1$. Choose $b_{i}^{0}=\kappa\left|P_{i}\right|-\epsilon \frac{(\kappa-1) r_{0}^{2}}{2 \sup _{D}|P|}, 2 \leqslant i \leqslant N$. Then from Lemma 4.3(b), $h\left(x, P_{1}, b_{1}^{0}\right) \leqslant \sqrt{2\left|P_{1}\right|} \sqrt{\frac{\kappa\left|P_{1}\right|-b_{1}^{0}}{\kappa-1}} \leqslant \sqrt{2\left|P_{1}\right|} \sqrt{\frac{\epsilon^{2} \sigma}{\kappa-1}}$. On the other hand, from Lemma 4.3(a), we have for $2 \leqslant i \leqslant N$ that

$$
h\left(x, P_{i}, b_{i}^{0}\right) \geqslant \frac{\kappa\left|P_{i}\right|-b_{i}^{0}}{\kappa-1}=\frac{\epsilon r_{0}^{2}}{2 \sup _{D}|P|} .
$$

By the choice of $\sigma, h\left(x, P_{1}, b_{1}^{0}\right) \leqslant h\left(x, P_{i}, b_{i}^{0}\right)$ for $2 \leqslant i \leqslant N$.

### 6.2.2. Existence in the general case

Theorem 6.9. Assume conditions $(\mathrm{H} 3)$ and $(\mathrm{H} 4)$. Let $\mu$ be a Radon measure on $\bar{D}, f \in L^{1}(\Omega)$ with $f>0$ a.e., and satisfying the energy conservation condition

$$
\int_{\Omega} f(x) d x=\mu(\bar{D})
$$

Then given $X_{0} \in Q_{r_{0}}$ with $0<\left|X_{0}\right|<\frac{\sigma}{\kappa-1}=\frac{r_{0}^{4}}{8\left(\sup _{D}|P|\right)^{3}}$, there exists a weak solution of the near field refractor problem passing through $X_{0}$.

Proof. We assume first that $\mu=\sum_{i=1}^{N} g_{i} \delta_{P_{i}}$, with $g_{i}>0$ and $P_{i}$ pairwise distinct points in $\bar{D}$. From Theorem 6.8, given $b_{1} \in\left(\kappa\left|P_{1}\right|-\sigma, \kappa\left|P_{1}\right|\right)$ there exists a unique $\left(b_{2}, \ldots, b_{N}\right)$ such that $\mathcal{S}_{b_{1}}$, defined by the radial function $\rho\left(x, b_{1}\right)=$ $\max _{i} h\left(x, P_{i}, b_{i}\right)$, is a weak solution to the near field refractor problem. By the comparison Theorem 2.10, the function $\rho\left(x, b_{1}\right)$ is decreasing in $b_{1}$ and continuous for $\left(x, b_{1}\right) \in \bar{\Omega} \times\left(\kappa\left|P_{1}\right|-\sigma, \kappa\left|P_{1}\right|\right)$. For small $\epsilon>0$, from Lemma 4.3(a) we have

$$
\begin{equation*}
\rho\left(x, \kappa\left|P_{1}\right|-(\sigma-\epsilon)\right) \geqslant h\left(x, P_{1}, \kappa\left|P_{1}\right|-(\sigma-\epsilon)\right) \geqslant \frac{\sigma-\epsilon}{\kappa-1}, \quad \forall x \in \bar{\Omega} . \tag{6.7}
\end{equation*}
$$

On the other hand, let $b_{i}(\epsilon), 2 \leqslant i \leqslant N$ be the corresponding $b_{j}$ 's to $b_{1}(\epsilon)=\kappa\left|P_{1}\right|-\epsilon$. We have $\frac{\kappa\left|P_{i}\right|-b_{i}(\epsilon)}{\kappa-1} \leqslant$ $h\left(x, P_{i}, b_{i}(\epsilon)\right) \leqslant \rho\left(x, b_{1}(\epsilon)\right)$. Since $\left|\mathcal{R}_{\mathcal{S}_{b_{1}(\epsilon)}}^{-1}\left(P_{1}\right)\right|>0$, there exists $x_{1}$ such that $\rho\left(x_{1}, b_{1}(\epsilon)\right)=h\left(x_{1}, P_{1}, b_{1}(\epsilon)\right) \leqslant$ $\sqrt{2 \sup _{D}|P|} \sqrt{\frac{\epsilon}{\kappa-1}}$. Consequently, $\kappa\left|P_{i}\right|-b_{i}(\epsilon) \leqslant \sqrt{2 \epsilon(\kappa-1) \sup _{D}|P|}$ and therefore

$$
\rho\left(x, \kappa\left|P_{1}\right|-\epsilon\right)=\max _{i} h\left(x, P_{i}, b_{i}(\epsilon)\right) \leqslant \max _{i} \sqrt{2 \sup _{D}|P|} \sqrt{\frac{\kappa\left|P_{i}\right|-b_{i}}{\kappa-1}} \leqslant C \sqrt[4]{\epsilon} \rightarrow 0,
$$

as $\epsilon \rightarrow 0$. Consequently, by continuity of $\rho\left(x, b_{1}\right)$, given $X_{0}=\left|X_{0}\right| x_{0} \in Q_{r_{0}}$ with $0<\left|X_{0}\right|<\frac{\sigma}{\kappa-1}$, there exists $b_{1}\left(X_{0}\right)$ such that $\rho\left(x_{0}, b_{1}\right)=\left|X_{0}\right|$.

For the general case of a Radon measure $\mu$ in $\bar{D}$, we choose a sequence of measures $\mu_{\ell}$ such that each one is a finite combination of Dirac measures and $\mu_{\ell} \rightarrow \mu$ weakly with $\mu_{\ell}(\bar{D})=\mu(\bar{D})$. From the above, let $\mathcal{S}_{\ell}$ be the near field refractor corresponding to the measure $\mu_{\ell}$ and parameterized by $\rho_{\ell}(x) x$ and passing through the point $X_{0}$. Thus, $\left|X_{0}\right| \in \operatorname{Range}\left(\rho_{l}\right)$ for all $l$. From (6.7), $\left|X_{0}\right|<\lim _{b \rightarrow \alpha_{P}} h(x, P, b)$, where $\alpha_{P}=\kappa|P|-\frac{(\kappa-1) r_{0}^{2}}{2 \sup _{D}|P|}$. By Lemma 4.3 and Lemma 6.6, one can apply Theorem 2.11 to obtain the existence of solutions.

## 7. Further applications

To illustrate the general framework described in Section 2, we briefly show how to recover the results for the far field refractor, proved using mass transport in [5], and also the solution to the second boundary value problem for the Monge-Ampère equation. We only state the results when the measure $\mu$ is a finite combination of Dirac measures. The general case for a general Radon measure follows by approximation as in Theorems 2.8 and 5.8, and noticing that the far field refractor problem is dilation invariant and the second boundary value problem for Monge-Ampère equation is translation invariant.

### 7.1. Far field refractor, $\kappa<1$

We have two domains $\Omega, \Omega^{*} \subset S^{n-1}$ satisfying the condition $x \cdot m \geqslant \kappa$ for all $x \in \Omega, m \in \Omega^{*}$, with $|\partial \Omega|=0$. In this case, refractors are defined with supporting semi-ellipsoids $\rho(x, m, b)=\frac{b}{1-\kappa m \cdot x}$ in [5, Definition 3.1].

We shall apply the setup in Section 2 with the spaces $X=\bar{\Omega}$, and $Y=\overline{\Omega^{*}}$. The Radon measure $\omega$ in $\bar{\Omega}$ is now given by $\omega=f d x$ with $f \in L^{1}(\bar{\Omega})$ nonnegative. If $\mathcal{S}$ is a far field refractor in the sense of [5, Definition 3.1], then it is proved in Lemma 7.1 below that the map $\Phi=\mathcal{N}_{\mathcal{S}} \in C_{s}\left(\bar{\Omega}, \overline{\Omega^{*}}\right)$, where $\mathcal{N}_{\mathcal{S}}$ is defined in [5, Definition 3.2]. From Lemma 2.1 we therefore obtain that the set function

$$
\begin{equation*}
\mathcal{M}_{\mathcal{S}, f}(F):=\int_{\mathcal{N}_{\mathcal{S}}^{-1}(F)} f d x \tag{7.1}
\end{equation*}
$$

is a Radon measure defined on $\overline{\Omega^{*}}$. We call this measure the far field refractor measure associated with $f$ and the refractor $\mathcal{S}$.

We next introduce the family $\mathcal{F}$. Let $\mathcal{S}_{\rho}$ denote the far field refractor with defining radial function $\rho$ given by [5, Definition 3.1]. We let $\mathcal{F}$ be the family of functions in $C^{+}(\bar{\Omega})$ given by

$$
\mathcal{F}=\left\{\rho(x): \mathcal{S}_{\rho} \text { is a far field refractor }\right\} .
$$

On $\mathcal{F}$ we define the mapping $\mathcal{T}$ by

$$
\mathcal{T}(\rho)=\mathcal{N}_{\mathcal{S}_{\rho}} .
$$

To continue with the application of the results from Section 2, we need to also show that $\mathcal{T}$ is continuous at each $\rho \in \mathcal{F}$ in the sense of Definition 2.2. This is proved in Lemma 7.2 below.

Lemma 7.1. For each far field refractor $\mathcal{S}$, we have $\mathcal{N}_{\mathcal{S}} \in C_{s}\left(\bar{\Omega}, \bar{\Omega}^{*}\right)$.
Proof. Suppose $\mathcal{S}$ is parameterized by $\rho(x)$. We first show that $\mathcal{N}_{\mathcal{S}}(\bar{\Omega})=\bar{\Omega}^{*}$. Because if $m \in \bar{\Omega}^{*}$, then letting

$$
b_{1}=\inf \{b: \rho(x) \leqslant \rho(x, m, b) \text { for all } x \in \bar{\Omega}\},
$$

we get that the semi-ellipsoid $\rho\left(x, m, b_{1}\right)$ supports $\rho(x)$ at some $y \in \bar{\Omega}$. Next show that $\mathcal{N}_{\mathcal{S}}(x)$ is single-valued for a.e. $x$ with respect to $\omega$. Indeed, will prove that $\left\{x \in \bar{\Omega}: \mathcal{N}_{\mathcal{S}}(x)\right.$ is not a singleton $\} \subset\{x \in \bar{\Omega}: \rho$ is not differentiable at $x\}$. In fact, if $m_{1}, m_{2} \in \mathcal{N}_{\mathcal{S}}(x)$, and $\rho$ is differentiable at $x$, then $\rho$ has a unique supporting hyperplane $\Pi$ at $x$ having outer unit normal $v$. Since the semi-ellipsoids $\rho\left(x, m_{1}, b_{1}\right)$ and $\rho\left(x, m_{2}, b_{2}\right)$ support $\rho$ at $x$, the hyperplane $\Pi$ supports both semi-ellipsoids at $x$, and then from the Snell law we get that $x-\kappa m_{1}=\lambda_{1} \nu$ and $x-\kappa m_{2}=\lambda_{2} \nu$. But since $\lambda_{1}=\lambda_{2}=\Phi(x \cdot v)$, we get that $m_{1}=m_{2}$. Since the graph of $\mathcal{S}$ is Lipschitz and $|\partial \Omega|=0$, the set of singular points of $\mathcal{S}$ has measure zero and therefore $\mathcal{N}_{\mathcal{S}}(x)$ is single-valued for a.e. $x \in \bar{\Omega}$.

To prove that $\mathcal{N}_{\mathcal{S}}$ is continuous, let $x_{i} \rightarrow x_{0}$ and $m_{i} \in \mathcal{N}_{\mathcal{S}}\left(x_{i}\right)$. Let $\rho\left(x, m_{i}, b_{i}\right)$ be a supporting semi-ellipsoid to $\mathcal{S}$ at $\rho\left(x_{i}\right) x_{i}$. Then

$$
\begin{equation*}
\rho(x) \leqslant \frac{b_{i}}{1-\kappa m_{i} \cdot x} \quad \text { for } x \in \bar{\Omega}, \tag{7.2}
\end{equation*}
$$

with equality at $x=x_{i}$ and $x \cdot m_{i} \geqslant \kappa$ for all $x \in \bar{\Omega}$. Assume that $a_{1} \leqslant \rho(x) \leqslant a_{2}$ on $\bar{\Omega}$ for some constants $a_{2} \geqslant$ $a_{1}>0$. From (7.2) we then get $a_{1}(1-\kappa) \leqslant b_{i} \leqslant a_{2}\left(1-\kappa^{2}\right)$. Therefore selecting a subsequence we can assume that $m_{i} \rightarrow m_{0} \in \bar{\Omega}^{*}$ and $b_{i} \rightarrow b_{0}$, as $i \rightarrow \infty$. By taking limit in (7.2), one obtains that semi-ellipsoid $\rho\left(x, m_{0}, b_{0}\right)$ supports $\mathcal{S}$ at $\rho\left(x_{0}\right) x_{0}$.

Lemma 7.2. The far field refractor mapping $\mathcal{T}(\rho)=\mathcal{N}_{\mathcal{S}_{\rho}}$ is continuous at each $\rho \in \mathcal{F}$.
Proof. Suppose $\rho_{j} \rightarrow \rho$ uniformly as $j \rightarrow \infty$. Let $x_{0} \in \bar{\Omega}$ and $m_{j} \in \mathcal{N}_{\mathcal{S}_{\rho_{j}}}\left(x_{0}\right)$. Then there exists $b_{j}$ such that $\rho_{j}(x) \leqslant$ $\rho\left(x, m_{j}, b_{j}\right)$ for all $x \in \bar{\Omega}$ with equality at $x=x_{0}$ and with $x \cdot m_{j} \geqslant \kappa$. Selecting subsequences as in the proof of Lemma 7.1, we obtain $m_{0} \in \mathcal{N}_{\mathcal{S}_{\rho}}\left(x_{0}\right)$.

We therefore can apply Lemma 2.3 to obtain that the definition of refractor measure given in (7.1) is stable by uniform limits, i.e., if $\rho_{j} \rightarrow \rho$ uniformly, then $\mathcal{M}_{\mathcal{S}_{\rho_{j}}, f} \rightarrow \mathcal{M}_{\mathcal{S}_{\rho}, f}$ weakly.

To be able to apply Theorem 2.5 , we next need to verify that the family $\mathcal{F}$ and the map $\mathcal{T}$ satisfy conditions (A1)-(A3) from Section 2. Indeed, (A1) follows immediately from the definition of far field refractor. Condition (A2) immediately follows from the definition of far field refractor.

It remains to verify (A3). Indeed, with the notation in condition (A3) we will take

$$
h_{t, y_{0}}(x)=\rho(x, m, b)
$$

with the understanding that $t=b$, and $y_{0}=m$, and $\rho(x, m, b)$ is the semi-ellipsoid $E(m, b)$. In other words, we will show that the family

$$
\left\{\rho(\cdot, m, b): m \in \bar{\Omega}^{*}, 0<b<+\infty\right\} \subset \mathcal{F},
$$

and verifies (A3). Indeed, it is clear that $\rho(\cdot, m, b)$ is a far field refractor, and in particular, $m \in \mathcal{T}(\rho(\cdot, m, b))(x)$ for all $x \in \bar{\Omega}$, that is, (A3)(a) holds. Condition (A3)(b) is trivial. Condition (A3)(c) follows from $\rho(x, m, b) \leqslant \frac{b}{1-\kappa^{2}}$. Finally, (A3)(d) follows from $\left|\rho\left(x, m, b^{\prime}\right)-\rho(x, m, b)\right| \leqslant \frac{\left|b^{\prime}-b\right|}{1-\kappa^{2}}$.

The notion of weak solution is introduced through conservation of energy.

Definition 7.3. A far field refractor $\mathcal{S}$ is a weak solution of the far field refractor problem for the case $\kappa<1$ with emitting illumination intensity $f(x)$ on $\bar{\Omega}$ and prescribed refracted illumination intensity $\mu$ on $\bar{D}$ if for any Borel set $F \subset \bar{D}$

$$
\begin{equation*}
\mathcal{M}_{\mathcal{S}, f}(F)=\int_{\mathcal{N}_{\mathcal{S}}^{-1}(F)} f d x=\mu(F) \tag{7.3}
\end{equation*}
$$

We are now ready to apply Theorem 2.5 to solve the far field refractor problem when the measure $\mu$ is a linear combination of deltas.

Theorem 7.4. Let $m_{1}, \ldots, m_{N}$ be distinct points in $\overline{\Omega^{*}}, g_{1}, \ldots, g_{N}$ are positive numbers, $f \in L^{1}(\Omega)$ such that $x \cdot m_{i} \geqslant \kappa$ for $x \in \Omega, 1 \leqslant i \leqslant N$, and

$$
\begin{equation*}
\int_{\bar{\Omega}} f(x) d x=\sum_{i=1}^{N} g_{i} \tag{7.4}
\end{equation*}
$$

Then there exist positive numbers $b_{1}, b_{2}, \ldots, b_{N}$ such that $\mathcal{S}=\{\rho(x) x: x \in \bar{\Omega}\}$ with

$$
\begin{equation*}
\rho(x)=\min _{1 \leqslant i \leqslant N} \rho\left(x, m_{i}, b_{i}\right) \tag{7.5}
\end{equation*}
$$

is a weak solution to the far field refractor problem. Moreover, $\mathcal{M}_{\mathcal{S}, f}\left(\left\{m_{i}\right\}\right)=g_{i}$ for $1 \leqslant i \leqslant N$.
Proof. To prove the theorem, we apply Theorem 2.5. So we only need to verify that there exists $\rho_{0}(x)=$ $\min _{1 \leqslant i \leqslant N} \rho\left(x, m_{i}, b_{i}^{0}\right)$ satisfying $\mathcal{M}_{\mathcal{S}_{\rho_{0}}, f}\left(m_{i}\right) \leqslant g_{i}, 2 \leqslant i \leqslant N$. From Remark 2.6 this follows by choosing $b_{1}$ close to zero.

### 7.2. Far field case, $\kappa>1$

Using the results from Subsection 2.3 and adapting the above arguments we can easily deal with the case $\kappa>1$. In this case, we assume $x \cdot m \geqslant \frac{1}{\kappa}+\delta,|\partial \Omega|=0$, and the definition of far field refractor is made with supporting semi-hyperboloids $\rho(x, m, b)=\frac{b}{k m \cdot x-1}$ as in [5, Definition 4.1]. The far field refractor mapping of $\mathcal{S}$ is given by [5, Definition 4.2]. The family $\mathcal{F}$ is then given by $\mathcal{F}=\left\{\rho: S_{\rho}\right.$ is a far field refractor for $\left.\kappa>1\right\}$. We have

$$
\left\{\rho(\cdot, m, b): m \in \bar{\Omega}^{*}, 0<b<+\infty\right\} \subset \mathcal{F},
$$

where the functions $\rho(\cdot, m, b)$ now satisfying conditions ( $\mathrm{A} 1^{\prime}$ )-( $\left.\mathrm{A} 2^{\prime}\right)$ and ( $\mathrm{A} 3^{\prime \prime}$ ) from Subsection 2.3. Weak solutions of the far field refractor problem for $\kappa>1$ are defined as in Definition 7.3.

Therefore, applying Theorem 2.12, we obtain the following theorem.
Theorem 7.5. Let $m_{1}, \ldots, m_{N}$ be distinct points in $\overline{\Omega^{*}}, g_{1}, \ldots, g_{N}$ are positive numbers, $f \in L^{1}(\Omega)$ such that $x \cdot m_{i} \geqslant \frac{1}{\kappa}+\delta$ for $x \in \Omega, 1 \leqslant i \leqslant N$, and

$$
\begin{equation*}
\int_{\bar{\Omega}} f(x) d x=\sum_{i=1}^{N} g_{i} \tag{7.6}
\end{equation*}
$$

Then there exist positive numbers $b_{1}, b_{2}, \ldots, b_{N}$ such that $\mathcal{S}=\{\rho(x) x: x \in \bar{\Omega}\}$ with

$$
\begin{equation*}
\rho(x)=\max _{1 \leqslant i \leqslant N} \rho\left(x, m_{i}, b_{i}\right) \tag{7.7}
\end{equation*}
$$

is a weak solution to the far field refractor problem for $\kappa>1$. Moreover, $\mathcal{M}_{\mathcal{S}, f}\left(\left\{m_{i}\right\}\right)=g_{i}$ for $1 \leqslant i \leqslant N$.

### 7.3. The second boundary value problem for the Monge-Ampère equation

We assume here that $X=\bar{\Omega}$ and $Y=\bar{\Omega}^{*}$ with $\Omega, \Omega^{*}$ bounded convex domains in $\mathbb{R}^{n}$. We have a Radon measure $\omega$ in $\bar{\Omega}$ given by $w=f d x$ with $f \in L^{1}(\Omega), f$ nonnegative. The subdifferential of the function $u: \bar{\Omega} \rightarrow \mathbb{R}$ is given by

$$
\partial u\left(x_{0}\right)=\left\{p \in \bar{\Omega}^{*}: u(x) \geqslant u\left(x_{0}\right)+p \cdot\left(x-x_{0}\right) \text { for all } x \in \bar{\Omega}\right\}
$$

We let the family $\mathcal{F}=\left\{u \in C(\bar{\Omega})\right.$ : $u$ is convex and $\left.\partial u(y) \cap \overline{\Omega^{*}} \neq \emptyset \forall y \in \bar{\Omega}\right\}$. On $\mathcal{F}$ we define the mapping $\mathcal{T}$ by $\mathcal{T}(u)=\partial u$. One needs to prove that $\partial u \in C_{S}\left(\bar{\Omega}, \bar{\Omega}^{*}\right)$ and the map $\mathcal{T}(u)=\partial u$ is continuous at each $u \in \mathcal{F}$. To show $\partial u(\bar{\Omega})=\bar{\Omega}^{*}$, we proceed exactly as at the beginning of the proof of Lemma 7.1. Everything else follows from well known properties of the subdifferential, see [6].

The family $\mathcal{F}$ satisfies $\left(\mathrm{A} 1^{\prime}\right)$ and ( $\mathrm{A} 2^{\prime}$ ), and we verify that it also satisfies $\left(\mathrm{A} 3^{\prime \prime}\right)$, all from Subsection 2.3. We let $h_{t, y_{0}}(x)=x \cdot p+b$, where $t=b$ and $y_{0}=p$. Here $x \in \bar{\Omega}$ and $p \in \bar{\Omega}^{*}$. We show that

$$
\left\{x \cdot p+b: p \in \bar{\Omega}^{*},-\infty<b<\infty\right\} \subset \mathcal{F}
$$

satisfies condition $\left(\mathrm{A} 3^{\prime \prime}\right)$. In fact, $p \in \partial(x \cdot p+b)(x)$ for all $x \in \bar{\Omega}$, so $\left(\mathrm{A} 3^{\prime \prime}\right)\left(\right.$ a) holds. $\left(\mathrm{A} 3^{\prime \prime}\right)(\mathrm{b})$ is trivial. Since $x \cdot p+b \geqslant b-|x||p| \geqslant b-C$, where $C$ depends on the diameters of $\Omega$ and $\Omega^{*},\left(\mathrm{~A} 3^{\prime \prime}\right)(\mathrm{c})$ follows. ( $\left.\mathrm{A} 3^{\prime \prime}\right)(\mathrm{d})$ trivially holds.

We are now ready to apply Theorem 2.12 to solve the second boundary value problem for the Monge-Ampère equation when the measure $\mu$ is a linear combination of deltas. That is, to find a convex function $u \in \mathcal{F}$ such that $\partial u(\bar{\Omega})=\bar{\Omega}^{*}$ and solving $\int_{(\partial u)^{-1}(E)} f(x) d x=\mu(E)$ for each Borel set $E \subset \bar{\Omega}^{*}$.

Theorem 7.6. Let $p_{1}, \ldots, p_{N}$ be distinct points in $\overline{\Omega^{*}}, g_{1}, \ldots, g_{N}$ are positive numbers, $f \in L^{1}(\Omega)$, and

$$
\begin{equation*}
\int_{\bar{\Omega}} f(x) d x=\sum_{i=1}^{N} g_{i} \tag{7.8}
\end{equation*}
$$

Then there exist positive numbers $b_{1}, b_{2}, \ldots, b_{N}$ such that the convex function

$$
\begin{equation*}
u(x)=\max _{1 \leqslant i \leqslant N}\left\{x \cdot p_{i}+b_{i}\right\} \tag{7.9}
\end{equation*}
$$

solves the second boundary value problem for the Monge-Ampère equation.

## Appendix A. Derivation of the pde

Suppose the function defining the refractor is $\rho\left(x_{1}, \ldots, x_{n-1}, x_{n}\right)$ and set $x^{\prime}=\left(x_{1}, \ldots, x_{n-1}\right)$. We have points $\left(x^{\prime}, x_{n}\right) \in \Omega \subset S^{n-1}$, so we think of the region $\Omega$ defined by $\left\{\left(x^{\prime}, \sqrt{1-\left|x^{\prime}\right|^{2}}\right): x^{\prime} \in U\right\}$ and therefore we identify $\Omega$ with $U$. We also think of the defining function $\rho$ as a function $\rho=\rho\left(x^{\prime}\right)$ with $x^{\prime} \in U$. For the derivation of the equation we assume that $\rho$ is $C^{2}$. Following the paper [8], we use the notation $D \rho=\left(\partial_{1} \rho, \ldots, \partial_{n-1} \rho\right)$ and $\hat{D} \rho=(D \rho, 0)$. We also use the notation $x=\left(x_{1}, \ldots, x_{n}\right) \in S^{n-1}$ and let $y \in S^{n-1}$ be the refracted direction of the ray $x$ by the surface $\rho(x) x$, that is,

$$
\begin{equation*}
y=\frac{1}{\kappa}(x-\Phi(x \cdot v) v) \tag{A.1}
\end{equation*}
$$

where $v$ is the outer unit normal to the refractor at the point $\rho(x) x$, and $\Phi(t)=t-\kappa \sqrt{1-\kappa^{-2}\left(1-t^{2}\right)}$.

## A.1. Case when the target domain $D \subset\left\{x_{n}=0\right\}$

Notice that this is compatible with hypotheses H 1 and H 2 if $\kappa<1$ or H 3 and H 4 if $\kappa>1$, when $\Omega$ is above or near the hyperplane $x_{n}=0$. Suppose the surface refracts off the ray with direction $x$ into the point $Z \in D$. Then

$$
Z=\rho(x) x+|Z-\rho(x) x| y
$$

We denote by $T$ the map $x \mapsto Z$ and we regard it defined in $U$, that is, $T: U \rightarrow D$, where $D$ is the target screen. Since $D \subset\left\{x_{n}=0\right\}$, we have that $T\left(x^{\prime}\right)=\left(z_{1}, \ldots, z_{n-1}, 0\right)$, and the Jacobian of $T$ is then the matrix $D Z=\left(\partial_{j} z_{i}\right)_{i j}$, $1 \leqslant i, j \leqslant n-1$. If $d S_{\Omega}$ and $d S_{D}$ denote the surface area elements in $\Omega$ and in $D$, respectively, then $\operatorname{det} D Z=\frac{d S_{D}}{d S_{\Omega}}$. Noticing that $d S_{\Omega}=\frac{1}{\sqrt{1-\left.\left|x^{\prime}\right|\right|^{2}}} d S_{U}$, and since $f$ and $g$ are the energy distributions in $\Omega$ and $D$, respectively, we obtain the equation

$$
\begin{equation*}
\operatorname{det} D Z=\frac{f}{g \sqrt{1-\left|x^{\prime}\right|^{2}}} . \tag{A.2}
\end{equation*}
$$

We now find the explicit form of $D Z$ which will yield the pde satisfied by $\rho$.
From [8, Formula (2.15)] we have the following expression for the outer normal (the change in the sign is due to the direction of the normal):

$$
\begin{equation*}
\nu=\frac{-\hat{D} \rho+x\left(\rho\left(x^{\prime}\right)+D \rho\left(x^{\prime}\right) \cdot x^{\prime}\right)}{\sqrt{\rho^{2}+|D \rho|^{2}-\left(D \rho \cdot x^{\prime}\right)^{2}}}, \tag{A.3}
\end{equation*}
$$

and so

$$
x \cdot v=\frac{\rho}{\sqrt{\rho^{2}+|D \rho|^{2}-\left(D \rho \cdot x^{\prime}\right)^{2}}} .
$$

We now calculate $d=\left|Z-\rho\left(x^{\prime}\right) x\right|$. Since $D \subset\left\{x_{n}=0\right\}$, we have $0=\rho\left(x^{\prime}\right) x_{n}+d y_{n}$ and so $d=-\rho\left(x^{\prime}\right) \frac{x_{n}}{y_{n}}$. Also

$$
\begin{aligned}
y_{n} & =\frac{1}{\kappa}\left(x_{n}-\Phi(x \cdot v) v_{n}\right) \\
& =\frac{1}{\kappa}\left(x_{n}-\Phi(x \cdot v) \frac{x_{n}\left(\rho+D \rho \cdot x^{\prime}\right)}{\sqrt{\rho^{2}+|D \rho|^{2}-\left(D \rho \cdot x^{\prime}\right)^{2}}}\right) \\
& =x_{n} \frac{1}{\kappa}\left(1-\Phi(x \cdot v) \frac{\rho+D \rho \cdot x^{\prime}}{\sqrt{\rho^{2}+|D \rho|^{2}-\left(D \rho \cdot x^{\prime}\right)^{2}}}\right) \\
& =x_{n} \frac{A}{\kappa},
\end{aligned}
$$

so

$$
d=-\rho \frac{\kappa}{A} .
$$

From (A.1) we then have

$$
y=\frac{1}{\kappa}\left(A x+\Phi(x \cdot v) \frac{\hat{D} \rho}{\sqrt{\rho^{2}+|D \rho|^{2}-\left(D \rho \cdot x^{\prime}\right)^{2}}}\right) .
$$

Therefore

$$
\begin{aligned}
Z & =\rho(x) x-\rho \frac{\kappa}{A} y=-\frac{\rho}{A} \frac{\Phi(x \cdot v)}{\sqrt{\rho^{2}+|D \rho|^{2}-\left(D \rho \cdot x^{\prime}\right)^{2}}} \hat{D} \rho \\
& =\rho \frac{\Phi(x \cdot v)}{-G+\Phi(x \cdot v)\left(\rho+D \rho \cdot x^{\prime}\right)} \hat{D} \rho \\
& =F\left(x^{\prime}, \rho\left(x^{\prime}\right), D \rho\left(x^{\prime}\right)\right) \hat{D}\left(\rho^{2}\right),
\end{aligned}
$$

where

$$
F\left(x^{\prime}, \rho\left(x^{\prime}\right), D \rho\left(x^{\prime}\right)\right)=\frac{1}{2} \frac{\Phi(x \cdot v)}{-G+\Phi(x \cdot v)\left(\rho+D \rho \cdot x^{\prime}\right)}
$$

with $G=\sqrt{\rho^{2}+|D \rho|^{2}-\left(D \rho \cdot x^{\prime}\right)^{2}}$. It is convenient to use the notation

$$
F\left(x^{\prime}, u, p\right)=\frac{1}{2} \frac{\Phi\left(\frac{u}{\sqrt{u^{2}+|p|^{2}-\left(p \cdot x^{\prime}\right)^{2}}}\right)}{-\sqrt{u^{2}+|p|^{2}-\left(p \cdot x^{\prime}\right)^{2}}+\left(u+p \cdot x^{\prime}\right) \Phi\left(\frac{u}{\sqrt{u^{2}+|p|^{2}-\left(p \cdot x^{\prime}\right)^{2}}}\right)} .
$$

So $z_{i}=F\left(x^{\prime}, \rho\left(x^{\prime}\right), D \rho\left(x^{\prime}\right)\right)\left(\rho^{2}\right)_{x_{i}}$ for $1 \leqslant i \leqslant n-1$ and $z_{n}=0$. Differentiating this with respect to $x_{j}$ we get

$$
\begin{aligned}
\partial_{j} z_{i} & =F\left(\rho^{2}\right)_{x_{i} x_{j}}+\left(\rho^{2}\right)_{x_{i}}\left(F_{x_{j}}+F_{u} \rho_{x_{j}}+\sum_{k=1}^{n-1} F_{p_{k}} \rho_{x_{k} x_{j}}\right) \\
& =2 F \rho \rho_{x_{i} x_{j}}+2 F \rho_{x_{i}} \rho_{x_{j}}+\left(\rho^{2}\right)_{x_{i}}\left(F_{x_{j}}+F_{u} \rho_{x_{j}}+\sum_{k=1}^{n-1} F_{p_{k}} \rho_{x_{k} x_{j}}\right) .
\end{aligned}
$$

If $\eta, \xi$ are row vectors in $\mathbf{R}^{n}$, the tensor product is the $n \times n$ matrix defined by

$$
\xi \otimes \eta=\xi^{t} \eta
$$

with the multiplication of matrices. Then the Jacobian matrix $D Z=\left(\partial_{j} z_{i}\right)$ can be written as

$$
D Z=2 \rho F D^{2} \rho+2 F D \rho \otimes D \rho+D\left(\rho^{2}\right) \otimes D_{x^{\prime}} F+F_{u} D\left(\rho^{2}\right) \otimes D \rho+D\left(\rho^{2}\right) \otimes\left(D_{p} F D^{2} \rho\right) .
$$

If $\xi, \eta$ are row vectors and $A$ is an $n \times n$ matrix, then $\xi \otimes(\eta A)=(\xi \otimes \eta) A$, and we then obtain the formula

$$
D Z=2 \rho\left\{F I+D \rho \otimes D_{p} F\right\} D^{2} \rho+2 F D \rho \otimes D \rho+D\left(\rho^{2}\right) \otimes D_{x^{\prime}} F+F_{u} D\left(\rho^{2}\right) \otimes D \rho
$$

We have from the Sherman-Morrison formula that if $\mathcal{M}=I+\xi \otimes \eta$, with $\xi$ and $\eta$ row vectors, then,

$$
\begin{equation*}
\operatorname{det} \mathcal{M}=1+\xi \cdot \eta \quad \text { and } \quad \mathcal{M}^{-1}=I-\frac{\xi \otimes \eta}{1+\xi \cdot \eta} \tag{A.4}
\end{equation*}
$$

Therefore, if

$$
\begin{equation*}
\mathcal{M}=I+\frac{1}{F\left(x^{\prime}, \rho, D \rho\right)} D \rho \otimes D_{p} F \tag{A.5}
\end{equation*}
$$

then

$$
\begin{equation*}
\mathcal{M}^{-1}=I-\frac{D \rho \otimes D_{p} F}{F(x, \rho, D \rho)+D \rho \cdot D_{p} F} . \tag{A.6}
\end{equation*}
$$

Hence

$$
\begin{equation*}
D Z=2 \rho F \mathcal{M} D^{2} \rho+2 F D \rho \otimes D \rho+D\left(\rho^{2}\right) \otimes D_{x^{\prime}} F+F_{u} D\left(\rho^{2}\right) \otimes D \rho=2 \rho F \mathcal{M} D^{2} \rho+B \tag{A.7}
\end{equation*}
$$

and so

$$
\frac{1}{2 \rho F} \mathcal{M}^{-1} D Z=D^{2} \rho+\frac{1}{2 \rho F} \mathcal{M}^{-1} B
$$

We have $\operatorname{det} \mathcal{M}^{-1}=\frac{F}{F+D \rho \cdot D_{p} F}$. Therefore

$$
\operatorname{det} D Z=\operatorname{det}\left(D^{2} \rho+\frac{1}{2 \rho F} \mathcal{M}^{-1} B\right)(2 \rho)^{n-1} F^{n-2}\left(F+D \rho \cdot D_{p} F\right)
$$

Since $(\alpha \otimes \beta)(\xi \otimes \eta)=(\beta \cdot \xi)(\alpha \otimes \eta)$, from the form of $\mathcal{M}^{-1}$ and $B$ we have that

$$
\mathcal{M}^{-1} B=\frac{2 F}{F+D \rho \cdot D_{p} F}\left[\left(F+\rho F_{u}\right) D \rho \otimes D \rho+\rho D \rho \otimes D_{x^{\prime}} F\right] .
$$

Combining this with (A.2), we obtain that $\rho$ satisfy the following pde of Monge-Ampère type:

$$
\begin{equation*}
\operatorname{det}\left(D^{2} \rho+\mathcal{A}\left(x^{\prime}, \rho, D \rho\right)\right)=\frac{f}{g \sqrt{1-\left|x^{\prime}\right|^{2}}(2 \rho)^{n-1} F^{n-2}\left(F+D \rho \cdot D_{p} F\right)}, \tag{A.8}
\end{equation*}
$$

where

$$
\mathcal{A}\left(x^{\prime}, \rho, D \rho\right)=\frac{1}{\rho\left(F+D \rho \cdot D_{p} F\right)}\left[\left(F+\rho F_{u}\right) D \rho \otimes D \rho+\rho D \rho \otimes D_{x^{\prime}} F\right] .
$$

## A.2. Case when D is contained in a hypersurface

We assume the target domain $D$ is contained in a hypersurface $\left\{P \in \mathbb{R}^{n}: \psi(P)=0\right\}$, where $\psi$ is $C^{1}$ and $\psi_{P_{n}} \neq 0$. We recall that we assume the configuration given by either (H1) and (H2), if $\kappa<1$, or (H3) and (H4), if $\kappa>1$. In order to find the pde in the general case we will use the calculations from Subsection A.1.

Given the direction $x \in \Omega$, the point $\rho(x) x$ is refracted with direction $y$ into the point $Z \in D$. The normal at $Z=\left(z_{1}, \ldots, z_{n}\right) \in D$ is given by $D \psi$ and so the map $T: x \mapsto Z$ has Jacobian matrix $J$ satisfying

$$
\operatorname{det} J=\frac{1}{|D \psi|} \operatorname{det}\left[\begin{array}{cccc}
\partial_{1} z_{1} & \cdots & \partial_{n-1} z_{1} & \psi_{P_{1}} \\
\partial_{1} z_{2} & \cdots & \partial_{n-1} z_{2} & \psi_{P_{2}} \\
\vdots & \vdots & \ddots & \vdots \\
\partial_{1} z_{n} & \cdots & \partial_{n-1} z_{n} & \psi_{P_{n}}
\end{array}\right] .
$$

We have $Z=Z\left(x^{\prime}\right)=\left(z_{1}\left(x_{1}, \ldots, x_{n-1}\right), \ldots, z_{n}\left(x_{1}, \ldots, x_{n-1}\right)\right)$ and $\psi\left(Z\left(x_{1}, \ldots, x_{n-1}\right)\right)=0$, so differentiating with respect to $x_{j}$ we get $\sum_{i=1}^{n} \psi_{P_{i}} \partial_{x_{j}} z_{i}=0$ and so

$$
\partial_{x_{j}} z_{n}=-\frac{1}{\psi_{P_{n}}} \sum_{i=1}^{n-1} \psi_{P_{i}} \partial_{x_{j}} z_{i}, \quad \text { for } j=1, \ldots, n-1 .
$$

Inserting these into $\operatorname{det} J$ yields

$$
\operatorname{det} J=\frac{|D \psi|}{\psi_{P_{n}}} \operatorname{det}\left[\begin{array}{ccc}
\partial_{1} z_{1} & \cdots & \partial_{n-1} z_{1}  \tag{A.9}\\
\partial_{1} z_{2} & \cdots & \partial_{n-1} z_{2} \\
\vdots & \ddots & \vdots \\
\partial_{1} z_{n-1} & \cdots & \partial_{n-1} z_{n-1}
\end{array}\right]
$$

For $Z \in D, x \in \Omega$, with $T x=Z$, let $y=\frac{Z-\rho(x) x}{|Z-\rho(x) x|}$, and let $\ell$ be the line with direction $y$ passing through the point $\rho(x) x$. Let $W$ be the intersection point between $\ell$ and the hyperplane $x_{n}=0$. We write

$$
W=\rho(x) x+d_{0} y .
$$

The existence of $W$ follows from (H1) and (H2) if $e_{n} \in \Omega$ and $\tau<\kappa$. Indeed, we notice that $\ell$ does not intersect $x_{n}=0$ if and only if $\ell$ is perpendicular to $e_{n}$, or equivalently the vector $y$ is perpendicular to $e_{n}$. From (H1), $Z /|Z|$ is contained in the solid cone with axis $e_{n}$ with opening $\kappa+\tau$ for $Z \in D$, i.e. $Z /|Z| \cdot e_{n} \geqslant \kappa+\tau$. On the other hand, since the refractor is contained in $Q_{r_{0}}$, we have $A=\left|\frac{Z}{|Z|}-y\right| \leqslant \frac{2 \rho(x)}{|Z-\rho(x) x|} \leqslant \frac{2 r_{0}}{|Z-\rho(x) x|}$. Now from (H2)

$$
|Z-\rho(x) x| \geqslant|Z|-r_{0} \geqslant \operatorname{dist}(D, 0)-r_{0} \geqslant r_{0}\left(\frac{1+\kappa-\tau}{\tau}\right),
$$

so $A \leqslant \frac{2 \tau}{1+\kappa-\tau}$. Therefore

$$
y \cdot e_{n}=\left(y-\frac{Z}{|Z|}\right) \cdot e_{n}+\frac{Z}{|Z|} \cdot e_{n} \geqslant-\frac{2 \tau}{1+\kappa-\tau}+\kappa+\tau=(\kappa-\tau) \frac{1+\kappa+\tau}{1+\kappa-\tau}:=r .
$$

Thus, if $\tau<\kappa$, then $r>0$, and so the vector $y$ lies in a cone with axis $e_{n}$ that does not intersect the plane $x_{n}=0$ which proves the existence of $W$. Similarly, if $\kappa>1$, then the existence of $W$ also follows from (H3) and (H4) assuming again $e_{n} \in \Omega$ and that $\tau$ is sufficiently small.

A calculation as in the case when $D \subset\left\{x_{n}=0\right\}$ yields that

$$
W=F\left(x^{\prime}, \rho\left(x^{\prime}\right), D \rho\left(x^{\prime}\right)\right) \hat{D}\left(\rho^{2}\right) .
$$

If we write

$$
Z=\rho\left(x^{\prime}\right) x+t\left(x^{\prime}\right)\left(W-\rho\left(x^{\prime}\right) x\right)
$$

then $Z-\rho\left(x^{\prime}\right) x=t\left(x^{\prime}\right)\left(W-\rho\left(x^{\prime}\right) x\right)$ and making the dot product of this equation with $e_{n}$ we obtain that

$$
t\left(x^{\prime}\right)=\frac{\rho\left(x^{\prime}\right) x_{n}-z_{n}}{\rho\left(x^{\prime}\right) x_{n}}
$$

where $x_{n}=\sqrt{1-\left|x^{\prime}\right|^{2}}$. In view of (A.9), we only need to calculate $\partial_{j} z_{i}$ for $1 \leqslant i, j \leqslant n-1$. Set $z^{\prime}=\left(z_{1}, \ldots, z_{n-1}\right)$ and $w^{\prime}=\left(w_{1}, \ldots, w_{n-1}\right)$, we get

$$
\partial_{j} z_{i}=\partial_{j} t\left(w_{i}-\rho\left(x^{\prime}\right) x_{i}\right)+(1-t) \partial_{j}\left(\rho\left(x^{\prime}\right) x_{i}\right)+t \partial_{j} w_{i}, \quad i, j=1, \ldots, n-1
$$

This equation written in matrix form is

$$
\begin{equation*}
D z^{\prime}=\left(w^{\prime}-\rho x^{\prime}\right) \otimes D t+(1-t) D\left(\rho x^{\prime}\right)+t D w^{\prime} \tag{A.10}
\end{equation*}
$$

We calculate $\partial_{j} t$. Differentiating the equation $\psi\left(t W+(1-t) \rho\left(x^{\prime}\right) x\right)=0$ with respect to $x_{j}, 1 \leqslant j \leqslant n-1$, we get

$$
\begin{aligned}
\partial_{j} t D \psi \cdot(W-\rho x) & =-(1-t) \sum_{i=1}^{n} \psi_{P_{i}} \partial_{j}\left(\rho x_{i}\right)-t \sum_{i=1}^{n} \psi_{P_{i}} \partial_{j} w_{i} \\
& =-\sum_{i=1}^{n-1} \psi_{P_{i}}\left((1-t) \partial_{j}\left(\rho x_{i}\right)+t \partial_{j} w_{i}\right)-(1-t) \psi_{P_{n}} \partial_{j}\left(\rho x_{n}\right),
\end{aligned}
$$

since $w_{n}=0$. So we have the formula for the vector $D t=\left(\partial_{1} t, \ldots, \partial_{n-1} t\right)$

$$
\begin{equation*}
D t=-\beta \tilde{D} \psi\left((1-t) D\left(\rho x^{\prime}\right)+t D w^{\prime}\right)-\beta(1-t) \psi_{P_{n}} D\left(\rho x_{n}\right) \tag{A.11}
\end{equation*}
$$

where $\beta=\frac{1}{D \psi \cdot(W-\rho x)}$, and we used the notation $\tilde{D} \psi=\left(\psi_{P_{1}}, \ldots, \psi_{P_{n-1}}\right)$. For simplicity in the calculation let $A=$ $(1-t) D\left(\rho x^{\prime}\right)+t D w^{\prime}$. So from (A.10)

$$
D z^{\prime}=\left(w^{\prime}-\rho x^{\prime}\right) \otimes D t+A,
$$

and from (A.11)

$$
D t=-\beta \tilde{D} \psi A-\beta(1-t) \psi_{P_{n}} D\left(\rho x_{n}\right)
$$

So inserting (A.11) into (A.10) and using the formula $\xi \otimes(\eta A)=(\xi \otimes \eta) A,{ }^{4}$ we obtain

$$
D z^{\prime}=\left(I-\beta\left(w^{\prime}-\rho x^{\prime}\right) \otimes \tilde{D} \psi\right) A-\beta(1-t) \psi_{P_{n}}\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)
$$

Letting $\mathcal{B}=I-\beta\left(w^{\prime}-\rho x^{\prime}\right) \otimes \tilde{D} \psi$, from (A.4) we get

$$
\mathcal{B}^{-1}=I+\frac{\beta\left(w^{\prime}-\rho x^{\prime}\right) \otimes \tilde{D} \psi}{1-\beta\left(w^{\prime}-\rho x^{\prime}\right) \cdot \tilde{D} \psi}
$$

Since $\frac{1}{\beta}=D \psi \cdot(W-\rho x)=\tilde{D} \psi \cdot\left(w^{\prime}-\rho x^{\prime}\right)-\psi_{P_{n}} \rho x_{n}$, it follows that

$$
\mathcal{B}^{-1}=I-\frac{\left(w^{\prime}-\rho x^{\prime}\right) \otimes \tilde{D} \psi}{\psi_{P_{n}} \rho x_{n}} .
$$

Therefore

$$
D z^{\prime}=\mathcal{B}\left(A-\beta(1-t) \psi_{P_{n}} \mathcal{B}^{-1}\left(\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)\right)\right)
$$

We have

[^2]\[

$$
\begin{aligned}
\mathcal{B}^{-1}\left(\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)\right) & =\left(I-\frac{\left(w^{\prime}-\rho x^{\prime}\right) \otimes \tilde{D} \psi}{\psi_{P_{n}} \rho x_{n}}\right)\left(\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)\right) \\
& =\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)-\frac{1}{\psi_{P_{n}} \rho x_{n}}\left(\left(w^{\prime}-\rho x^{\prime}\right) \otimes \tilde{D} \psi\right)\left(\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)\right) \\
& =\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)-\frac{1}{\psi_{P_{n}} \rho x_{n}}\left(\tilde{D} \psi \cdot\left(w^{\prime}-\rho x^{\prime}\right)\right)\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right) \\
& =\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)-\frac{1}{\psi_{P_{n}} \rho x_{n}}\left(\frac{1}{\beta}+\psi_{P_{n}} \rho x_{n}\right)\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right) \\
& =-\frac{1}{\beta \psi_{P_{n}} \rho x_{n}}\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right) .
\end{aligned}
$$
\]

Consequently

$$
\begin{aligned}
D z^{\prime} & =\mathcal{B}\left(A+(1-t) \frac{1}{\rho x_{n}}\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)\right) \\
& =\mathcal{B}\left(t D w^{\prime}+(1-t) D\left(\rho x^{\prime}\right)+(1-t) \frac{1}{\rho x_{n}}\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)\right) .
\end{aligned}
$$

We recall from (A.7) that

$$
D w^{\prime}=2 \rho F\left(x^{\prime}, \rho, D \rho\right) \mathcal{M} D^{2} \rho+B
$$

with $\mathcal{M}$ from (A.5), so

$$
\begin{aligned}
D z^{\prime} & =\mathcal{B}\left(t 2 \rho F \mathcal{M} D^{2} \rho+t B+(1-t) D\left(\rho x^{\prime}\right)+(1-t) \frac{1}{\rho x_{n}}\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)\right) \\
& =\mathcal{B} 2 t \rho F \mathcal{M}\left(D^{2} \rho+\frac{1}{2 t \rho F} \mathcal{M}^{-1}\left(t B+(1-t)\left(D\left(\rho x^{\prime}\right)+\frac{1}{\rho x_{n}}\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)\right)\right)\right) .
\end{aligned}
$$

We have $\operatorname{det} \mathcal{B}=1-\beta\left(w^{\prime}-\rho x^{\prime}\right) \cdot \tilde{D} \psi=-\beta \psi_{P_{n}} \rho x_{n}$ and $\operatorname{det} \mathcal{M}=1+\frac{1}{F}\left(D \rho \cdot D_{p} F\right)$. So

$$
\operatorname{det} D z^{\prime}=(2 t \rho F)^{n-1}\left(-\beta \psi_{P_{n}} \rho x_{n}\right)\left(1+\frac{1}{F}\left(D \rho \cdot D_{p} F\right)\right) \operatorname{det}\left(D^{2} \rho+\mathcal{A}\right),
$$

with

$$
\mathcal{A}=\mathcal{A}\left(x^{\prime}, \rho, D \rho\right)=\frac{1}{2 t \rho F} \mathcal{M}^{-1}\left(t B+(1-t)\left(D\left(\rho x^{\prime}\right)+\frac{1}{\rho x_{n}}\left(w^{\prime}-\rho x^{\prime}\right) \otimes D\left(\rho x_{n}\right)\right)\right) .
$$

From (A.2) and (A.9) we then obtain that $\rho$ satisfy the pde of Monge-Ampère type

$$
\begin{equation*}
\operatorname{det}\left(D^{2} \rho+\mathcal{A}\right)=\frac{f}{g\left(1-\left|x^{\prime}\right|^{2}\right)|D \psi|(2 t)^{n-1} \rho^{n}(-\beta) F^{n-2}\left(F+D \rho \cdot D_{p} F\right)} \tag{A.12}
\end{equation*}
$$

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[^1]:    ${ }^{3}$ Since the refraction angle depends on the frequency of the radiation, we assume our light ray is monochromatic.

[^2]:    $4 \xi \otimes \eta=\xi^{t} \eta$ as multiplication of matrices.

